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Technical Report



No. <u>13341</u>

Track Standing Wave Analysis

Contract No. DAAE07-87-C-R061

May 1988



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By Washington, D.C. 20036

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19. ABSTRACT (Continued)

Damping in the track/pin rubber bushing interface may be varied in separate analyses to study the effects of damping on dynamic tension and resulting energy dissipation in the track.

The analytical model was configured to represent the M113 Armored Personnel Carrier. Sample analyses of this configuration were complet ed and tabulated results appear to be reasonable.

PREFACE

The cooperation and assistance provided by Roger Smith, TACOM Technical Representative, and George Poteet, TACOM Liaison Officer at Aberdeen Proving Ground, are appreciated and acknowledged.

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1.0. INTRODUCTION

1.1. Purpose

The purpose of this MPR Associates feasibility study, Contract Number DAAE07-87-C-R061, was to determine whether an analytical model capable of calculating the dynamic motion and loads in the tracks and suspension of a tracked vehicle could be developed. Such a model could be used to evaluate causes of track vibration and the associated energy dissipation. The model could also be used to analyze the effects of design changes made to reduce the energy dissipation associated with vibration of the tracks or to reduce the loads which would occur in the track under normal operation, therefore improving track reliability. With such a model, design changes could be evaluated analytically prior to actual prototype fabrication and field testing, leading to a better understanding of the effects of particular changes to the track on track dynamics.

2.0 OBJECTIVES

This report presents the results of the feasibility study discussed above which was completed under Phase I of the 1987 Small Business Innovation Research Program (SBIR). The initial problem definition for the study is contained in the Department of Defense FY 1987 SBIR Program Solicitation and is as follows:

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A87-167. TITLE: Track Standing Wave Analysis

DESCRIPTION: At higher speeds, the momentum of the track on tracked vehicles forms standing waves. These standing waves absorb power and reduce drivetrain efficiency. The hysteresis of rubber bushings in single pin tracks or the hysteresis of the rubber surrounding the pins in double pin tracks dampens the standing waves to an acceptable level. However, the rubber material on tracks is a prime cause of failure and represents a large portion of the life cycle costs of the track. It would be possible to use a more rugged and less costly unbushed track if a means could be found to externally dampen the standing wave formation.

In response to the request for proposal contained in the SBIR Program Solicitation, we proposed an analytical approach, which would be programmed for use on a computer, and which would demonstrate the feasibility of solving the track dynamics problem by obtaining a solution for the loads and displacements in the track and the vehicle suspension for a specific configuration. After the feasibility of the model had been demonstrated on this test problem, we proposed that the model should be used in Phase II of the SBIR program to analyze the effect of changes in track/pin interface stiffness and damping and to investigate alternate track designs which might reduce or eliminate standing waves.

3.0. CONCLUSIONS

The objective of our study was to determine whether an analytical method could be devised which would evaluate the effects of changes in track design on the formation of standing waves which occur in the track of a tracked vehicle. We began our feasibility study by completing several literature searches, including a review of documentation provided by the U.S. Army Tank Automative Command (TACOM) from the TACOM technical library at Warren, Michigan. Based on our understanding of the problem from these literature searches and our experience, we concluded that use of a commercially available finite element program, such as ANSYS, is not feasible because such a program cannot model track motion explicitly. The literature searches also showed that recent research had been completed to address track pin fatigue failure and to develop a low-weight aluminum track. How these research efforts are interrelated with the present study is discussed below in our recommendations.

Our initial analytical approach attempted to solve the equations of motion of a track assuming the existence of steady state standing waves caused by the dynamics of the track shoes as they travel around the tracks. Results obtained from this initial investigation indicated that the existence of standing waves could not be explained without the excitation from a force spectrum resulting from the dynamic interaction of the track and the drive sprocket, idler wheel and road wheels. A trip to Aberdeen Proving Grounds in Maryland on October 19, 1987, during which we observed actual track motion on several vehicles, reinforced our initial conclusion regarding the transient nature of the waves in the track system. For these reasons, we concluded that proper analytical modeling of the track system requires an explicit model of the track and its associated components which is capable of predicting the dynamic, transient response of the entire system.

As a result, a detailed analytical model for the dynamic analysis of a tracked vehicle was developed. This model includes the detailed motion of the track shoes, the drive sprocket, the idler wheel, the road wheels, and the vehicle as a whole. The model allows the specification of a terrain profile over which the vehicle is to proceed. Forces between the vehicle and the drive sprocket; idler wheel and road wheels; between the drive sprocket, idler wheel and road wheels and the track shoes; between individual track shoes; and, between the track shoes and the ground are included in the model and an equation of motion for each component is written in detail. The torsion bar suspension and the shock absorbers are explicitly modeled in these equations. The entire system of equations is then numerically integrated to obtain the transient solution for the motion and forces in the track and suspension. Details on the solution techniques are provided in Section 5.5.

Input data for the M113 Armored Personnel Carrier geometry and suspension configuration were generated for the computer program written to solve the equations discussed above and several test cases were run. In addition, a piece of track was tested to obtain approximate stiffness

constants for the model to represent the rotational stiffness between two shoes. It was found to be necessary to include nonlinear stiffness in the force relationships between the shoes and between the shoes and wheels to obtain realistic results from the model. Results of our initial analyses indicated that a very small time step is required to achieve stable integration (on the order of one-tenth of a millisecond), since there are natural frequencies associated with the track and suspension system which are in the range of several hundred hertz.

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The resulting analytical model, developed over a period of 3 months of improvement, trial use and increased detail, is a sophisticated dynamic analysis tool which provides predicted time-dependent reaction forces, track tension, energy dissipation and intercomponent loads for a wide range of geometric parameters. The explicit modeling of the suspension components is a powerful feature of the program in that detailed design features (and changes) can be evaluated. The dynamic loads on suspension and track components are needed to enable designers to evaluate the stresses and fatigue usage in component parts, to understand abnormal failures and to design improvements. Based on our review of the literature, we believe this model provides the first and only such design tool.

The results and conclusions of the Phase I feasibility study can be summarized as follows:

- An analytical model for the dynamic analysis of a tracked vehicle has been developed and a computer program incorporating the model has been written and is operational. The vehicle suspension and track geometry are variables specified in the input to this program.
- The analytical model provides details of the track motion using a time history solution. The dynamic track tension, which can be correlated with the energy dissipated in the track, is determined as a function of time for each track link. Damping in the track/pin rubber bushing interface may be varied in separate analyses to study the effects of damping on dynamic track tension and resulting energy dissipation in the track.
- The analytical model has been configured to represent the M113 Armored Personnel Carrier. Sample analyses of this configuration were completed and tabulated results appear reasonable and realistic. However, actual measured vehicle load data are required to verify that the predicted load magnitudes and frequencies are correct. The model cannot be adequately verified using drawbar pull test curves.
- This modeling technique is capable of defining design loads, load ranges and the number of duty cycles for track components.

 Preliminary results show oscillating tensile loads in the track and oscillating reaction loads on the drive sprocket, idler wheel and road wheels. Previously, the magnitude and frequency of these loads have not been well understood. This analytical technique provides a

powerful tool for the design and analyses of new track designs or modifications to existing designs.

4.0. RECOMMENDATIONS

4.1. Phase II Research

Based on the results of the feasibility study, we recommend the following courses of action:

- Material Properties: Additional tests of the rubber bushings are required to establish material properties such as torsional stiffness, longitudinal stiffness and damping when the track is also subject to tensile loads. The material properties are believed to be very non-linear and should be incorporated into the track model to more accurately duplicate this important variable. We recommend these properties be measured using simple inexpensive bench tests.
- Model Validation: Analysis of several existing and prior suspension designs should be performed and the results compared to the measured vehicle performance and failure modes in order to validate the accuracy of the model and provide information for fine tuning the model, if necessary. Detailed measurements of track tension and suspension reaction forces are needed to compare with the model output.
- * Additional analyses using the computer model are recommended to further investigate the effects of the different track/pin interface designs. Specifically, analyses of a dry steel on steel and lubricated bearing track/pin interfaces should be performed to evaluate the theoretical performance of these two design alternatives.
- A parametric analysis is recommended to evaluate the use of alternate materials in the track/pin bushing. Variations in stiffness and damping should be explored to determine whether a more rugged material can be substituted for the rubber bushings.
- An analysis of the M113 track substituting a conventional-type track suspension with small road wheels and track support rollers is recommended to establish a benchmark for comparison with the flattrack-type suspension currently used.
- Several parametric analyses are recommended in which suspension system details are systematically varied and studied. For example, in one such analysis, track pitch, drive sprocket diameter and idler wheel diameter would be varied while the other component sizes and material properties are kept constant. Also recommended is a parametric analysis in which the road wheel diameter is varied while the other component sizes and material properties are kept constant.

These parametric studies would provide insight and guidelines for track design and modification.

A detailed discussion of the proposed material testing, model validation testing and additional analyses will be included in our proposal for Phase II research and development under the SBIR program.

4.2. Additional Applications

Although not addressed by the problem definition, analyses can be completed using this analytical technique to support the development of fatigue resistant pins, lightweight tracks and improvements in trac't design as follows:

- An analysis in which the mass of the track shoe used in the model is reduced to represent an aluminum track can be used to evaluate the effects of the use of a lighter track. This analysis would address the demonstrated need for an understanding of aluminum track dynamics.
- An analysis in which the track pin diameter is increased (with corresponding changes in track rotational and longitudinal stiffness and damping) can be used to evaluate the effects of using a more fatigue resistant pin design. This analysis would address the demonstrated need for a more fatigue resistant pin design.
- * Finally, track design modifications can be explored using the model to investigate the effects of design modifications to the track and suspension. Promising design modifications can be evaluated prior to fabrication of prototypes. The analytical model can be used to determine design loads for sizing these new components.

5.0. DISCUSSION

The M113 Armored Personnel Carrier, the tracked vehicle selected as the subject vehicle for this feasibility study, was first placed into service in 1960 with about 73,000 vehicles currently in service in 45 countries. The current version of the M113 is the M113A2, which carries an improved suspension over the original vehicle. The M113 is slowly being replaced by the M2 Bradley Infantry Fighting Vehicle. There are many variants of the M113, such as mortar vehicles, command vehicles and antiaircraft and missile launch vehicles, which have the same track and suspension design as the M113.

The M113 suspension and track design, shown in Figure 5-1, is of the flat-track-type². There are 10 road wheels, each of which has its own torsion bar suspension spring. The two front road wheels and the two rear road wheels are also attached to shock absorbers. The drive sprocket is located in the front of the vehicle. The track is a reversible single-pin block and pin-type track. The pins use rubber bushings at the track/pin interface. The track block is constructed of

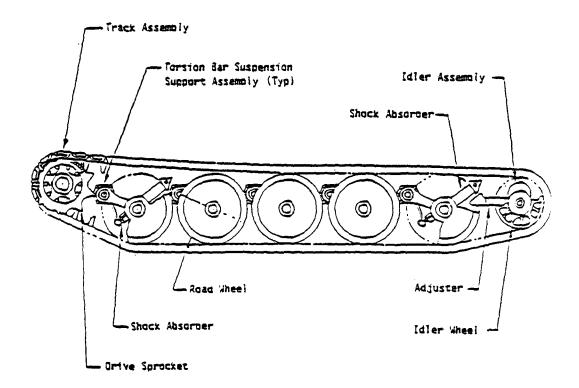


Figure 5-1. MII3 Armored Personnel Carrier Track and Suspension

a steel frame with a rubber pad on the ground side. There are 65 track shoe assemblies on each track.

5.1. Background

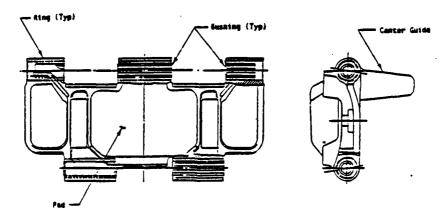
A brief general summary of different types of tracks and track/pin interfaces is presented in Appendix A. This information was compiled from a literature search and from an examination of the tracked vehicles on display at the Aberdeen Proving Ground Ordinance Museum. There are four basic types of tracks used for military vehicles^{3,4}. These are the reversible block and pin track, irreversible block and pin track, band track, and spaced-link track. The analysis of track motion presented in this report only considers the reversible block and pin-track-type which is used in the M113 Armored Personnel Carrier. The two types of reversible block and pin tracks, the single-pin shoe and the double-pin shoe, are shown in Figure 5-2. The advantages and disadvantages of all of the track types are discussed in Appendix A to provide a basis for understanding the current preference for using the reversible block and pin-track-type in military vehicles.

In addition, there are four different pin/track interface designs for the block and pin track⁴. The advantages and disadvantages of these different interface designs are also discussed in Appendix A as this is the specific component in the block and pin track design addressed by the problem definition. Also, a brief discussion of the advantages and disadvantages of small and large road wheels is included.

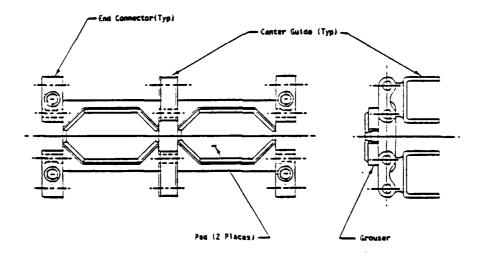
The principal method of measuring and comparing the performance of tracked vehicles on hard ground is the drawbar pull test in which a dynamometer is placed between the pulling tracked vehicle and the pulled vehicle. The dynamometer is used to measure the drawbar pull force as a function of velocity. The drawbar pull force is equal to the difference between the tractive force and the resisting force of the pulling tracked vehicle. The tractive force is equal to the force delivered by the tracked vehicle power plant and transmission. The tracked vehicle resisting force is composed of the following force components:

- internal resistance of running gear which includes frictional losses in the track pins, driving sprocket teeth, sprocket hub, roadwheel running surfaces, and roadwheel bearings,
- resistance due to vehicle/terrain interaction,
- obstacle resistance,
- grade resistance, and
- aerodynamic drag.

To characterize the internal resistance component of the resisting force of military tracked vehicles on hard ground, the drawbar test is



(a) SINGLE PIN SHOE



(b) DOUBLE PIN SHOE.

Figure 5-2. Reversible Block and Pin Tracks

performed by towing the tracked vehicles with the dynamometer between the towing vehicle and the tracked vehicle. The tracked vehicle's transmission is disconnected in this test to remove the effects of transmission efficiency. Drawbar pull force is again tabulated as a function of velocity and used to determine the coefficient of internal resistance (drawbar pull force divided by vehicle weight) as a function of velocity. Resistance-to-propulsion tests are also performed to characterize the internal resistance component of military tracked vehicles. In these tests, measurements of horsepower delivered to the drive sprockets are converted to a tractive force, and a corresponding coefficient of internal resistance as a function of velocity is determined for propulsion. Figure 5-3 illustrates the range of coefficients of internal resistance for several different track and track/pin interface designs. As shown in the figure, the coefficient of internal resistance is nonlinear with velocity. Peaks in the coefficient of internal resistance curves have been correlated with track vibration resonant frequencies. These resonances are particularly evident in resistance to propulsion test data.

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5.2. Track Vibration

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Many studies have been made of track vibration and its effects on military vehicle occupants and on military vehicle performance 6,7,8,9,10. In the U.S., most research has concentrated on the reduction of track-vibration-induced noise inside the vehicle in an effort to improve working conditions for vehicle occupants. Early in the development of the M113 Armored Personnel Carrier the problem with noise was recognized as a result of both the track as a source of vibration and the use of aluminum body panels in the vehicle. The aluminum body panels were not stiffened and tended to respond to track vibration excitation.

Research completed in 1964 on the M113 indicates that the vehicle vibration driving forces were applied at the track sprocket engagement frequency⁶. Using a selective source removal technique, the chief source of vibration in the vehicle was determined to be the oscillating forces applied at the drive sprocket and track idler. At that time, use of a rubber-coated drive sprocket and track idler was found to reduce the transmission of the track vibration to the vehicle. In 1976, an analytical study of vibration transmission from the track to the rear idler wheel was completed. This study attempted to determine the importance of different parameters, such as idler wheel diameter, track shoe length and idler wheel suspension stiffness on the magnitude of track impact forces on the idler wheel. The study did not address the effects of the transverse vibrations which occur in the track suspended between the drive sprocket and the track idler (or track support rollers in a conventional suspension).

In 1979, a study of experimental idler designs for the M113 was again addressed primarily to the damping of hull vibration to reduce cabin noise to the point that would permit crewmembers to perform their duties without the use of hearing protectors. This study also included the use of a track simulation program developed as a means to predict the

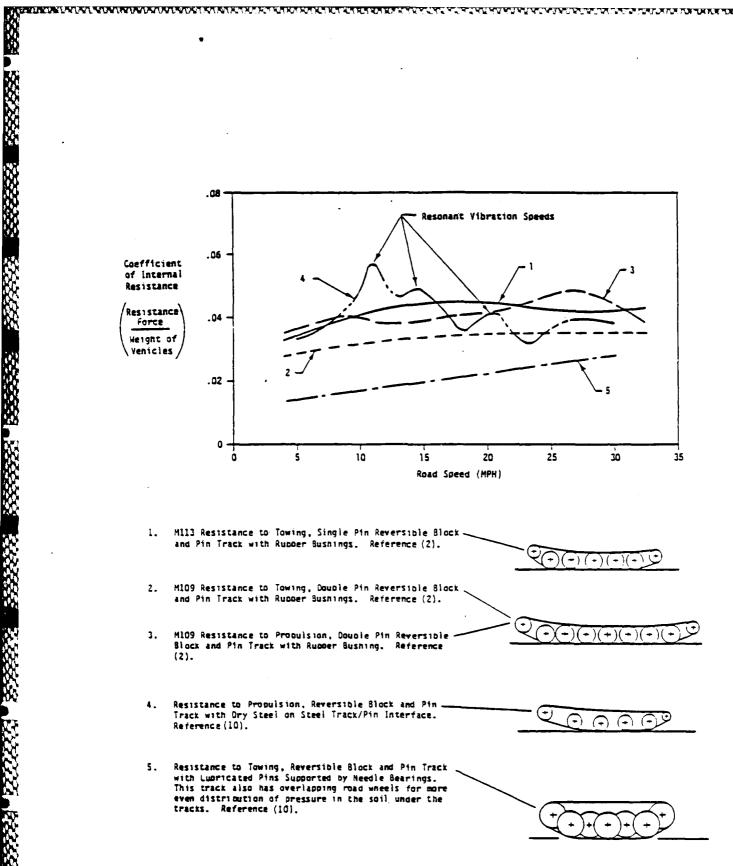


Figure 5-3. Motion Resistance of Several Track/Pin Interface Designs

effects of design changes in the track sprocket and track idler on interior noise levels. The program was developed to only include the drive sprocket, the track idler and the track, however, and did not include nonlinear material effects, road wheels, or track support rollers. Results of one computer simulation showed dynamic amplification of track tension due to resonant vibration by a factor of four. The study indicated that further development of the program was required to properly simulate track motion and to calculate reaction forces at the drive sprocket and track idler.

In 1984, preliminary development and testing of an aluminum track was completed. This track was a reversible block-and-pin-type, single-pin, rubber-bushed track in which the steel block was replaced with an aluminum block which reduced the weight of a track assembly from 33 lb to 26 lb. Results of tests completed at that time show that some degradation of performance with respect to land acceleration and maximum speed was observed with the aluminum track. This degradation was attributed to a slight difference in drive sprocket diameter between the steel and aluminum tracks, but it is also possible that the resonant frequencies and response amplitudes of the aluminum track caused the increase in resistance to motion. One conclusion of this test program was that future track developments must take into account the dynamic behavior of the track and its interface components.

The problem with excessive vibration causing tractive energy dissipation has been more of a concern with users of dry steel on steel track/pin interfaces (i.e., outside of the United States) 10 . Research in the Soviet Union has been directed at methods of determining the resonant velocities of the track and operating the tracked vehicle at speeds away from resonance 11 . The classical mechanical vibrations method of calculating the natural frequencies of the track is to consider the track to be a string or chain in tension. The tension in the track is composed of the effects of deadweight and the centripetal force placed on the track at the contact with the driving sprocket. It is assumed that the vibration displacements are small so that the tension is constant and that there is no torsional stiffness in the track. It is also assumed that the track vibrates in only one plane (up and down) that the track is inextensible, and that there is no damping of the vibrations. The nomenclature and formulae for the classical method, illustrated in Figure 5-4(a), are as follows 12 , 13 :

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Antisymmetric in-plane modes:

$$f_{\text{n}} = \frac{N}{L}$$
 $\frac{T_{\text{t}}}{M}$ $N = 1, 2, ... K$

Symmetric in-plane modes:

$$fn = \frac{1.43}{I}$$
 $N = 1$

$$fn = \frac{2.46}{L}$$

$$\int \frac{T_t}{M} \qquad N = 2$$

$$fn = \frac{(2N + 1)}{2L}$$

$$\int \frac{T_t}{M} \qquad N = 3, ...K$$

where fn = natural frequency

The state of the s

 T_t = horizontal component of track tension

 $= T_s + T_d$

 $T_s = static horizontal component of track tension due to deadweight$

 $= \frac{q L^2}{8 H}$

T_d = dynamic horizontal component of track tension due to track motion

 $= MV_t^2$

q = weight/length = Mg

L = horizontal length of track span

H = static sag

 V_t = velocity of the track

M = mass/length

g = gravitational acceleration

K = maximum mode possible which is limited by the number of track links in the span

= one half of number of free track links in the span

= drive sprocket impact frequency = V_t/P

P = track pitch

A symmetric in-plane mode is defined as one in which the vertical displacement component is symmetric about the center of the span, and vice versa. In the antisymmetric modes, no additional cable tension is induced by the motion of the cable based on the classical analyses of first order effects. In the symmetric modes, significant additional cable tension is induced by the motion of the cable. The above

equations can be solved for track velocities such that the track natural frequency is equal to the drive sprocket impact frequency. This is the resonant condition for drive sprocket impact excitation of the track. For the M113 track configuration, assuming no rotational stiffness at the track/pin interface (e.g., a lubricated pin supported by needle bearings), the natural frequencies calculated by this method for the antisymmetric and symmetric modes are shown in Table 5-1. Also shown in Table 5-1 are the corresponding vehicle speeds for the drive sprocket impact forces to excite these natural frequencies. Experimental research of vibration in chain drives has shown that vibration occurs at calculated natural frequencies and is caused by chain link impact forces at the drive sprocket.

Soviet research on track vibration also has identified additional resonant frequencies and track velocities which are based on establishing a traveling wave moving with and in the opposite direction to the track. This form of vibration may be caused by the centripetal force on the track as it passes over the track idler. For this wave motion, which appears to be a standing wave but is actually traveling, the magnitude of the wave velocity must be equal to a multiple of the track velocity in order to be reflected at the drive sprocket and the track idler. This is illustrated in Figure 5-4(b). The nomenclature and formula for the standing wave calculation, which were verified by lab tests of track¹¹ are as follows:

$$V_W$$
 = wave velocity = m V_t at resonance m is an integer 2, 3 ...

 V_W = $\sqrt{\frac{T_t}{M}}$

m V_t = $\sqrt{\frac{T_s + M V_t^2}{M}}$
 $V_{resonance}$ = $\sqrt{\frac{T_s}{M(m^2-1)}}$

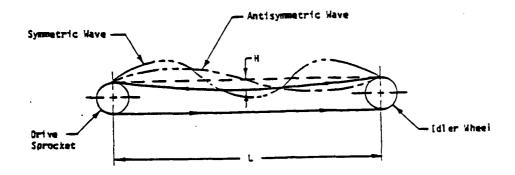
Table 5-2 tabulates the wave frequencies and corresponding track velocities for stable track standing waves, assuming no rotational stiffness at the pin/track interface. As shown in the table, several resonant track velocities calculated by this standing wave method are concurrent with track sprocket impact velocities which would excite symmetric or antisymmetric modes of vibration calculated by the suspended chain method. Tension measured in the track vibration tests referenced above showed a dynamic amplification factor of three at standing wave resonance. This implies that the standing waves are of a symmetric mode of vibration.

Apparently, part of the solution to the standing waves in Russian track design has been to operate with a low static tension in the track.

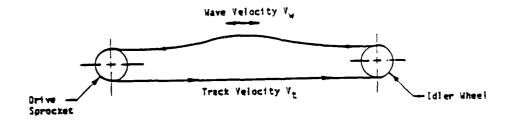
Table 5-1. Calculated Symmetric and Antisymmetric Natural Frequencies for the Vibration of the M113 Armored Personnel Carrier Track Treated as a Suspended Chain

	Symmetric M	odes		Modes	
Mode	Natural Frequency (Hz)	Vehicle Speed for Track Sprocket Impact Excitation (MPH)	Mode	Natural Frequency (Hz)	Vehicle Speed for Track Sprocket Impact Excitation (MPH)
1	10.0	3.4	1	7.0	2.4
2	16.8	5.9	2	13.9	4.8
3	24.5	8.4	3	21.0	7.2
4	31.7	10.8	4	28.1	9.6
5	39.1	13.3	5	35.4	12.1
6	46.6	15.9	6	42.8	14.6
7	54.4	18.6	7	50.5	17.2
8	62.5	21.3	8	58.4	19.9
9	70.9	24.2	9	66.6	22.7
10	79.7	27.2	10	75.2	25.6
11	89.0	30.3	11	84.3	28.7
12	98.9	33.7	12	93.9	32.0
13	109.6	37.4	13	104.2	35.5

Note: A static tensile force of 10,750 lb. was assumed for the M113 track due to pretensioning and deadweight. L is assumed to be 156.75 in. Lower static tension would reduce the natural frequencies and corresponding vehicle speeds for track sprocket excitation.



(a) Classical Vibrating String/Chain Method



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(b) Classical Traveling Wave Method

Figure 5-4. Nomemclature for Classical Analysis of Track Vibration 27

Table 5-2. Calculated Resonant Track Velocities For Stable Standing Waves in the Suspended Portion of the M113 Armored Personnel Carrier Track

Wave Velocity Integer		Track Velocity (MPH)
2	· · · · · · · · · · · · · · · · · · ·	35.7
3		21.9
4		16.0
5		12.6
6		10.5
7		8.9
8		7.8
9		6.9
10		6.2

Note: A static tensile force of 10,750 lb. was assumed for the M113 track due to pretensioning and deadweight. Lower static tensin would reduce the resonant track velocities.

Photographs of Soviet tanks¹ show either significant track sag in flat-track-type suspensions or the use of several track support rollers to reduce static tension in conventional-type suspensions. This shifts the resonant track velocities down and reduces high-speed vehicle resistance to propulsion. The problem with this strategy with respect to flat-track-type suspensions is that relatively loose track is more likely to be "thrown" (disengaged from the drive sprocket) when traversing rough terrain. On the other hand, the use of the conventional-type suspension with several track support rollers increases the motion resistance at all speeds.

The actual M113 track/pin interface is a rubber bushing with torsional stiffness and damping. The rubber bushing is preloaded during installation to provide an interference fit between the pin and the track. Rotation at the track/pin interface is accommodated by torsional deformation of the rubber bushing. These rubber bushings change the track natural frequencies and make the track behave less like a suspended string or chain in tension. The longitudinal stiffness of the track is nonlinear and dynamic track tension is not uniform. The use of rubber-bushed pins in block and pin track also reduces the response of the track, when the vehicle passes through speeds which would otherwise excite the track, by damping the track vibrations, because the rubber bushings dampen the vibrations by energy absorption in the hysteresis of the rubber. The classical method of calculating the natural frequencies of the track and track tension cannot satisfactorily explain rubber bushed track/pin behavior. In addition, these methods are not sufficient for evaluating designs of improvements and modifications to the M113 tracks.

5.3. Field Observations of Track Vibratory Motion

On 19 October 1987, three MPR engineers were guests of TACOM's Aberdeen Proving Ground Liaison Officer, George C. Poteet, to witness field tests of tracked vehicles on the Perryman vehicle test courses at Aberdeen. During this visit several vehicles were observed on the test courses: an M109 self-propelled howitzer, an M2 Bradley Fighting Vehicle, an M1 main battle tank and an M548 cargo carrier. The M109 and the M548 did not have mud guard cowlings over the suspended portion of the track and it was possible to observe the track vibratory motion of these vehicles. (Note: The M548 has the same suspension as the M113.) The M109 uses the double-pin reversible block and pin track, and the M548 uses the single-pin reversible block and pin track.

No low-frequency resonant vibration of the suspended track caused by sprocket impact forces was observed in the operation of these vehicles. High-frequency or low-amplitude vibration of the tracks (with respect to what can be detected by the naked eye from a distance) was also occurring, but could not be quantified. Track vibration was observed when lower frequency modes were excited by suspension/soil interaction over rough terrain. The suspension/soil interaction caused a variation in track tension which resulted in a "snapping" of the track. This vibration was quickly damped out by the forward motion of the track and

did not appear to form a standing wave. MPR personnel also viewed a film which documented M113 vehicle tests on the Perryman course. This film showed visual track vibration to be the result of excitation of the lower modes of vibration as a result of suspension/ground interaction.

In both the field-observed and film-documented vehicle tests, the vehicles appeared to have fresh track without excessive wear on the track pads and the track bushings. As a result, this field-observed behavior is not unexpected and is in keeping with the intent of the rubber-bushed track/pin interface design which prevents standing waves from forming by rubber hysterisis damping. The main conclusions of these observations are as follows:

- In addition to resonant vibrations caused by drive sprocket impact and track centripetal forces, tracks experience vibrations from suspension/soil interaction.
- Significant damping is present in the track so results of an analytical model of the present track configuration may show standing waves.
- A model capable of a time history solution is required to account for suspension/soil interaction in the design of improvements and modifications to the track.

5.4. Rubber-Bushed Track/Pin Interface Material Properties

Actual rubber-bushed track/pin interface material properties such as rotational stiffness and damping were required for use as input data in the development of the analytical model. Appendix B documents the measurement of torsional stiffness and percent of critical damping in a rubber-bushed T130 track/pin assembly which is the type used on the M113 Armored Personal Carrier. Based on the results of these tests, the torsional stiffness of the interface is 3,700 in-lb/radian and the rubber bushing provides 11.8% of critical damping. These properties were incorporated into the analytical model described below.

5.5. Analytical Model of Track

In order to demonstrate the solution of the equations which describe the motion of the track and suspension of a tracked vehicle, a computer program was written to solve those equations and a sample preliminary analysis was accomplished. The analytic approach used for this computer program is discussed below and preliminary results obtained using this computer program are described.

5.5.1. Analytic Approach. The track and suspension of a tracked vehicle as used in the computer model are shown in Figure 5-1. The computer model includes the vehicle as a rigid body with mass and rotational inertia which can translate in two directions and can rotate about the axis normal to those two directions when responding to the forces and moments which act on it. Forces acting on the vehicle include forces from the wheels, wind resistance, and gravity. The road

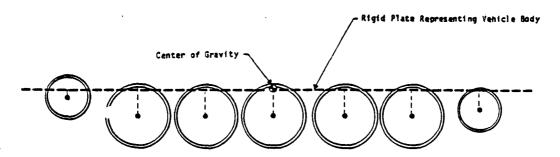
wheels, drive sprocket, and idler wheel are modeled as attached to the vehicle as shown in Figure 5-5. The forces between these wheels and the vehicle are expressed as functions of the relative displacement and velocity of the wheels with respect to the vehicle. Each wheel has mass and rotational inertia and its motion is governed by the forces imposed on the wheel from the track, from the interaction of the wheel with the main vehicle, and from gravity. The forces and moments acting on the drive sprocket, idler wheel and road wheels are shown in Figure 5-5. The track is modeled as a number of shoes, each of which is free to move in two directions and free to rotate about an axis normal to these two directions. Forces and moments acting on each shoe as included in the model are shown in Figure 5-6. These include the force due to gravity, forces on the ends of the shoe due to the relative position of neighboring shoes, and forces of interaction with the wheels and the ground if the shoe is in position to contact a wheel or the ground. The ground is modeled as a surface described by a series of line segments, and a force normal to this surface is imposed on any track shoe which interferes with the surface.

Since the response of the track is significantly more complicated than the response of the wheels and the vehicle, a two-step approach was used to integrate the system of equations which describes the motion of the shoes, the wheels, and the vehicle. The equations of motion for the track shoes are solved using a fully implicit backward difference technique by assuming the boundary conditions imposed by the wheels and the ground are constant over the time interval. In the second step of the solution for a time interval, the positions and velocities of the wheels and vehicle are revised by explicitly integrating the equations of motion for the wheels and the vehicle while the position of the shoes is assumed fixed. The small time interval required to ensure a stable solution for the track part of the analysis is considered limiting and the equations of motion of the wheels and vehicle are integrated explicitly.

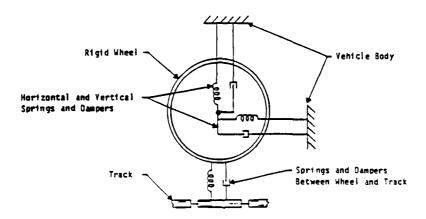
To allow flexibility in modeling the interaction of the components making up the track and suspension, stiffness and damping are entered into the program as force versus displacement and force versus velocity curves, respectively. Consequently, nonlinear effects in the bushings between track shoes and between the tracks and the wheels or the tracks and the ground could be included in the model.

5.5.2. Equations of Motion for Components. Each component in the system (vehicle, wheel, track shoe) has three degrees of freedom and three corresponding equations of motion.

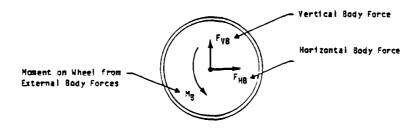
Where: x is the x coordinate of the component



(a) SUSPENSION CONNECTIVITY

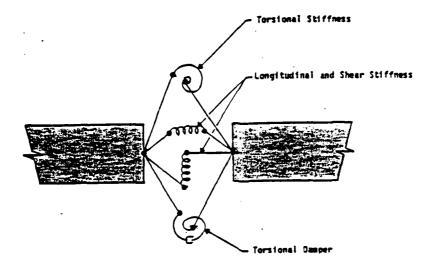


161 TYPICAL WHEEL STRUCTURE

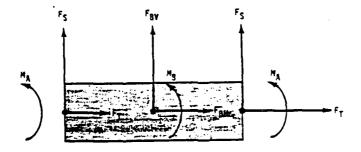


(c) TYPICAL WHEEL FORCES AND MOMENTS

Figure 5-5. Forces and Moments Acting on Drive Sprocket, Idler Wheel and Roadwheels 32



(a) TYPICAL TRACK PIN INTERFACE STRUCTURE



FRM . Horizontal Body Force

F Vertical Body Force

F = Shear Force from Adjoining Shoe

F_ = Tensile Force from Adjoining Shoe

M = Applied Homent from Adjoining Shoe

M = Moment from External Body Forces

(b) TYPICAL TRACK FORCES AND MOMENTS

Figure 5-6. Forces and Moments Acting on Each Track Shoe in the Analytical Model

y is the y coordinate of the component

θ is the angular rotation of the component

F is a force

M is a moment

t is time

m is mass

I is rotational mass moment of inertia

In these equations, the forces and moments are functions of the positions, rotations, velocities, and angular velocities of the components. When this dependence is expressed explicitly, the system of equations of motion can be written as a single vector equation as follows.

$$\frac{2}{dU} = f(U, \frac{dU}{dt}, t)$$

This system of 3n second order differential equations can be written as 6n first order differential equations by adding the two linear velocities and one angular velocity for each of the n components as a degree of freedom. The resulting system of 6n equations is solved in the computer program using a fully implicit finite difference method.

Due to the significant computer time required to solve 6n equations in 6n unknowns when n is typically in the order of 70 to 80, the problem was reduced significantly by banding the matrix of coefficients. For this reason, the equations of motion for the vehicle and the wheels are

removed from the system of equations described above, and the equations of motion for the track is solved independently.

5.6. Summary of Results of Analyses Using Model

The analytic technique described above was incorporated into a computer program and was tested on several sample problems. The purpose of these sample problems was to demonstrate that the complex system of differential equations which represents the track and suspension of a tracked vehicle could be integrated, providing reasonable and stable results. A computer generated plot of the track and suspension used for these sample problems is shown in Figure 5-7 as it was plotted on the screen of an IBM personal computer. This plot shows an approximate model of the M113 Armored Personnel Carrier. The shaded portion at the bottom of the model represents the ground which was entered as perfectly flat terrain.

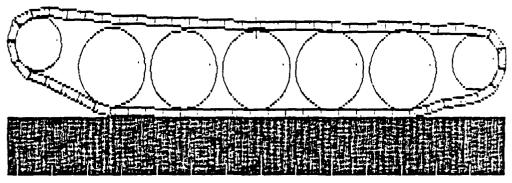
The initial problem evaluated using the model was a severe and unrealistic case where large loads occurred in the track and suspension as a result of poor initial conditions. The purpose of this analysis was to test the numerical stability of the solution technique under "extreme" conditions. A severe interference was entered between the first road wheel and the track shoe below it. This interference generated a force on the track and the road wheel which caused them to move apart as is shown in Figure 5-8 through 5-12. The track begins to move back to its proper shape as the transient progresses. This analysis was also used to define the time step under which the solution remains stable under these severe conditions. As a result of several trial and error computer runs, a time step on the order of about a tenth of a millisecond was chosen. We believe that this time step can be increased to provide a quicker computer solution time in Phase II research and development.

The problem was restarted using initial conditions in which the interference was removed and the speed of the vehicle was maintained at 10 miles per hour. The transienc was run for 1,600 time steps. Appendix C contains sample input and output from this analysis. Figure 5-13 through 5-29 show time history displacement snapshots obtained during the transient. Some wave motion appears in the track during the latter part of the transient.

Figures 5-30 through 5-37 show track tension as a function of time for several track shoes around the suspension. The calculated track tension is not a constant but fluctuates with frequencies ranging from 20-60 Hz. The magnitude of the calculated dynamic peak tensile forces are much greater than would be obtained using a static approach to balancing track deadweight and centripetal forces.

Figures 5-38 and 5-39 show the net forces on the drive sprocket in horizontal and vertical directions, respectively. The effect of the track impacting on the drive sprocket can be seen in these figures. The oscillations of the forces die out due to damping. The frequency of the

TEST CASE FOR PERSONNEL CARRIER AT 10 MPH



Scale in Feet

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Figure 5-7. Computer Generated Plot of the Track an Suspension as Plotted on the Screen of an IBM Personal Computer

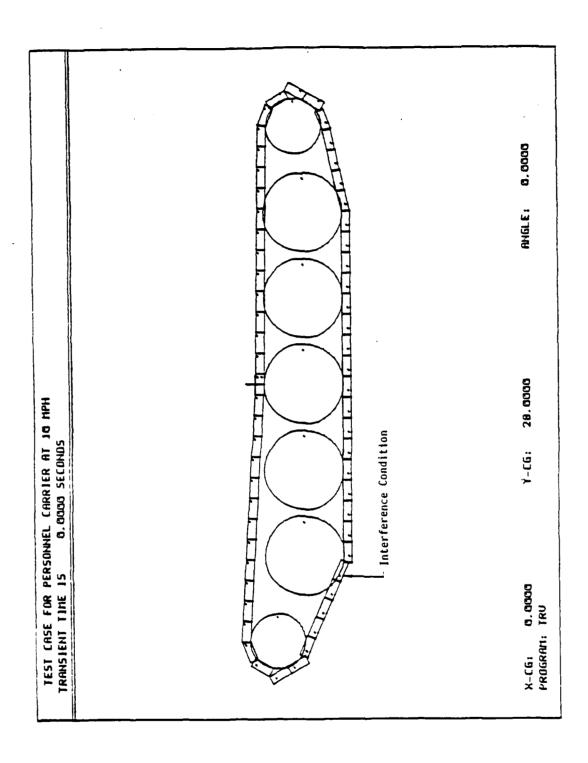


Figure 5-8. Numerical Stability Test Case for a Personnel Carrier at 10 MPH, Time = 0.000 seconds

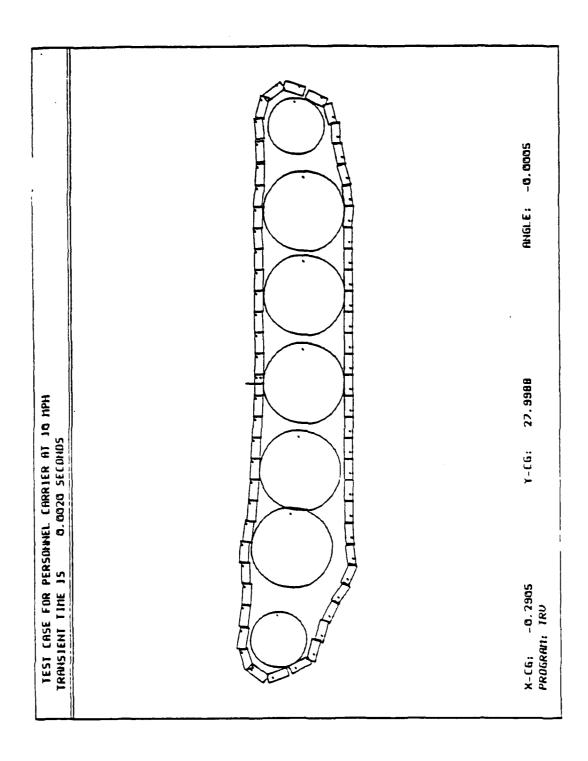


Figure 5-9. Numerical Stability Test Case for a Personnel Carrier at 10 MPH, Time = 0.002 seconds

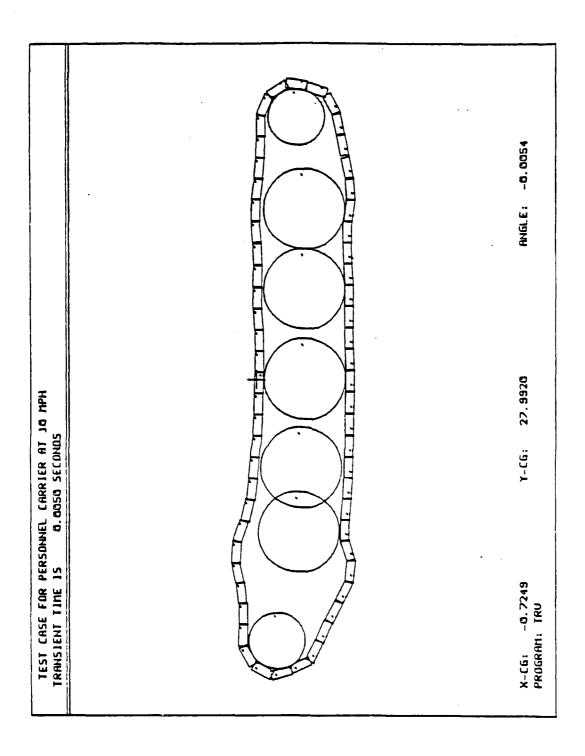
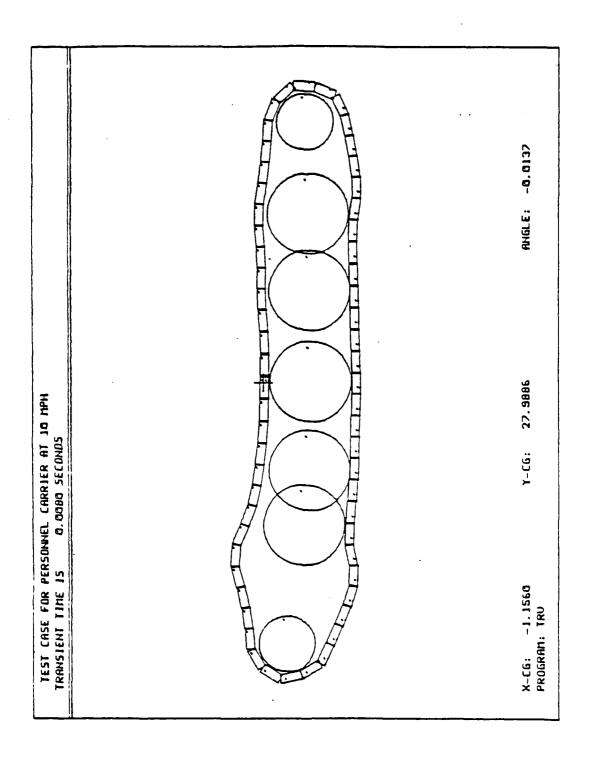


Figure 5-10. Numerical Stability Test Case for a Personnel Carrier at 10 MPH, Time = 0.005 seconds

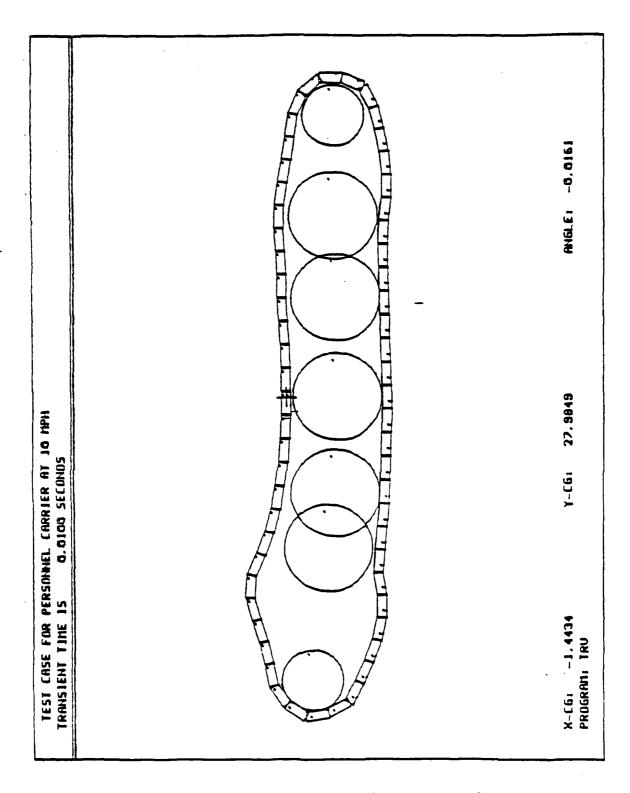


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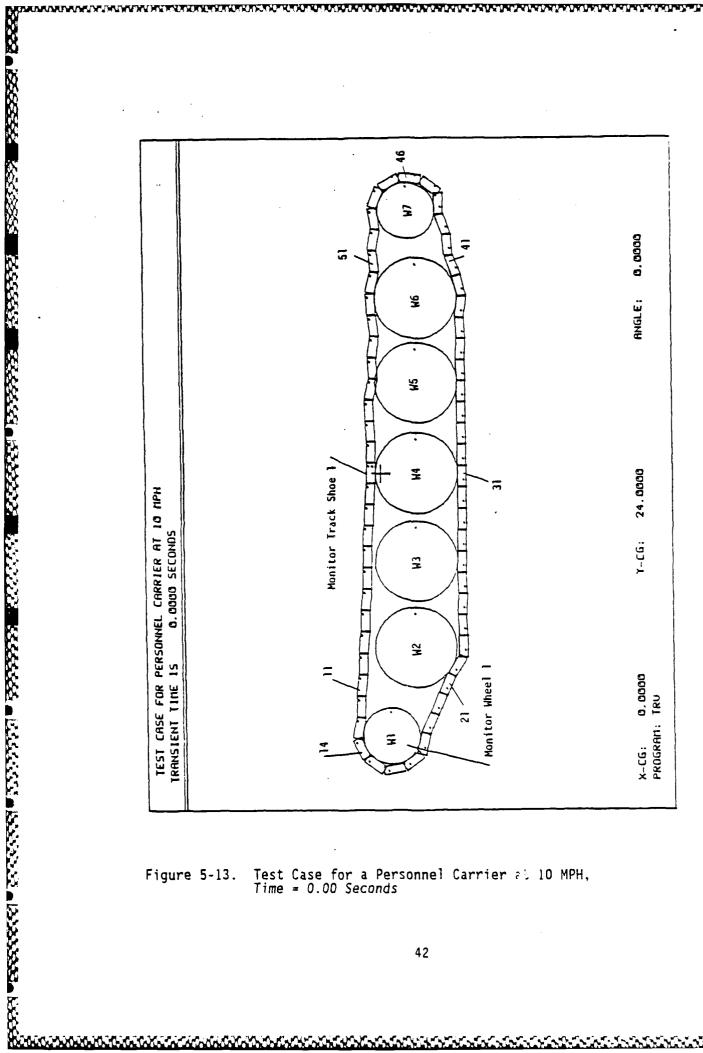
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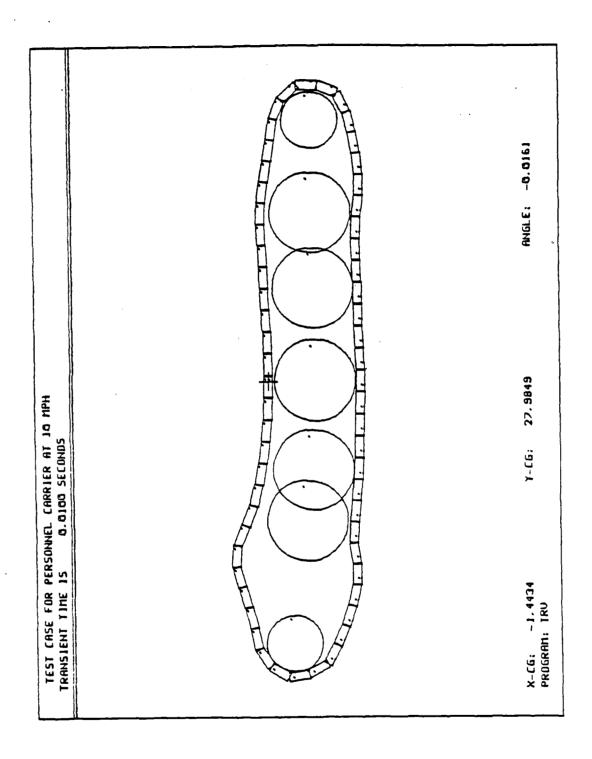
Figure 5-11. Numerical Stability Test Case for a Personnel Carrier at 10 MPH, Time = 0.008 seconds



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Figure 5-12. Numerical Stability Test Case for a Personnel Carrier at 10 MPH, Time = 0.010 Seconds





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Figure 5-14. Test Case for a Personnel Carrier at 10 MPH, Time = 0.01 Seconds

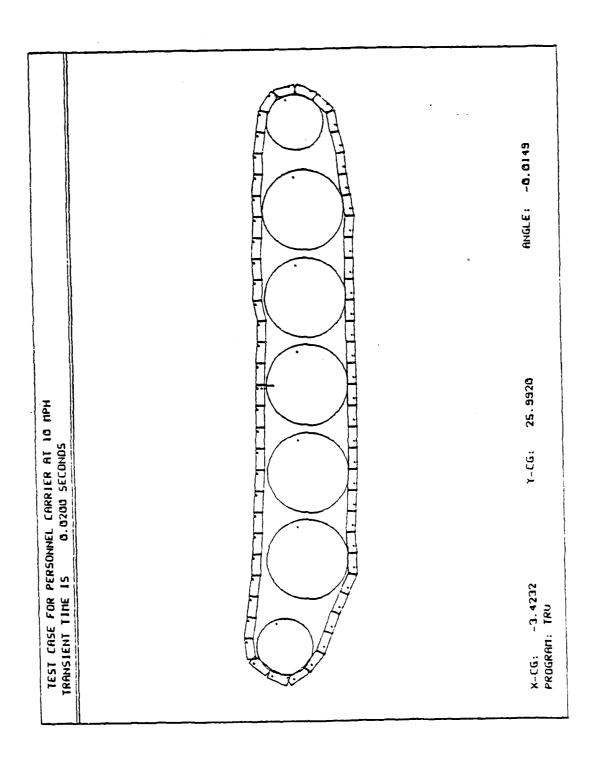


Figure 5-15. Test Case for a Personnel Carrier at 10 MPH, Time = 0.02 Seconds

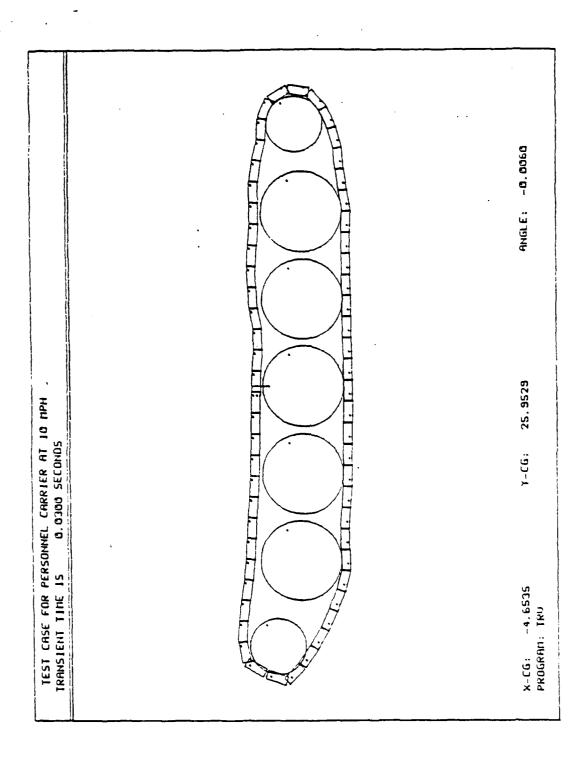


Figure 5-16. Test Case for a Personnel Carrier at 10 MPH, Time = 0.03 Seconds

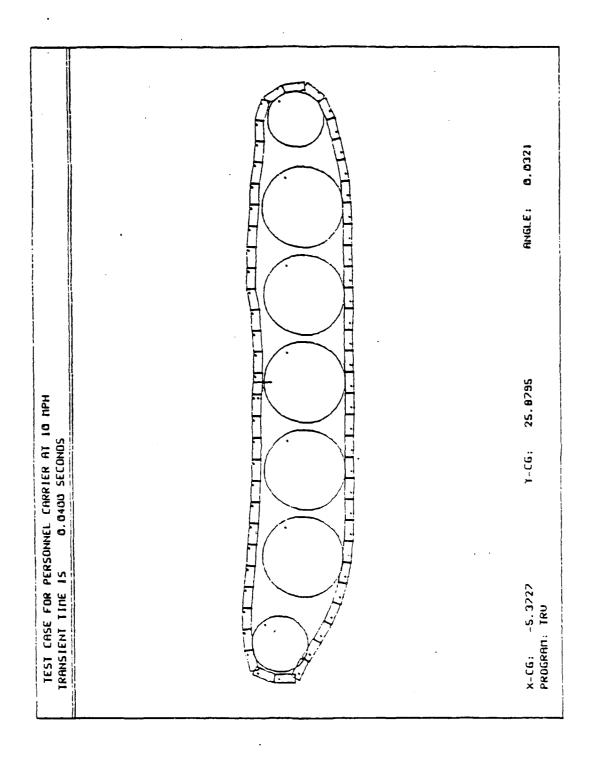
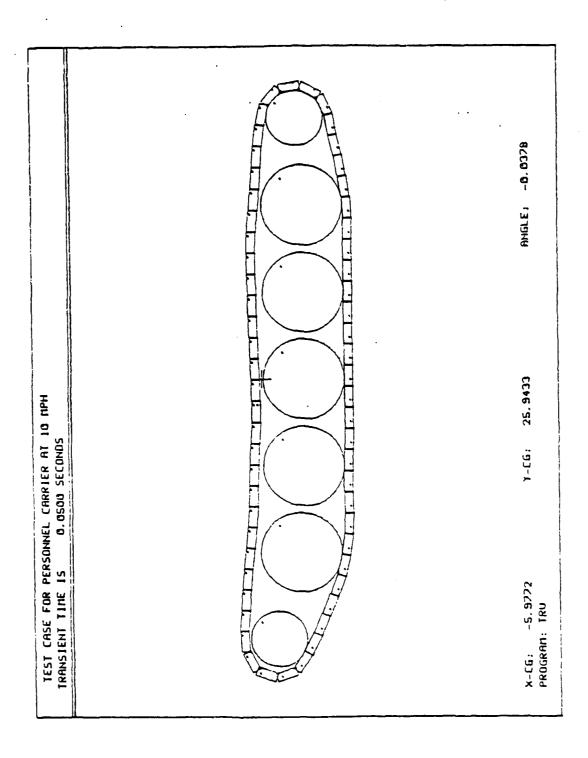


Figure 5-17. Test Case for a Personnel Carrier at 10 MPH, Time = 0.04 Seconds



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Figure 5-18. Test Case for a Personnel Carrier at 10 MPH, Time = 0.05 Seconds

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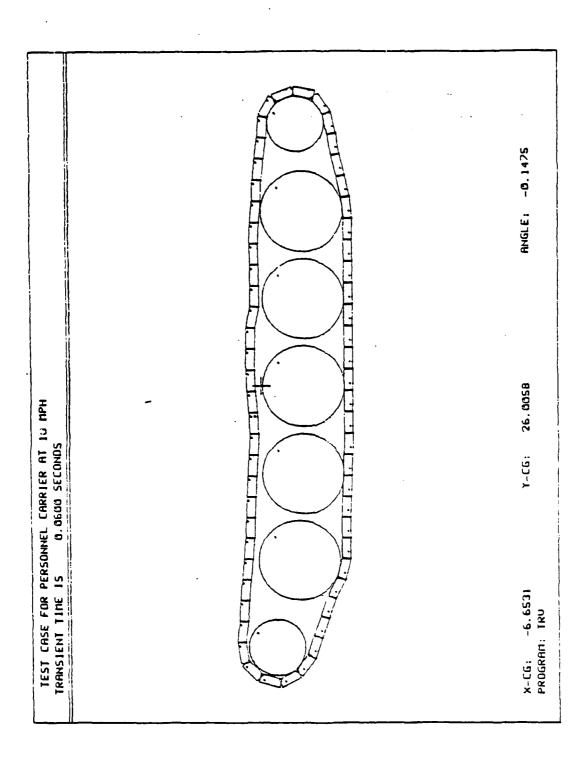
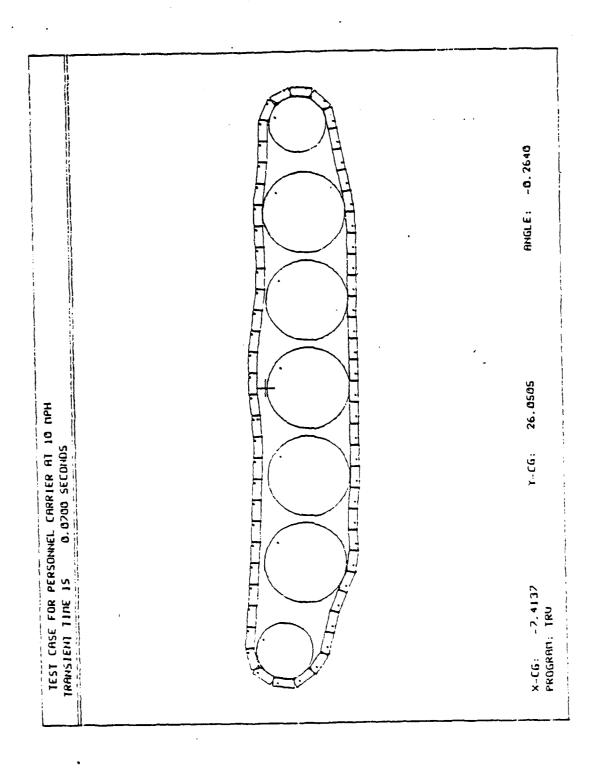


Figure 5-19. Test Case for a Personnel Carrier at 10 MPH, Time \Rightarrow 0.06 Seconds



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Figure 5-20. Test Case for a Personnel Carrier at 10 MPH, Time = 0.07 Seconds

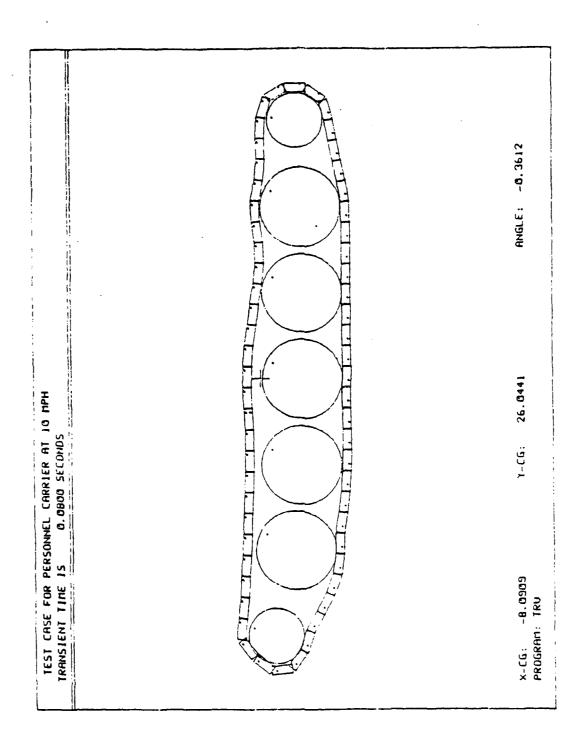


Figure 5-21. Test Case for a Personnel Carrier at 10 MPH, Time \approx 0.08 Seconds

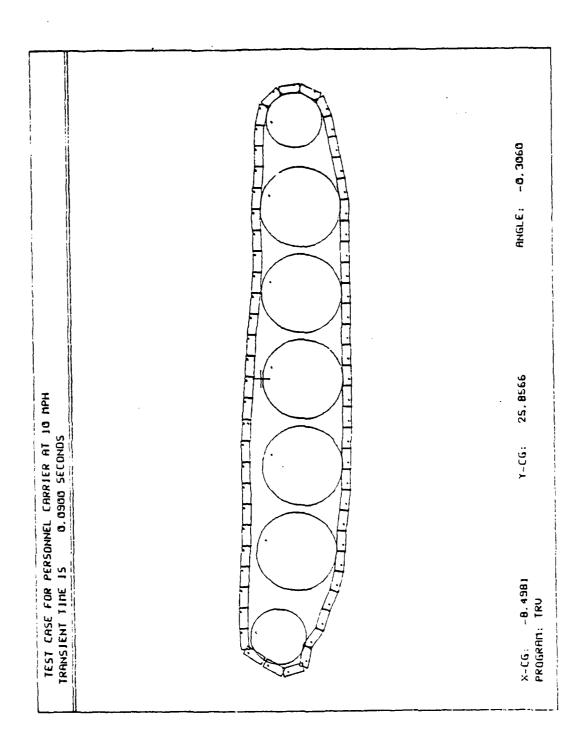


Figure 5-22. Test Case for a Personnel Carrier at 10 MPH, Time = 0.09 Seconds

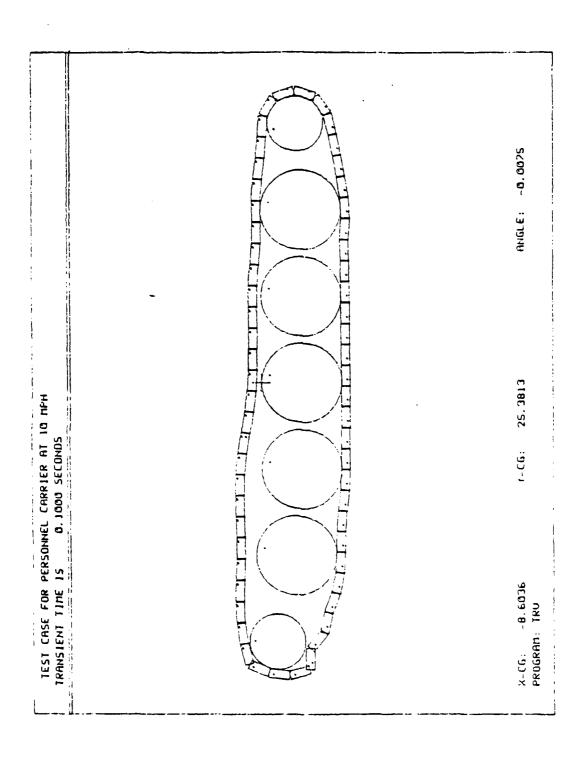
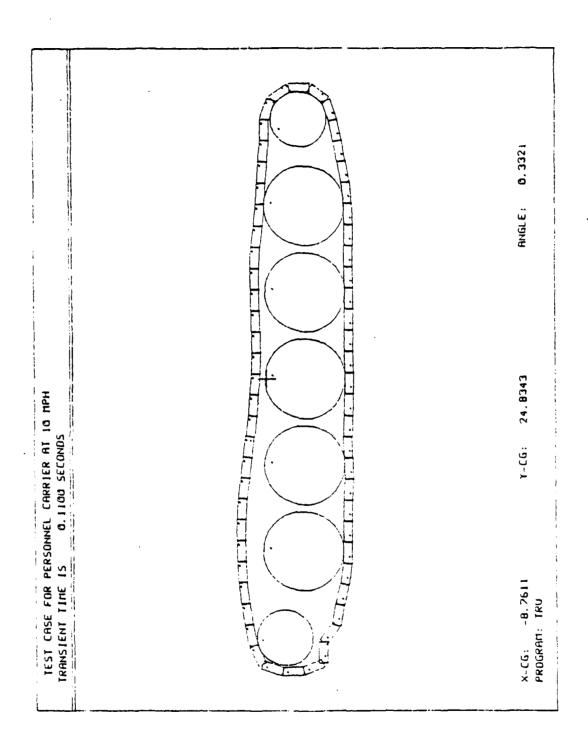


Figure 5-23. Test Case for a Personnel Carrier at 10 MPH, Time = 0.10 Seconds



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Figure 5-24. Test Case for a Personnel Carrier at 10 MPH, Time = 0.11 Seconds

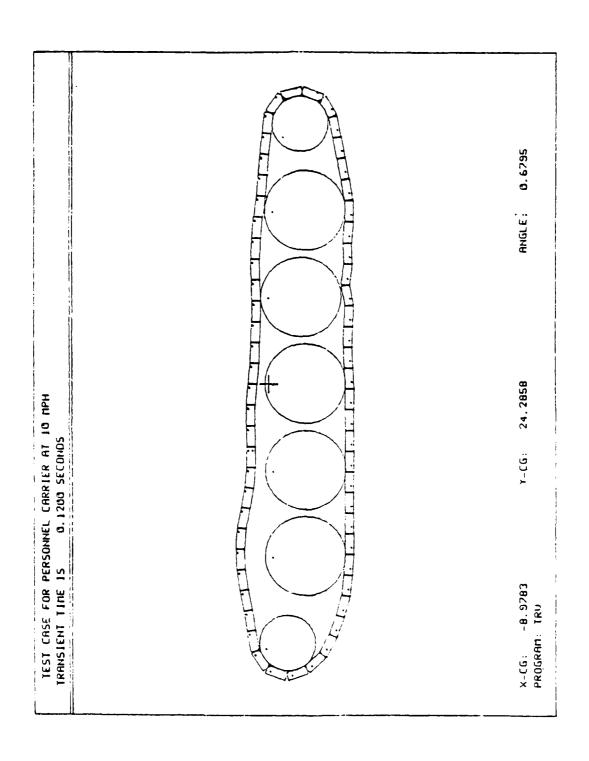


Figure 5-25. Test Case for a Personnel Carrier at 10 MPH, Time = 0.12 Seconds

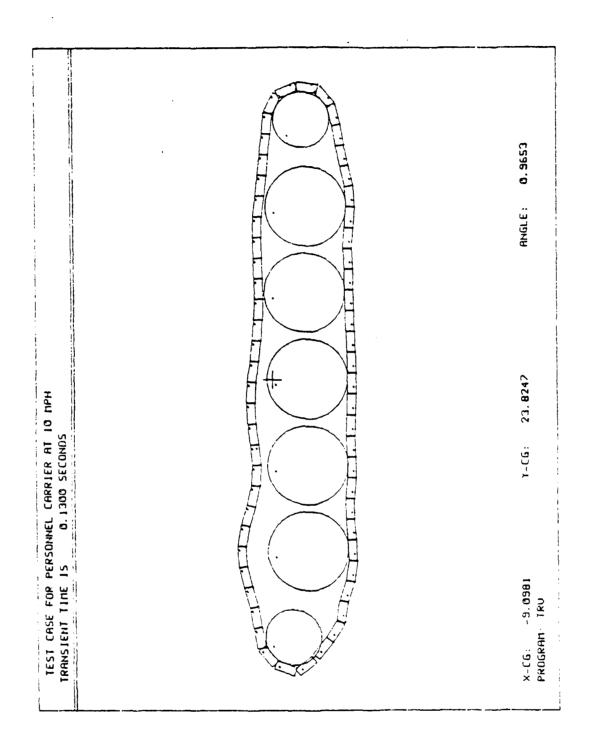
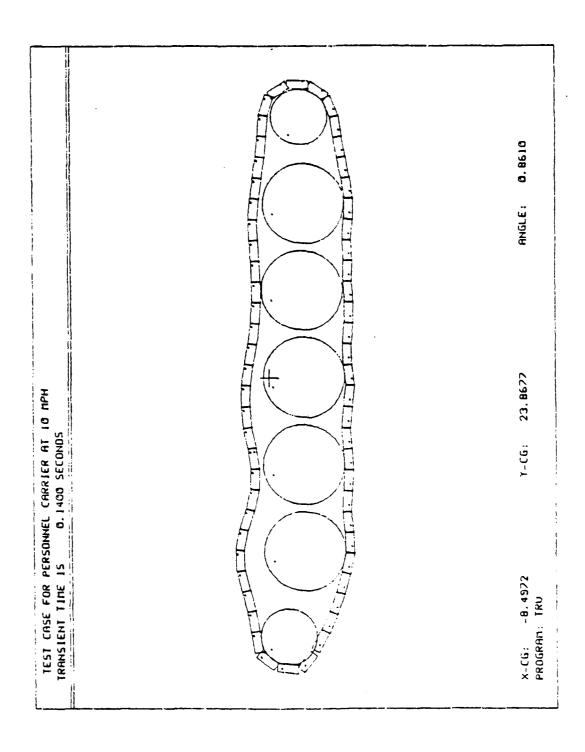
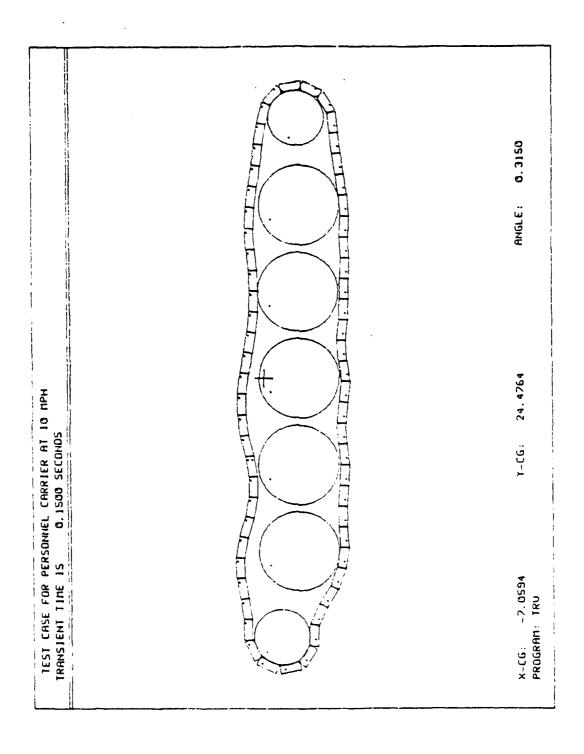


Figure 5-26. Test Case for a Personnel Carrier at 10 MPH, Time = 0.13 Seconds



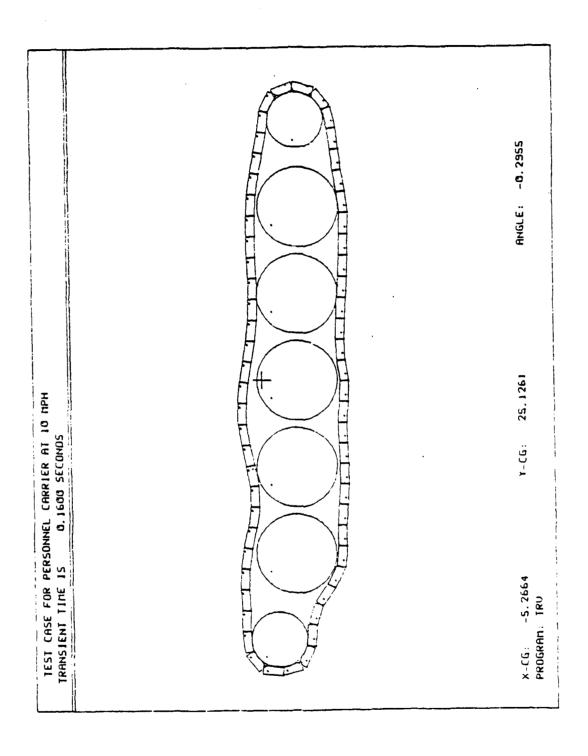
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Figure 5-27. Test Case for a Personnel Carrier at 10 MPH, Time ≈ 0.14 Seconds



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Figure 5-28. Test Case for a Personnel Carrier at 10 MPH, Time = 0.15 Seconds



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Figure 5-29. Test Case for a Personnel Carrier at 10 MPH, Time = 0.16 Seconds

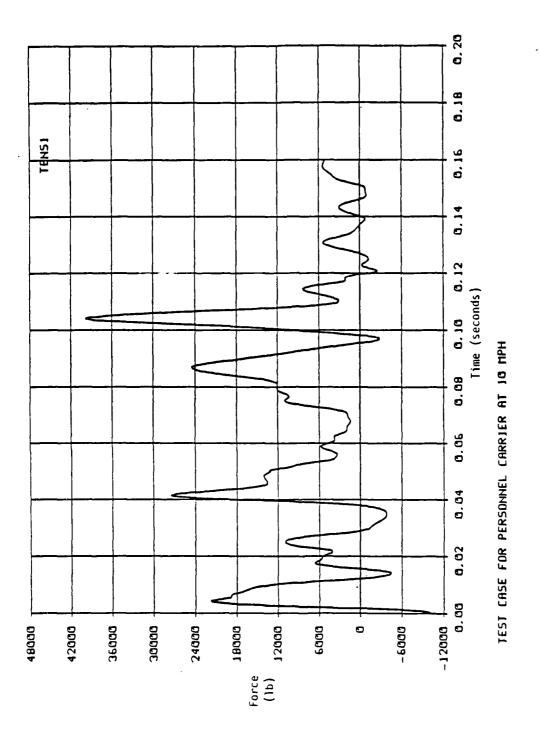
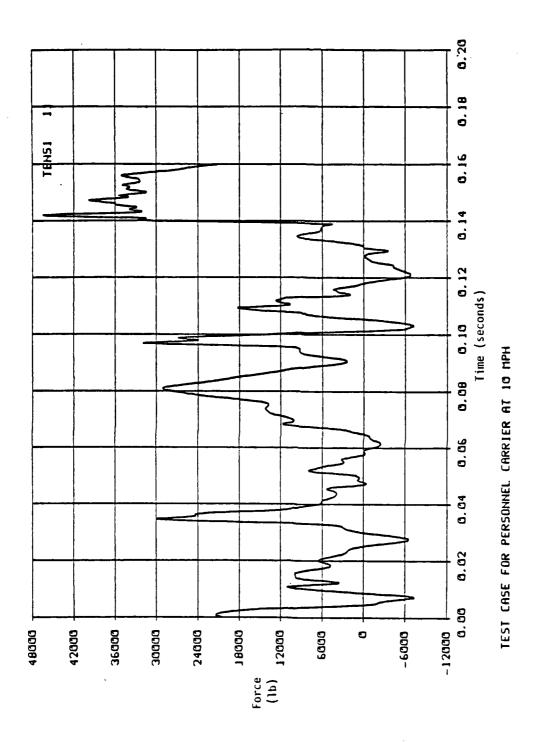


Figure 5-30. Track Tension as a Function of Time, Track Monitor Shoe 1, Test Case for a Personnel Carrier at 10 MPH



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Figure 5-31. Track Tension as a Function of Time, Track Monitor Shoe 11, Test Case for a Personnel Carrier at 10 MPH

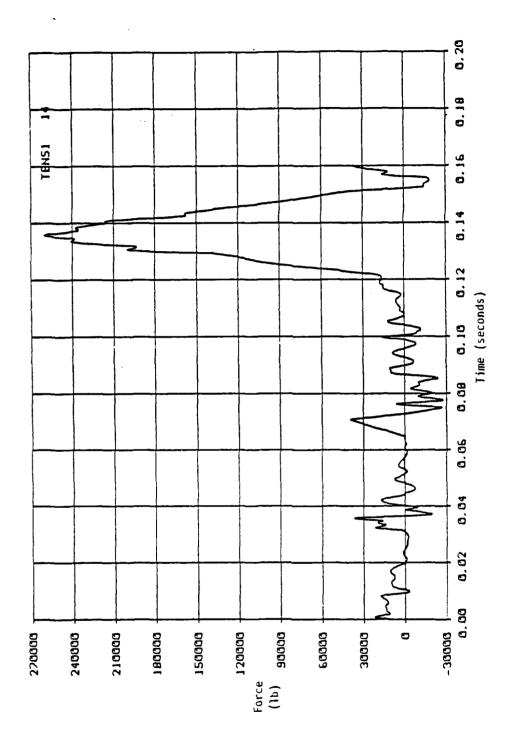
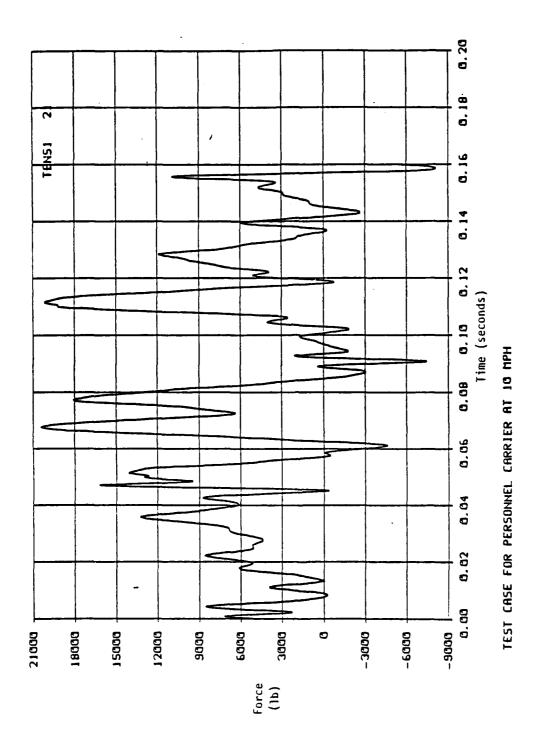


Figure 5-32. Track Tension as a Function of Time, Track Monitor Shoe 14, Test Case for a Personnel Carrier at 10 MPH



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Figure 5-33. Track Tension as a Function of Time, Track Monitor Shoe 21, Test Case for a Personnel Carrier at 10 MPH

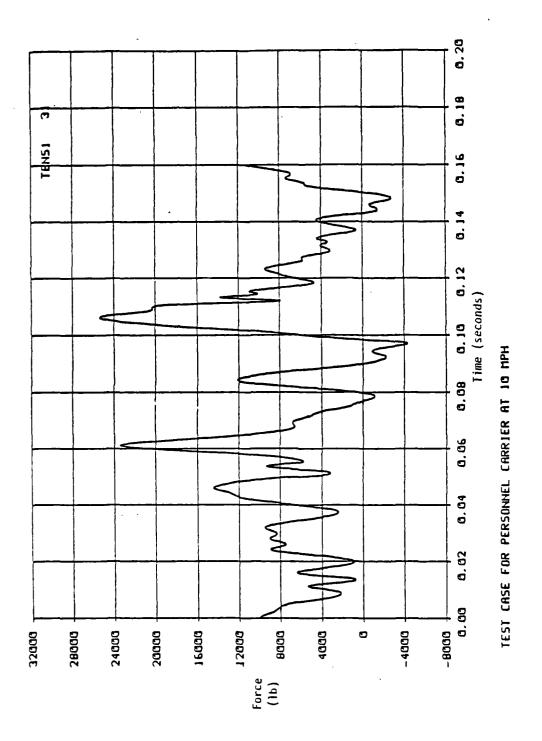


Figure 5-34. Track Tension as a Function of Time, Track Monitor Shoe 31, Test Case for a Personnel Carrier at 10 MPH

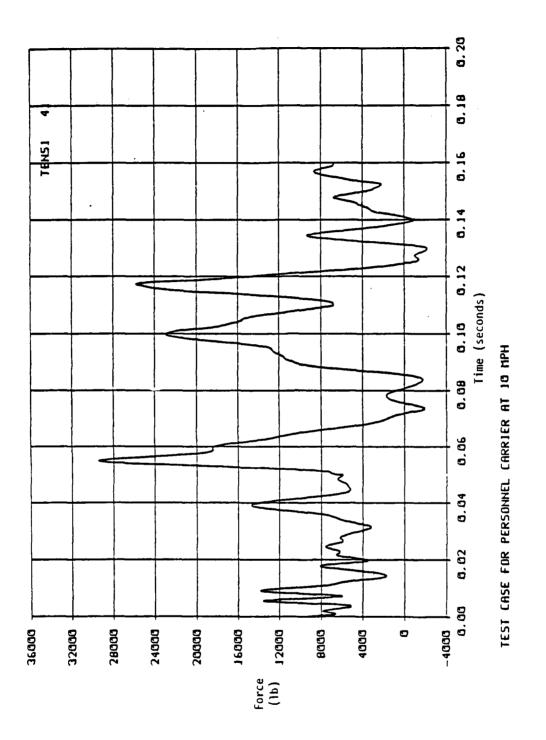


Figure 5-35. Track Tension as a Function of Time, Track Monitor Shoe 41, Test Case for a Personnel Carrier at 10 MPH

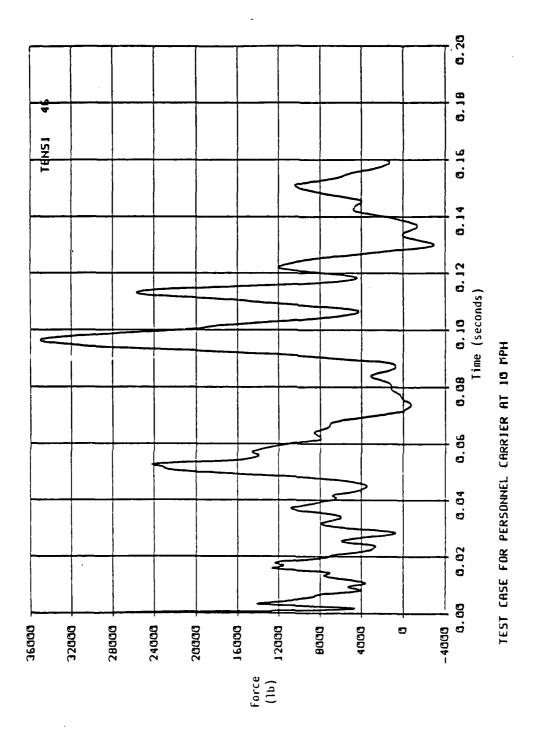


Figure 5-36. Track Tension as a Function of Time, Track Monitor Shoe 46, Test Case for a Personnel Carrier at 10 MPH

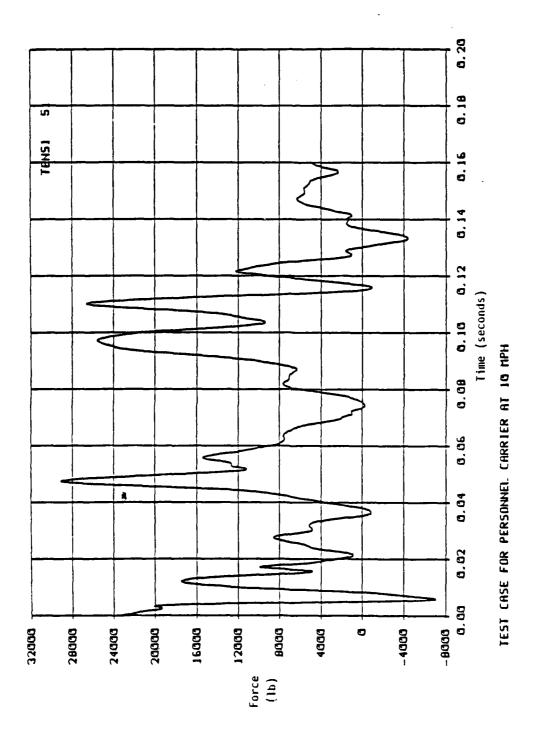


Figure 5-37. Track Tension as a Function of Time, Track Monitor Shoe 51, Test Case for a Personnel Carrier at 10 MPH

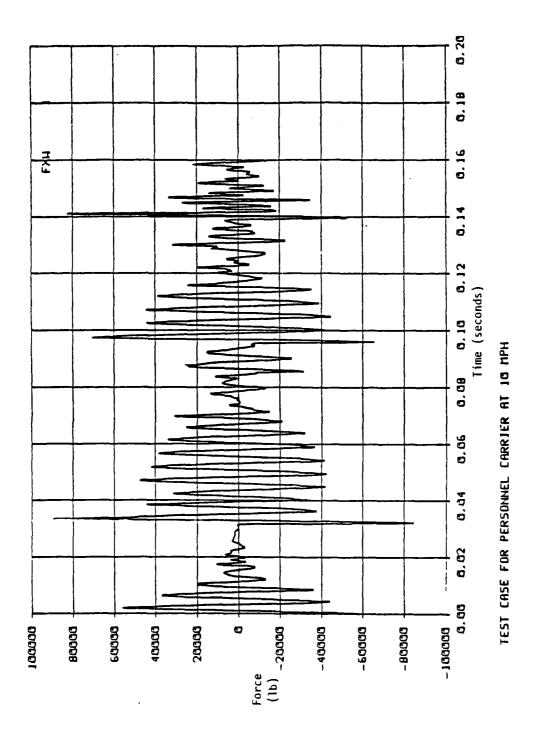
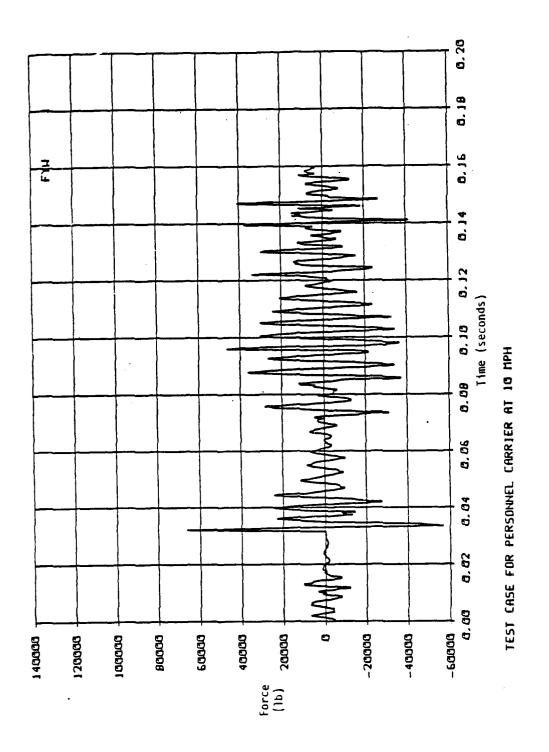


Figure 5-38. Net Horizontal Force on the Drive Sprocket as a Function of Time, Test Case for Personnel Carrier at 10 MPH



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Figure 5-39. Net Vertical Force on the Drive Sprocket as a Function of Time, Test Case for Personnel Carrier at 10 MPH

oscillations is dependent on the stiffness of the sprocket with respect to the vehicle, which has not been measured but was estimated as part of the program input.

Figures 5-40 and 5-41 show the net forces at the third road wheel in the horizontal and vertical directions, respectively. The effect of a track impact can also be seen in these figures.

Figures 5-42 and 5-43 show the shear forces at two track/pin interfaces. These forces illustrate a "beat" phenomenon associated with the impact of tracks at the drive sprocket. The higher frequency component of the "beat" is caused by the response of the drive sprocket while the enveloping "beat" is caused by the response of the track.

Due to the uncertainty associated with the dynamic material properties used in modeling the suspension components and the track, it became apparent that while the analytical approach is feasible, the exact results of this model may not be accurate and cannot be validated without additional test data. Therefore, additional constant speed evaluations were not completed, as the results of these calculations would contain consistent errors related to dynamic material property uncertainties.

We can conclude from these feasibility calculations, however, that the analytical technique is viable. Additional work is required in Phase II to test components for dynamic material properties, to refine and validate the computer model using these test results, and to evaluate alternate materials or mechanical components which will provide a more rugged and durable track than the existing track.

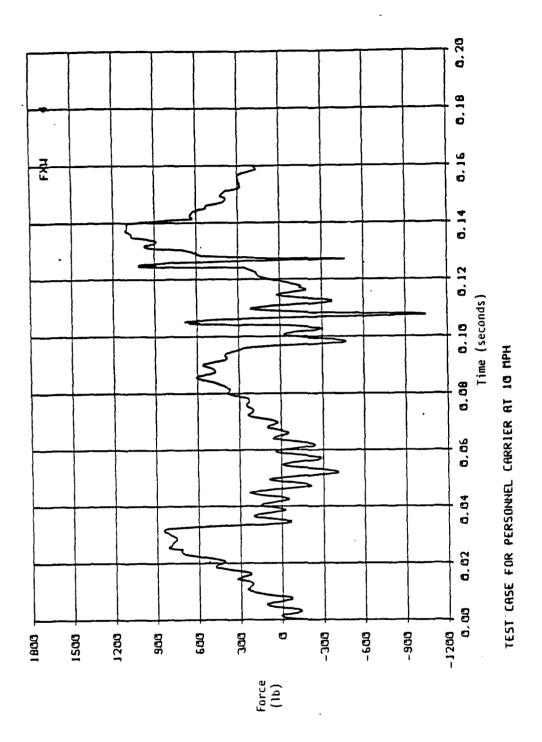


Figure 5-40. Net Horizontal Force at the Third Road Wheel as a Function of Time, Test Case for Personnel Carrier at 10 MPH

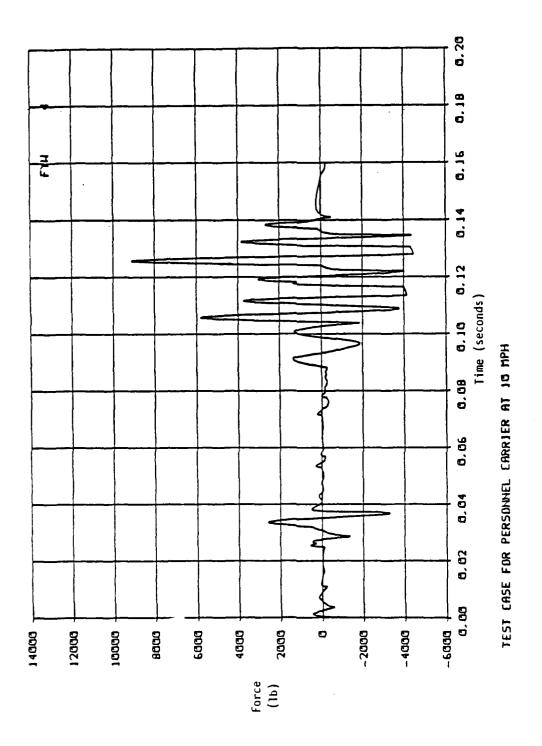


Figure 5-41. Net Vertical Force at the Third Road Wheel as a Function of Time, Test Case for Personnel Carrier at 10 MPH

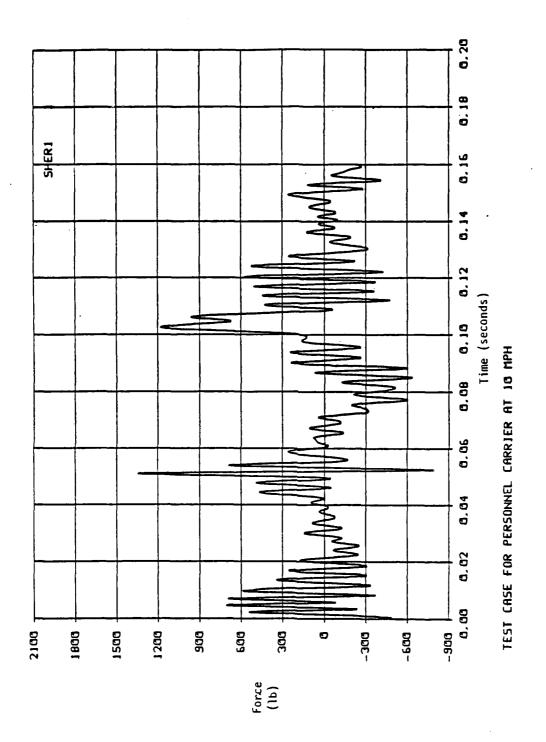


Figure 5-42. Shear Force at Track Pin Interface as a Function of Time, Monitor Track Shoe 1, Front Pin, Test Case for a Personnel Carrier at 10 MPH

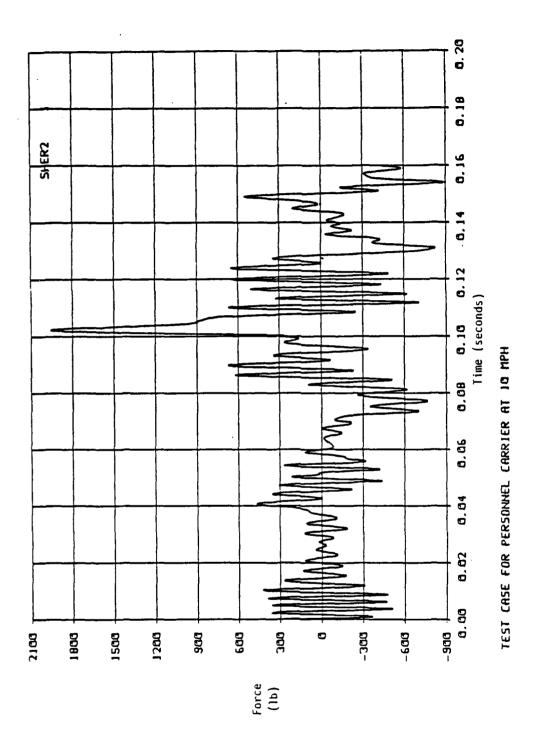


Figure 5-43. Shear Force at Track Pin Interface as a Function of Time, Monitor Track Shoe I, Rear Pin, Test Case for a Personnel Carrier at 10 MPH

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APPENDIX A DESCRIPTION OF CURRENT TRACK DESIGN PRACTICE

A.1. Track Design Practice

A summary of the current track design practice is as follows:

Reversible Block and Pin Track - The reversible block and pin track type consists of a chain formed by a series of rigid links (shoes) connected by hinged joints. The hinged joints are formed by passing a pin through interlocking links (single pin shoe) or through adjacent rigid links (double pin shoe). (Note: For the single pin shoe, the block is referred to as the body.) Track blocks can be constructed of steel casings with a rubber pad or of an all rubber construction. (Note: All rubber blocks are not currently in use on U.S. military vehicles.) Pins are high strength carbon steel. At the pin joint, the interfaces may be either dry steel on steel, lubricated steel on steel, rubber bushings or lubricated bearings. These tracks are free to rotate about the pin joint in either direction and can be used with a sprung suspension, such as a torsion bar suspension. The advantage of this track type is that, with a sprung suspension, this track can traverse uneven terrain by conforming to the shape of the terrain. One disadvantage of this track type is a large track to vehicle weight ratio (regardless of whether the block is of a steel/rubber or a rubber construction). Also, the steel pins are subject to fatique failure¹⁴. Additional disadvantages of this track type are discussed in the descriptions of the pin/track interface designs. Recently, research has been conducted on substituting aluminum for steel in the construction of the track block⁹. Although the initial tests show promise, the wear characteristics of aluminum sprockets and track blocks limit the life of these tracks. In addition, the reduced mass of the track may affect track vibration response and amplitude. This is discussed further in Section 3.2 of the report.

Irreversible Block and Pin Track - This type of track is similar to the reversible block and pin track but is connected to only allow block rotation around the pin when the track is passing over the drive sprocket or follower sprocket. The ground pressure under the irreversible block and pin track is more uniform than under the reversible block and pin track, because the track acts more like a beam on an elastic foundation. Advantages of this type of track are reduced motion resistance due to soil compaction. Disadvantages are the inability to use a sprung suspension system or to easily traverse uneven terrain.

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<u>Band Track</u> - The band track type is a continuous band which is flexible along its length. This differs from the block and pin track which is only flexible at the pin connections. The track is constructed of steel track bars reinforced longitudinally by steel wire rope cables. Track alignment guides are welded to the wheel side of steel track bars and rubber pads are bonded to the ground side of the bars. The application of this track is limited b strength, wear and fatigue considerations of the materials of

construction, particularly the wire rope. Vehicle weights for this track type have typically been less than 10 tons. The chief advantage of this track is a lower ratio of track weight to vehicle weight. Disadvantages are difficult maintenance and strength limitations.

<u>Spaced Link Track</u> - The spaced link track is similar to the block and pin tracks described above but is adapted to specific "soft" terrain conditions (e.g. deep snow) by spacing track grouses to optimize subsurface soil shear area to minimize slipping of the tracks and dissipation of tractive energy. A disadvantage of the spaced link track is that the grouses have to be designed to also withstand high impact loadings for high speed operation on hard surfaces. This track design continues to be experimental.

Pin/Track Interface Design Practice

Charles and Charle

There are four pin/track interface designs used at the pin joint of the block and pin track. These are dry steel on steel, lubricated steel on steel, rubber bushings and lubricated bearings. The advantages and disadvantages of each design are summarized as follows:

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<u>Dry Steel on Steel</u> - Dry steel on steel pin/track interfaces are used extensively in track design outside of the U.S. The advantages of this design are low motion resistance and a simple design with few parts. Disadvantages are excessive wear, a short useful life and excessive vibration and power losses at resonant velocities.

<u>Lubricated Steel on Steel</u> - Lubricated steel on steel pin/track interfaces are essentially the same as the dry steel on steel interfaces with the addition of a lubricating film between the pin and the track. The lubricated pin typically has flexible seals at the ends of the pins to prevent foreign matter from entering the joint and to keep the lubricant between the pin and the shoe. The advantages of the lubrication are reduced pin and track wear compared to the dry steel on steel interfaces. Disadvantages are short seal lives and excessive vibration and power losses at resonant velocities.

Rubber Bushings - The rubber bushed pin/track interfaces are similar to the dry steel on steel except that the pin is surrounded by a rubber bushing. The rubber bushing is preloaded in compression when it is installed. This interference fit provides a frictional bond on the pin OD and the track casing ID. The rotation at the pin is accommodated by torsional distortion of the rubber bushing instead of siiding between the pin and a dry or lubricated track casing surface. The block and pin type tracks in current use on U. S. military vehicles use a rubber bushed pin. Advantages of the rubber bushed pin are extended track life due to reduced wear of track and pin, damping of track vibrations due to hysteresis in the rubber bushings and ease of repair by replacement of sacrificial bushings. The disadvantages of the rubber bushed pin are energy

loss in the internal friction of the rubber which reduces tractive force and yehicle speed and periodic replacement of the worn rubber bushings.

<u>Lubricated Bearings</u> - Lubricated bearings at the pin/track interface were introduced by the German military during World War II. This design incorporated sealed lubricated pins supported by needle bearings4. At that time, logistics of manufacture and supply did not permit widespread deployment of this design, however, test data show that this design has the lowest drawbar coefficient of internal resistance¹⁰. This is shown in Figure 5-2. Research completed by the Department of the Army in 1969, attempted to adapt a lubricated bearing pin/track interface design for use with the M60 main battle tank¹⁵. At that time a reversible block and pin type track using a single pin shoe was tested with a sealed lubricated pin supported by spherical TFE lined bearings. Results of field tests of this pin/track interface showed failure of seals, bearings and pins after only limited operation. One conclusion drawn from these tests was that loads encountered during vehicle operation were greater than the postulated loads used in the designs of the bearings and seals. This work illustrated the need for a better fundamental understanding of the effects of track design details on vibration damping, internal friction and the dynamic loads on track components.

A.2. Road Wheels and Track Support Rollers

In the selection of the size, number and spacing of road wheels, several factors are considered. The mean maximum pressure under the tracked vehicles must meet design requirements to reduce the motion resistance of the track as it sinks into the soil. The use of many small road wheels helps to distribute the tank weight and reduce the mean maximum pressure under the tracks, but this has the disadvantage of increasing frictional losses in the road wheels and associated track support rollers. Large road wheels can also be used in an overlapping configuration to reduce mean maximum pressure under the tracks. In addition, the number of road wheels is a factor (along with track width) in meeting the required contact area of the track. In cohesive soils, the tractive force is maximized when slip (soil shearing) is minimized. The soil shear stress is a function of the tract contact area.

Two types of road wheel/suspension configurations are used with block and pin tracks: the conventional suspension and the flat track suspension. The conventional suspension uses small roadwheels with track support rollers and the flat track suspension uses large road wheels without support rollers. The internal resistance of the conventional suspension track has been shown to be consistently greater than that of the flat track suspension².

APPENDIX B

BENCH TEST OF TORSIONAL

STIFFNESS AND DAMPED NATURAL

FREQUENCY OF A TRACK BUSHING ASSEMBLY

- B.1. <u>Purpose</u>. The purpose of this Appendix is to document the measurement of the torsional stiffness and natural frequency of the M113 T130 track rubber bushed track/pin interface.
- B.2. <u>Summary</u>. The measurements were completed in a simple bench test using two track links connected by a rubber bushed track/pin interface.

The torsional stiffness was measured by clamping one of the track shoes to the bench and barging a cantilevered weight from the end of the second shoe as shown in Figure B-1(a). The rotation at the pin was measured and correlated with the applied moment at the pin. The resulting torsional stiffness curve is shown in Figure B-2. A torsional stiffness of 3700 in-lb/radian is the approximate average.

The natural frequency was measured using the impulse test method by attaching an anchored potentiometer linear transducer to the end of the cantilevered track and striking the track with a rubber mallet. A five volt power supply was provided as the excitation voltage to the transducer. The output voltage was directed to a Hewlet-Packard 7090A Measurement System Plotter as shown in Figure B-1(b). A plot of one of the impulse tests is shown in Figure B-3. The damped natural frequency of the single track shoe spring-mass system was measured to be 11.5-12.5 Hz. (Note: The stiffness of the potentiometer was assumed to be negligible.) Using the decay curve shown in Figure B-3, an estimate of the damping constant and the damping ratio can be calculated as follows:

logarithmic decrement =
$$\delta = \ln \left[\frac{x(t)}{x(t+T)} \right]$$

x(t) = amplitude of vibration at time (t)

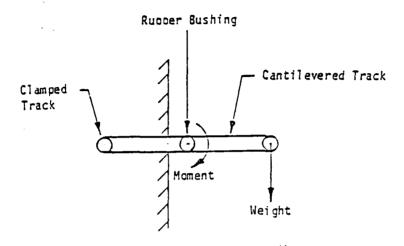
x(t + T) = amplitude of vibration at time (t + T)

$$\delta = \ln \left[\frac{1.36 - 0.92}{1.13 - 0.92} \right] = .740$$

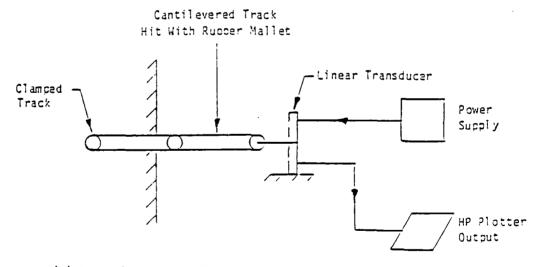
For $\delta < 1$, $\delta = 2\pi \xi$

 ξ = critical damping constant

 ξ = .740/2 π = .118 or 11.8% of critical damping



(a) Torsional Stiffness Measurement



(b) Natural Frequency Messurement

Figure B-1. Test Configuration

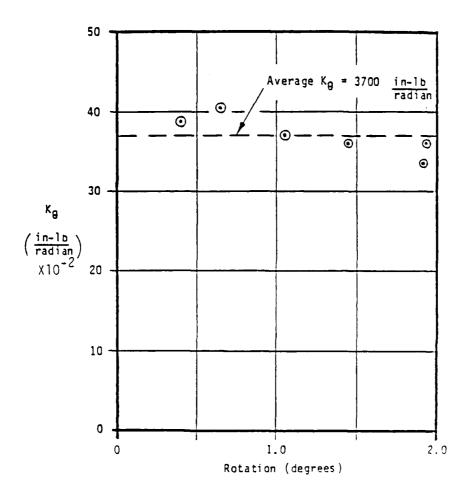


Figure B-2. Torsional Stiffness of Rubber Bushed Track/Pin Interface Assembly

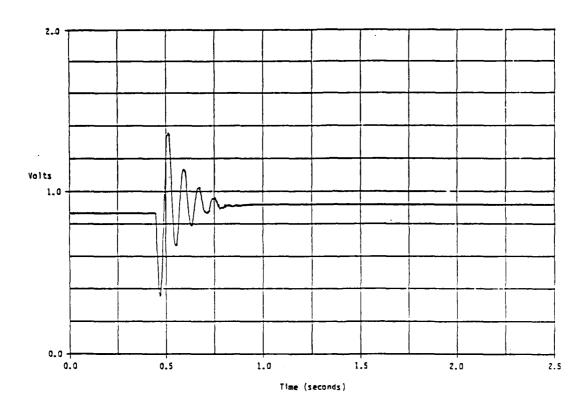


Figure B-3. Impact Test of Rubber Bushed Track/Pin Interface Assembly

APPENDIX C
LIST OF INPUT AND OUTPUT
FOR SAMPLE COMPUTER ANALYSES

This appendix contains input and output for the sample case without the track wheel interference as described on p. 35 of the report. Output results from six time steps are included to show the format and details of the computer solution.

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Number of Links	66	
Number of Drive Wheel	1.	
Number of Bushing Forces	3	
Number of Bushing Resistances	2 3 2	
Number of Wheel Forces	3	
Number of Wheel Resistances	2	
Humber of Terrain Forces	3	
Number of Terrain Resistances	2	
Number of Terrain Points	2	
Number of Track Shape Points	14	
General Vehicle Data		
Mass of Vehicle		80E+0
Rotary Inertia of Vehicle		00E+0
Wind Resistance Coeff		00E+0
Rotational Resistance Coeff	.000	00E+ 0
Initial Vehicle Position		
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Y-Coordinate of Vehicle CG		00E+0
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Initial Angular Velocity		00E+0
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THERE ARE 50 MONITORS

RV. Tracked Vehicle Dynamics - Versian 1.00

CUITPUT AT TIME .0000

Displacements, Velocities, and Accelerations										
		X	,,,,,,,,,,,,,,,,	Thete	X-Vel	Y-Vel	Omega	X-Accel	Y-Accel	Alphe
Vehicl	•	.000000€+00	.24000E+02	.000000€+00	14530E+03	.000000E+00	.00000€+00	.35229€+03	.14714E+05	.13395E+01
Uheel	1	·.74882E+02	.21536E+02	.00000E+00	-,14530E+03	.00000E+00	.15708E+02	·. 15975E+05	61449E+06	.000000€+00
Uheel	2	49691E+0Z	.14411E+02	.00000E+00	14530E+03	.000000€+60	.11396E+02	26324E+05	20615E+05	.00000E+00
Wheel	3	24995E+02	.14044E+02	.00000E+00	14530E+03	.00000€+00	.11396E+02	43499E+03	19321E+05	.00000E+00
wheel	4	.21929€-01	.13952E+02	.00000E+00	14530E+03	.00000E+00	.11396E+02	18532E+04	18789E+05	.00000E+00
wheel	5	.25600E+02	. 13726€+02		-,14530€+03	.00000€+00	.11396E+02	69000E+05	18208E+05	.00000E+00
Wheel	6	.49944E+02	. 13651E+02	.00000E+00	14530€+03	.00000€+00	.11396€+02	.49884E+04	20919E+05	.00000E+00
Wheel	7	.74848E+0Z	.16061E+02		14530€+03	,00000E+00	.1570 8E+ 02	.20009€+05	41951E+06	.000000€+00
Link	1	.39392E-02	.26702E+02		·.29054E+03	.41888E+01		3906 8 £+03		
Link	2	 .59202E+01 	.26923E+02		·.29044E+03	.66861E+01		11567E+04	. 69 045E+03	.225 99E+ 03
Link	3	11841E+02	.272348+02		29035E+03	.85477E+01	.000000€+00	60155E+04	49428E+03	
Link	4	17761E+02	.27587E+02		29033E+03	.87319E+01	.00000E+00	. 14119E+05	.31063E+03	19537E+03
Link	5	23682E+02	.27781E+02		29059€+03	.85038E+00	.000000€+00	·.62662E+06		.17226E+04
Link	6	29640E+02	.27857E+02		·.29057E+03	.30601E+01	.00000€+00	.59208E+04		66772E+02
Link	7	35983E+02	.28212E+02		28996E+03	. 13591E+02	.00000E+00	.61264E+04	.23759E+05	39791E+03
Link	8	42123E+02	.28548E+02		·.29057E+03	.26258E+01	.00000€+00		. 99398E+05	.95967E+02
Link	9	48258E+02	.28923E+02		28978E+03	. 15372E+02	.00000E+00	.50829E+04	. 15512E+06	.15889E+04
Link	10	54391E+02			29060E+03	16675E+00	.00000E+00		15189E+06	
	11	60518E+02	.29634E+02		28947E+03	. 18092E+02	.000000€+00		.11422E+06	.52726E+04
	12	66647E+02			29058E+03		.00000E+00			.40997E+04
	13	72719E+02	.30591E+02		28655E+03	.34048E+02	.00000E+00	.17472E+05	.49639E+06	.87112E+03
	14	·.78453E+02			27454E+03		.000000€+00		53381E+06	
	15	82909E+02			23066E+03		.00000€+00	.34876E+05		15071E+04
Link	16	84175E+02			12069E+03		.000000+00		·.21328E+06	
	17	·.81854E+02			56862E+02		.0000000	. 11983E+06	.10754E+06	.53529E+03
Link	18	77054E+02			29584E+01		.00000E+00		42934E+05	. 19779E+04
Link	19	·.71354E+02			13280E+02		.000000+00		66907E+05	
	20	65818E+02			- 11075E+02		.000000€+00	.84902E+04	.93119E+05	.57058E+03
	21	60295E+02			14067E+02		.000000€+00		12815E+06	
	22	55006€+02			22520E+62		.0000000	.33520E+05		29433E+01
	23 24	-,49414E+02 -,43360E+02	.12308E+01		51082E-01 23529E+00		.00000€+00	.72436E+04	.39366E+06 82441E+05	.38517E+03
Link	23	37306E+02			18647E+00	.82656E+01 73589E+01	.00000€+00	.62348E+04	.11887E+06	.10066E+03
Link	26	31248E+02	.12307E+01		15856E+00	.67862E+01	.00000€+00		67688E+04	.36963E+02
	27	25184E+02			40188E-01		.00000E+00	.49189E+04		·.16168E+03
Link	28	19116E+02	.12305E+01		23107E-03	.25913E+00	.00000E+00	.42506E+04	.42026E+05	.24637E+03
	29	13045E+02			41441E-03		.00000E+00	.22988E+04		27557E+03
Link	30	69731E+01	.12303E+01		90224E-03	.51204E+00	.00000E+00	48103E+03	.62980E+05	.37932E+03
Link	31	90151E+00			86636E-03			35580E+04		
	32	.51688E+01	.12301E+01		10557E-02	.55387E+00		10121E+05	.80714E+05	.87004E+02
	33	.11235E+02			32299€-02			14836E+05		
	34	.17296E+02	.12300E+01		78169E-02	.15072E+01	.00000E+00		.12015E+06	.13097E+04
	35	.23352E+02			36720E-01		.00000E+00		49077E+05	
	36	.294046+02	.12298E+01		97182E-01	.53133E+01	.00000E+00	.93625E+04	.19764E+06	.68871E+03
Link	37	.35458E+02			16640E+00		.00000E+00		19770E+06	
	38	.41509E+02	.12296E+01		31522E+00	.95658E+01	.00000E+00	.90389E+03		10515E+04
	39	.47544E+02			10157E+01	17150E+02	.00000E+00		87404E+05	.41951E+04
	40	.53514E+02	.14192E+01		39896E+01	.33815E+02	.00000E+00	-,79247E+05		22147E+04
	41	.59267E+02	.32857E+01		10014E+02	.53006E+02	.00000E+00		29262E+06	.55247E+02
	42	.65099E+02	.46151E+01	.89983E-01	58784E+00	.13057E+02	.00000E+00	.18709E+05	.22113E+06	.12071E+04

امعا		nts, Velocit	ies, and Acco	elerations						
•		X	· Y	Theta	X-Vel	Y-Vet		X-Accel		Alpha
nk	43	.70969E+02	.5944SE+01		85194E+01	.49022€+02				.47560E+04
w.	44	.76854E+02	.70123E+01	.10684E-01	82924E-02	. 15523E+Q1	.00000€+00	65032E+04	21226E+06	·.52489E+04
*	45	.81806#+02	.931686+01	.887998+00	53619E+02	.11272E+03	.00000E+00	17488E+05	.68659€+06	.77698E+03
rik .	46	.84013E+02	.14833E+02	. 14833E+01	13260E+03	.14474E+03	.00000€+00	13599E+06	.57683E+05	29953E+04
	47	.82851E+02	.20684E+02		21426E+03	.12789E+03			17873E+06	
	48	.78505E+02		.27776E+01		.51728E+02			46967E+06	
	49	.72551E+02			28892E+03			.47450E+05		18527E+05
	50	.66456E+02	.25209€+02		28881E+03	.22727E+02			37006E+06	
×		.40350E+02			28978E+03			57123E+04		.28461E+04
		.54294E+02								
*				.28964E+01		.34963E+02		11333E+05		20269E+04
	53	.48226E+02			29013E+03				45251E+06	
×		.421166+02			28930E+03				.49836E+06	
	55	.36016€+02		.30087E+01		192476+02			13315E+06	
	56	.29893E+02			29027E+08		.00000€+08		15360E+06	
ĸ.	57	.23840E+02			26621E+03				.68399€+05	
ĸ	58	.17793E+02	.26965E+02	31061E+01	29051E+03	51509€+01	.000000€+00	.55140E+06	.27421E+04	12B13E+04
wk.		,11862E+02	.26735E+02	30996E+01	29047E+03	60961E+01	.00000E+00	.50733E+04	29404E+04	.55364E+03
	60	.59311E+01			29060E+03		.00000E+00		52631E+03	
:01	and	1 Homents FX	FY		FX-End 1	FY-End 1	FX-End 2	FY-End 2	M-End 1	M·End 2
ici		.91173E+04		.17145E+06	TA CING 1	PT-CIM I	FA-EIM E	AL-CHO F	M-EIM I	M. CIM. C
	٠,	49522E+04		.00000E+00						
et.		30536E+04		.00000E+00						
	3	50459E+02		.00000E+00						
el.			21796E+04	.00000E+00						
æŧ	5	+.80040€+04		.00000E+00						
eel	6		24267E+04	.00000E+00						
el	7		19205€+06	.00000€+00						
W.	1		-,11362E+02				.10002E+05			
W.	2		20093E+02				.99423E+04			
w.	3		·.20093E+02		99423E+04	.50893E+03				
ĸ.	4	.000000€+00	·.20093E+02		·.96295E+04	.\$1454E+03	.10364E+05	51060E+03	.28448E+01	.12159E+03
rk .	5		20093E+02		10364E+05		+.22220€+05			
×	6	.00000E+00	·.20093E+02	,00000E+00	.22220E+05	.47776E+03	21912E+05	.16113E+04	.34070E+02	16265E+03
ĸ	7	.000000€+00	20093E+02	.0000000+00	.21912E+05	16113E+04	21594E+05	.28669€+04	.16265E+03	.16934E+03
wk	8	.000000€+00	20093E+02	.00000E+00			21256E+05			19694E+03
*	ě		20093E+02	.000000€+00	.21256E+05		20991E+05			.23999E+03
×	10		-,20093E+02	.0000000+00			210216+05			
-k	11		20093E+02	.00000€+00	.210216+05		21462E+05			.31400E+03
	12		20093E+02	.00000E+00			21810E+05			
k	13		20093E+02	.000000€+00			209018+05			
	14		.13793E+04	.0000000			34256E+04			
	15		20093E+02	.000008+00	.34256E+04		16121E+04		10489E+04	
	16		20093E+02	.000000€+00			17891E+04			.10846E+04
١k	17	·.37585E+03	34741E+03	.00000E+00	.17891E+04	.47773E+04	.48179E+04	.11624E+04	10846E+04	.16000E+04
٦k	18	.00000E+00	20093E+02	.000000€+00	48179E+04	11624E+04	.50374E+04	10501E+04	16000E+04	51236E+03
	19		·.20093E+02				.54000E+04			.84905E+02
nk			20093E+02		54000E+04		.58415E+04		84905E+02	
	21		20093E+02		58415E+04					
	22		97251E+02						.27001E+03	
3			20431251				AL4386+04			

Output File

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TRY, Tracked Vehicle Dynamics - Version 1.00

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-.14813E-01 .27755E-01

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3	.0003	.0001000	2.500	
4	.0004	.0001000	2.500	
5	.0005	.0001000	2,500	
. 6	.0006	.0001000	2.500	
7	.0007	.0001000	2.500	
8	.0008	.0001000	2.500	
9	.0009	.0001000	2,500	
10	.0010	.0001000	2.500	

Output File - Page 10

TRY. Tracked Vehicle Dynamics - Version 1.00

OUTPUT AT TIME .0010

0 (spieces	ents. Velociti	es. and Acce	iterations						
	x	y	Thete	x-vet	Y-Vel	Omega	X-Accel	Y-Accel	Alpha
Vehicle	14513E+00	.24007E+02	.64221E-06 -	.14497E+03	. 14133E+02	.12400E-02	.30724E+03	. 130416+05	.11114E+01
Wheet 1	75031E+02	.21240€+02	.15708E-01 -	.14436E+03	56546E+03	. 15708E+02	.61013E+05	43152E+06	.000000E+00
Wheel 2	·.49848E+02	.14403E+02	.11396E-01 -	.16502E+03	74658E+01	.11396E+02	36537E+04	.26094E+05	.00000E+00
Wheel 3	25140E+02	.14036E+02	.113966-01 -	.14567E+03	14161E+02	.11396E+02	30147E+03	37097E+04	.000000E+00
Wheel 4	12415E+00	.13945E+02	.11396E-01 -	.14664E+03	·.11119E+02	.11396E+02	47789E+03	.23091E+04	.00000E+00
Wheel 5	.25622E+02	.13719€+02	.11396E-01 -	.21014E+03	94219E+01	.11396E+02	58326E+05	.69492E+04	.00000E+00
Wheel 6	.49601E+02	.13643E+02	.11396E-01 -	.14124E+03	75063E+01	.11396E+02	.52707E+04	.40800E+05	.00000E+00
Wheel 7	.74709E+02	.15762E+02	.15708E-01 -	.14227E+03	56653E+03	.15708E+02	14305E+06	.72352E+04	.00000E+00
Link 1	28440E+00	.26702E+02	.311246+01 -		21457E+01		.21937E+05		79425E+03
Link 2	62124E+01	.26928E+02	.30954E+01 -			43236E+00			
Link 3	12163E+02	.27241E+02	.30826E+01 -			12838E+00			.80180E+02
Link 4	18109E+02	.275948+02	.308186+01 -		.73019E+01		23093E+06	.58539€+64	.12132E+04
Link 5	24167E+02	.27788E+02	.31362E+01 ·		.16472E+02	.38853E+00	.10802E+06		12766E+04
Link 6	30189E+02	.27876E+02	.31199E+01 -			13512E+01			
Link 7	36281E+02	.28224E+02	.30487E+01 -		.59484E+01		· 10497E+06		.33486E+04
Link 8	42412E+02	.28561E+02	.31225E+01 -			24729E+01			.38855E+04
Link 9	48546E+02	.28956E+02	.30369E+01 ·		.61100E+01		13103E+04		.33777E+04
Link 10	54681E+02	.29262E+02	.31403E+01 ·			37099E+01	13052E+04		17299E+04
	60810E+02	.29653E+02							
			.30195E+01 -			.46583E+01		63247E+05	.28398E+04
Link 12	66935E+02		*.31275E+01 ·			43339E+01	.36436E+05		85583E+04
Link 13	72989E+02	.30663E+02	.291036+01 -			.12615€+02		36832E+06	. 19625E+05
Link 14	.78674E+02		· .26723E+01				.23406E+06	.27698E+06	.75988E+04
Link 15	83104E+02		21945E+01 -			.94401E+01		17477E+06	.11026E+05
Link 16	.84298E+02		13968E+01 -			.95291E+01	.43932E+04	.14873E+06	.13585E+05
Link 17	81898E+02		91029E+00 -				36637E+06		. 15601E+05
Link 18	.77064E+02	.123956+02	19957E+00 -	.11/5/E+UZ	·. 17342E+03		11824E+06		.56350E+04
Link 19	·.71361E+02		43058E+00 -			.18057E+01		33644E+05	.65621E+04
Link 20	65826E+02		39324E+00 -					70717E+05	
Link 21	60304E+02		44388E+00 ·			.39816€+00	.44266E+04	.11435E+06	.36719E+04
Link 22	55008E+02			.328496+01	.24360E+02		18502E+05	.10901E+05	.20588E+05
Link 23	49413E+02		24825E-01	.66134E+01	.61852E+02	.320986+01		13491E+06	.30965E+04
Link 24	.43357E+02	.12468E+01		.47626E+01		54090E+01	.49748E+04		86501E+04
Link 25	37302E+02			.59116E+01	.314386+02	.43957E+00		16201E+05	
Link 26	31244E+02	.12387E+01		.57355E+01		19647E+01	.52530E+04		35945E+04
Link 27	-,2518ZE+02			.49283E+01	.10750E+02	.41734E+00	.49579E+04	.59483E+03	.91652E+03
Link 28	19114E+0Z	.12439E+01	.21376E-02	.36637E+01	.16880E+02	.82106E+00		30073E+04	. 13552E+04
Link 29	13044E+02		23655E-02	.17705E+01	.23147E+02	. 15602E+00	.93975E+03	.92013E+04	.39516E+03
Link 30	69735E+01	.12480E+01	.34174E-02 -			46261E+00			12293E+04
Link 31	90414E+00		34364E-02 -		.13625E+02		72054E+04	.86334E+04	.212686+03
Link 32	.51635€+01	.12499E+01	.39231E-02 -		. 18255E+02		·.76432E+04		.99084E+03
Link 33	.11228E+02		65574E-02 -		.28249E+02		69641E+04	.32865E+05	.80904E+03
Link 34	. 17290E+02	.12576E+01	.10717E-01 -		.24059E+02	.33809€+00	76615E+04	27066E+05	51989E+03
Link 35	.23349E+02		22258E-01 -		.23192E+02		10559E+05	. 19912E+05	. 12480E+04
Link 36	. 29407E+02	.12678E+01	.36015E-01	.29702E+01	.24068E+02	+.13548E+01	45135E+04	544 <i>7</i> 3E+05	12272E+04
Link 37	.35461E+02	.12213E+01	47829E-01	.56901E+01	.50595E+02	.13332E+01	. 19723E+04	. 16401E+06	.49568E+04
Link 38	.41511E+02	.13060E+01	.66245E-01	.30269E+01	.64920E+02	.15786E+01	25648E+04	82782E+05	.38927E+04
Link 39	.47544E+02	.11572E+01	11573E+00 -	.11201E+02	.81335E+02		36443E+05	.61065E+05	.23227E+04
Link 40	.53496E+02	. 15042E+01	.23360E+00 ·			36392E+01		15132E+06	
Link 41	.59265E+02	.32744E+01	.37222E+00 -			26578E+01			31153E+04
Link 42	.65102E+02	.46837E+01	.91802E-01	.14541E+01	.47992E+02	.39875E+01		. 13870£+06	.50916E+04

C-14

Displacements, Velocities, and Accelerations										
		X	Y	Theta	X-Vel	Y-Vel	Omega	X-Accel	Y-Accel	Alpha
Link	43	.709656+02	.596196+01	.34386E+00	. 60075E+01		22239E+01			66310E+04
Link	44	.768356+02	.703016+01	.17114E-01	· , 16442E+02	. 176206+02			28305E+07	
Link	45	.81722E+02	.96008E+01	.89673E+00	11771E+03	.26677E+03	.20054E+02	69224E+05	27646E+06	.29881E+05
Link	46	.83827E+02	.15008E+02	.14894E+01	21742E+03	.19242E+03	.15284E+02	57331E+05	22151E+04	.25308E+05
Link	47	.825386+02	.20713E+02			34929E+02		65408E+05		.29243E+05
Link	48	.7E176E+02	.24458E+02		·.34872E+03			18271E+05	.45635E+05	
Link	49	.72267E+02	.25153E+02				14674E+02			
Link	50	.66175E+02	.25148E+02					13220E+05	.22495€+06	.35229€+04
Link	51	.60062E+02	.25348E+02	30389E+01			90587E+01		14447E+06	
Link		.54005E+02	.25752E+02		28612E+03	.81621E+01	.10734E+02		6482ZE+05	. 18220E+05
Link		.47947E+02		30623E+01			38470€+01		.28181E+06	
Link	54	.41825E+02		30123E+01			84439E+01		23313E+06	
Link		.35727E+02	.25594E+02		28216E+03	.10257E+02		.37369E+05	.11328E+06	
Link		.29623E+02		30790E+01			45550E+01	.10835E+06	.10144E+06	
Link		.23616E+02	.263596+02		14329E+03		.87857E+01		57291E+05	
Link		.17678E+02		31057E+01		.48634E+01	.63260E+00		23271E+05	
Link	59	.11629E+02		30995E+01		.23930E+01	.197478+00	.20858E+06		
Link		.54549E+01					57034E+00		22438E+04	
CIVIE	-	.363476701	.200102	.314036401	·.23039E+03	300306+01	*.370346+00	.90/496403	224306+04	*. 1000yE*03
force	s and	Noments								
		FX	FY	H	FX-End 1	FY-End 1	fX-End 2	FY-End 2	M-End 1	M-End 2
Vehic	le	.79514E+04	.33749E+06	. 14226E+06						
Wheel			13377E+06	.00000E+0G						
Wheel		42383E+03	.30269E+04	.00000E+G0						
Uhesi		34971E+02		.00000E+00						
Uheel		55435E+02	.26785E+03	.00000E+00						
Wheel		67658E+04	.80610E+03	.00000E+00						
Wheel		.61141E+03	.47328E+04	.00000E+00						
uheel		44344E+05	.224295+04	.00000E+00						
Link	1		20093E+02		+.83137E+04	15476E+02	.94544E+04	.39356E+02	.69492E+02	19738E+02
Link	ż		20093E+02			39356E+02		30042E+03		36097E+01
Link	š		·.20093E+02		85674E+04	.30042E+03		-,42095E+03	.36097E+01	.84594E+02
Link	ĭ		20093E+02		31993E+04		88091E+04			.78043E+02
Link	Š		20093E+02	.00000E+00	.88091E+04		31921E+04		78043E+02	
Link	á		20093E+02	.00000E+00			14749E+05	.585888+03	.17980E+03	.12460E+03
ink	7		20093E+02	.00000E+00			20207E+05		12460E+03	
Link	8		20093E+02	.000000E+00			21176E+05	.34543E+04	.21102E+03	.23475E+03
Link	ē		20093E+02	.00000E+00			21244E+05			
Link	10		20093E+02	.00000E+00			21176E+05	.30562€+04	.29670E+03	.41815E+03
Link	11		20093E+02	.00000€+00			20669E+05			
Link	12		20093E+02	.00000E+00	.20669E+05		18775E+05	.60735E+04	.43504E+93	.84527E+03
Link	13		20093E+02	.00000E+00			12501E+05			.15149E+03
Link	14		20093E+02	.00000E+00			32975E+03		15149E+03	.22268E+04
Link	15		20093E+02	.00000E+00		13640E+04		77042E+04		.17941E+04
Link	16		20093E+02		54537E+04	.77042E+04	.568215+04		17941E+04	.13948E+04
		20735E+05				50080E+02				
Link	17				73655E+04				13948E+04	.92343E+03
Link	18	38917E+04					.51088E+04		92343E+03	
Link	19		20093E+02		51088E+04			85800E+03		
Link	20		20093E+02		53398E+04	.85800E+03			.1292ZE+03	
Link	21		20093E+02		57887E+04	.45152E+04	.60189E+04	.14509E+04	.16404E+02	.78446E+03
Link	22	23461E+04			60189E+04		.74029E+04		78446E+03	.38563E+03
Link	/3	. UKRAKRE+()()	.55275E+04		- 74029E+04	* . / \$1U \$E +O4	016 MF+06	· >/ 5/ 3/ 3E+04	38563F+03	*.351100+035

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00000E+00 98035e-04
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00000E+00 97153E-04
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-.88025E+04
-.90917E+04
-.93648E+04
-.96277E+04
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.18000E+02
.40601E+02
.90447E+02
.64821E+02
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.53116E+03
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.52323E+04
.14100E+03
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.71362E+03
.89410E+03
.14777E+03
.73487E+02
.89005E+03
.97063E+03
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.94545E+04
.85727E+04
.32269E+04
.88097E+04
.33357E+04
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.11055E-03 -.6753ZE-01
.28111E-03 -.61196E-01
-.21458E-02 -.2285ZE-01
-.30068E-02 -.629ZZE-01
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-.28111E-03
.21458E-02
.30068E-02
.68893E-03
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.67532E-01
.61234E-01
.23049E-01
.62926E-01
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.59383E-01
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.59383E-01
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.15181E-02
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Link	Offsets and	Tension Data										
L	Longth	Tension-1	Tension-2	Del X1	Det 11	Dei X2	Del Y2	Del 1	Del 2			
13	.60000E+01	. 19733E+05		13411E+00		.892938-01	.93279€-01	.14095E+00	.12913E+00	•		
14	.60000E+01	. 18078£+05			93279€-01	.23554E-02			.10023E-01			
15	.60000E+01	. 14033E+04	.94391E+04	23554E-02	.97427E-02	38955E-01	.55030€-01	. 10023E-01	.67422E-01			
16	.60000€+01	.94391E+04	.56823E+04	.38955E-01	55030€-01	40587E-01	35 <i>7</i> 71E-03	.67422E-01	.40588E-01			
17	.60000€+01	.5 6823E+0 4	.74646€+04	.40587E-01		52611E-01		.40588E-01	.53319E-01	Wheel	1	
18	.60000E+01	.74646E+04	.51825E+04	.52611E-01	.86604E-02	36491E-01	62243E-02	.53319E-01	.37018E-01	Wheel	1	
19	.60000E+01	.51825E+04	.54083E+04	.36491E-01		38142E-01	.61286E-02	.37018E-01	.38631E-01			
20	.60000€+01	,54083E+04	.73414E+04		61286E-02		.32251E-01	.35631E-01	.52438E-01			
21	.60000E+01	. 73414E+04	.61913E+04			42992E-01		.5243 8E -01	.44223E-01			
22	.60000€+01	.61913E+04	.10404E+05	.42992E-01		52878E-01		.44223E-01	.74314E-01	Wheel		
23	.600000€+01	.10404E+05	.10019E+05	.52878E-01	.52217E-01	61027E-01	.37374E-01	.74314E-01	.71562E-01	Ground		
24	.60000€+01	.10019E+05	.88036E+04	.61027E-01	37374E-01	62875E-01	.10072E-02	.71562E-01	.628838-01	Ground		
25	10+30000à.	.88036E+04	.91426E+04	.62875E-01	10072£-02	64941E-01	.68811E-02	.62 6836 -01	.65304E-01			
26	.60000E+01	.91426E+04	.93920E+04	.64941E-01	68811E-02	66892E-01	.50973E-02	.65304E-01	.67086E-01	Ground		
27	.60000€+01	.93920E+04	.96691E+04			68769E-01		.67086E-01	.69065E-01	Uheel	3	
28	.60000E+01	.96691E+04	.97845E+04	.68769E-01		69882E-01		.69065E-01	.69 890E- 01	Ground		
29	.60000€+01	.97845E+04	.98326E+04	.69 682 E-01	. 10555E-02	70231E-01	52491E-03	.49890E-01	.70233E-01	Ground		
30	.60000E+01	.98326E+04	.97560E+04	.70231E-01	.52491E-03	69395E-01	.63575E+02	.70233E-01	.69686E-01	Ground		
31	.60000E+01	.97560E+04	.95276E+04	.69395E-01	63575E-02	67700E-01	69331E-02	.69686E-01	.68055E-01	Ground	and Wheel	4
32	.60000E+01	.95276E+04	.90825E+04	.67700E-01	.69331E-02	64862E-01	.13201E-02	.68055E-01	.64875E-01	Ground		
33	.60000E+01	.90825E+04	.87402E+04	.64862E-01	·.13201E-02	62275E-01	44006E-02	.64875E-01	.62430E-01	Ground		
34	.60000E+01	.5740ZE+04	.83558E+04	.62275E-01	.44006E-02	59429E-01	.55090E-02	.62430E-01	.59684E-01			
35	.60000E+01	.83558E+04	.86351E+04	.59429E-01	55090€-02	61011E-01	90569E-02	.59684E-01	.61680E-01	Ground	and Wheel	5
36	.60000E+01	.86351E+04	.84492E+04	.61011E-01	.90569€-02	59335€-01	.11032E-01	.61680E-01	.60352E-01			
37	.60000E+01	.84492E+04	.93720E+04	.59335E-01	11032E-01	60067E-01	29552E-01	.6035ZE-01	.66943E-01	Ground		
38	,60000€+01	.93720E+04	.82773E+04	.60067E-01	. 295528-01	59114E-01	.10521E-02	.66943E-01	.591248-01			
39	.60000€+01	.82773E+04	.74823E+04	.59114E-01	10521E-02	53434E-01	.10706E-02	.59124E-01	.53445E-01	Ground	and Wheel	6
40	.60000E+01	.74823E+04	.82078E+04	.53434E-01	10706E-02	56613E-01	. 15235E-01	.53445E-01	.58627E-01	Uheel	6	
41	.60000E+01	.82078£+04	.97649€+04			54759E-01		.58627E-01	.69749E-01			
42	.60000E+01	.97649E+04	. 73087E+04	.54759E-01		51562E-01	.81706E-02	.69749E-01	.52205E-01			
43	.60000€+01	.73087E+04	.64720E+04			45900E-01		.52205E-01	.46229E-01			
44	.60000€+01	.64720E+04	.24653E+05	.45900E-01		14713E-01		.46229E-01	.17610E+00	Meet	7	
45	.60000E+01	.24653E+05	.103274+05	.14713E-01		.10 999E -01		.17610E+00	.73761E-01		_	
44	.60000E+01	. 10327E+05		10999€-01		.10366E+00		.73761E-01	.12982E+00	Wheel	7	
47	.60000E+01	. 18175E+05		10366E+00		.12795E+00		.12982E+00	.13457E+00			
48		. 18839E+05		12795E+00				.13457E+00	.14700E+00			
49	.60000E+01	.20580E+05		13474E+00		.15814E+00		.14700E+00	.16075E+00			
50	.60000€+01	.22504E+05			28839E-01	.143058+00		.16075E+00	.17203E+00			
51	.60000€+01	.24084E+05		16305E+00		.15744E+00		.17203E+00	.15745E+00			
52		.22042E+05		15744E+00		.15351E+00	.22594E-01	.15745E+00	.15517E+00			
53	.60000E+01				22594E-01	.15669€+00		.15517E+00	.16272E+00	Meet	٥	
54	.60000E+01			15669E+00		.14989E+00	.42569E-01	.16272E+00	.15582E+00			
55	.60000E+01	.21815E+05			42569E-01	.13601E+00	.35130E-03	.15582E+00	.13601E+00		-	
56	.60000E+01				35130E-03	.99461E-01		.13601E+00	.10288E+00	Wheel	5	
57	.60000E+01			-,99461E-01		.25155E-01		.10288E+00	.25681E-01			
58	.60000E+01			25155E-01			.33263E-02	.25681E-01	.54125E-01			
59	.60000€+01					23448E-01		.54125E-01	.23462E-01			
60	.60000E+01	.32847E+04	.83137E+04	.23448E-01	.80045E-03	59383E-01	11055E-03	.23462E-01	.59383E-01			

Cyc Time Time-Step DM-RPH 11 0011 0001000 2.500 12 0012 0001000 2.500

OUTOUT	File	- PI	-	15

TRV. Tre	cked Veh	ícle Dynamics	· Version	1.00
13	.0013	.0001000	2.500	
14	.0014	.0001000	2.500	
15	.0015	.0001000	2.500	
16	.0016	.0001000	2.500	
17	.0017	.0001000	2.500 .	
18	.0018	.0001000	2.500	
19	.0019	.0001000	2.500	
20	0020	.0001000	2.500	

SEERCECCO DIVISION MALECICO DIVININO DISCOSSO PINSONINO NADIONISTO PERIODES DESIGNAS DANS

TRY, Tracked Vehicle Dynamics - Version 1.00

OUTPUT AT TIME . DO

Displace	ments, Velociti	ies, and Acce	lerations						
·	· x	· Y	 Thets 	x-vet	Y-Yel	, Omega	X-Accel	Y-Accal	Alpha
Vehicle	·.28993E+00	.2402BE+02	.26618E-05	·.14460E+03	.26299€+02	.26825E-02	.51143E+03	.11214E+05	.77350E+00
Uheel 1	·.74982E+02	.20757E+02	.314166-01	. 190206+03	42090E+03	.15708E+02	.77192E+05	47000E+05	.000000E+00
Wheel 2	50011E+02	.14417E+02	.22792€-01	15796E+03	.41239E+02	.11396E+02	.11616E+05	.57621E+05	.00000E+00
Wheel 3	25286E+02	.14023E+02	.22792E-01	14602E+03	88501E+01	.11396E+02	44410E+03	.12457E+05	.00000E+00
Wheel 4	27082E+00	.13939E+02	.22792E-01	14656E+03	.15019E+01	.11596E+02	.32294€+03	. 18560E+05	.00000E+00
Wheel 5	.25387E+02	.137246+02	.22792E-01	25675E+03	.27954E+02		36821E+05	.539396+05	.00000E+00
Uheel 6	.49663E+02	. 13670E+02	.22792E-01	131948+03	.67525E+02			.55539E+05	.00000E+00
Wheel 7	.744728+02	.152738+02	.31416E-01	32043E+03	46120E+03	.15708E+02	15584E+06	.88944E+05	.00000E+00
Link 1	·.54102E+00	.26700E+02		22797E+03			.654748+05	.11459E+04	.86307E+03
Link 2	653656+01	.26929E+02		35351E+03		76726E+00		.76164E+04	.26924E+03
Link 3	12553E+02	.27248E+02		47321E+03		11301E+00			29393E+03
Link 4	18605E+02	.27607E+02		49079E+03	.16001E+02		.79277E+05		11848£+04
Link 5	·.24632E+02	.27806E+02		45547E+03		12633E+01		16233E+05	
Link 6	·.30680E+02	.27894E+02		48671E+03		18161E+01	.72587E+05		67199E+02
Link 7	36689E+02	.28237E+02		47615E+03	.20880E+02				77690E+03
Link 8	42740E+02	.28582E+02		38067E+03		39022E+01			.52864E+03
Link 9	48843E+02	.28947E+02		31394E+03	49121E+01			.58299E+05	.16023E+04
Link 10	54968E+02	.29284E+02		28237E+03		57213E+01			
Link 11	61083E+02	.29652E+02		·.24455E+03	.16645E+02				.25910E+04
Link 12	67164E+02					45786E+01		12320E+06	.60726E+04
Link 13	73140E+02					.24270E+02		.17230E+06	.25629E+04
Link 14	78763E+02			11606E+03				20883E+06	
Link 15	83211E+02			10357E+03				.963748+05	
Link 16	84482E+02					78550€+01			
Link 17	82179E+02			63771E+02				95271E+06	
Link 18	77076E+02			11258E+02				10039E+07	
Link 19	71364E+32			43637E+01				-,27899E+06	.40814E+05
Link 20	65826E+02		39175E+00		11507E+03			98021E+05	.17532E+05
Link 21	·.60317E+02			25976E+02				12909E+06	.16264E+04
Link 22	55015E+02			81326E+01				56686E+05	.27062E+04
Link 23	49392E+02			.290596+02	.31845E+02			.52295E+05	.59113E+04
Link 24	43345E+02			.20314E+02		95319€+01		65328E+05	.79195E+03
Link 25	·.37293E+02		51012E-01	.13104E+02		17184E+01		.10535E+05	
Link 26	- 31236E+02	.12591E+01		.10409E+02		57978E+01		- 12627E+05	
Link 27	25174E+02			.902896+01				21769E+05	
Link 28	+.19109E+02		.37713E-02	.55480E+01	.70827E+01			11363E+05	.12736E+04
Link 29	13042E+02	.12625E+01		.76499E+00	.11783E+02			14791E+05	
Link 30				52157E+01		22872E+01			
Link 31	91291E+00			10747E+02				23488E+05	.1927ZE+03
Link 32		.12617E+01		. 13833E+02	.79782E+01			12239E+05	.25590E+04
Link 33				14778E+02	.13219E+02			28929€+05	
	.17277E+02	.12723E+01		15395E+02		18958E+01			
Link 35	.23338E+02			14329E+02				29131E+05	.14047E+04
Link 36		.12893E+01		94576E+01	.285356+02		17377E+05	.72813E+04	.68352E+04
Link 37				70543E+01	.40401E+02			93435E+05	.231726+04
Link 38		.13475E+01		15333E+02		33267E-01			
Link 39				14475E+02				31698E+05	
Link 40				65362E+01		84806E+01		.849996+05	.13354E+04
Link 41	.59265E+02	.33175E+01	.36833E+00	.25532E+01		52000E+01			

	FUGRE	na venticie byn		110h 1.00						output Fite	
Displ	acem	ınts, Velociti	es, and Acce								
		X	Υ .	Theta				X-Accel	Y-Accel	Algha	
Link	43	.70997E+02	.57895E+01	.31946E+00			53047E+02		44377E+06		
Link	44	. <i>76</i> 938€+02	.66316€+01			29887E+03			18205E+07	.41300E+04	
Link	45	.81672E+02	.95057E+01	.94437E+00	.39957E+02	38911E+03	.73483E+02	.13949€+06	35419E+06	.51061E+05	
Link	46	.83607E+02	. 150 99E+ 02	. 15175E+01	21306E+03	·.63395E+02	.36970E+02	29811E+05	43729E+06	.150986+05	
Link	47	.82187E+02	.20697E+02	.20962E+01	33715E+03	.11352E+02	.41399E+02	.23340€+05	.93491E+04	.21300E+05	
Link	48	.77810E+02	.24361E+02	.27808E+01	39047E+03	93747E+02	.49953E+01	69879E+05	24905E+05	.89708E+04	
Link		.71932E+02					29747E+02			12983E+05	
Link		.65873E+02	.25178E+02		32533E+03		.66765E+01				
Link		.59781E+02					20044E+02				
Link		.537238+02	.257645+02				.18631E+02			.50408E+03	
Link		.47659E+02					90972E+01				
Link		.41555E+02					87279E+01			.25861E+04	
Link		.354918+02	,256438+02				.13606E+02			.37444E+04	
Link		.29461E+02			10651E+03		79729E+01		14732E+05	.50780E+04	
		.235238+02	.26359€+02				.88598E+01			.38811E+04	
Link											
Link		.17560E+02				28595E+02			89726E+03		
Link		.11532E+02					66688E+00				
Link	80	.54801E+01	.∠00U5E+0Z	.314UUR+01	11/1YE+03	(80802+01	.73897E-Q1	.8/601E+05	142ZDE+04	.72516E+03	
Focce	s and	i Maments									
		FX	FY	M	FX-End 1	FY-End 1	FX-End 2	fy-End 2	M-End 1	M-End 2	
Vehic	ie	. 13236E+05	.29021E+06	.99008E+05							
uneet	1	.23930E+05	14570E+05	.00000E+00							
Uheel	2	.13475E+04	.66840€+04	.000000E+00							
wheel	3	51516E+02	.14451E+04	.00000E+00				•			
Uheel	4	.37461E+02	.215298+04	.000000€+00							
Uheel	5	42712E+04	.62570E+04	.00000E+00							
wheel	6	.17117E+04	.64425E+04	.000000€+00							
Wheel	7	48309E+05	.27573E+05	.00000E+00							
Link	1	.000000€+00	·.20093E+02	.00000€+00	.31443E+04	.28655E+03	.26040E+03	20687E+03	.12231E+03	·.48478E+02	
Link	2	.00000E+00	20093E+02	.00000E+00	26040E+03	.20687E+03	37975E+04	.20927E+03	.48478E+02	.26653E+02	
Link	3	.00000€+00	20093E+02	.00000E+00	.37975E+04	20927E+03	86832E+04	.74826E+03	26653E+02	.67718E+0Z	
Link	Ä	.000000€+00	20093E+02	.000000E+00	.86832E+04	74826E+03	45609E+04	.82413E+03	67718E+02	43402E+02	
Link	5		20093E+02	.000000€+00			68456E+04		.43402E+02		
Link	6	.00000€+00	20093E+02	.00000E+00		10558E+00		.38970E+03		.24661E+03	
Link	7		20093E+02	.000000E+00			89635E+04		24661E+03		
Link	8		20093E+02	.00000€+00			16558E+05			.58053E+03	
Link	ě		20093E+02	.00000E+00	. 165586+05		19696E+05				
Link			20093E+02	.000000E+00			18913E+05	.219086+03		.72847E+03	
Link	11		20093E+02	.00000E+00			14293E+05		72847E+03		
Link			20093E+02	.000000€+00			58964E+04				
Link	13		20093E+02	.000000€+00	.58964E+04		17275E+04		18839E+04		
Link			20093E+02	,00000€+00			64255E+04		.43778E+03	.17318E+04	
Link			20093E+02	,0000000	.64255E+04		11326E+05				
	16		20093E+02	.00000€+00	.11326E+05		14647E+05			.23640E+04	
Link		14220E+05		.000000€+00	.14647E+05		.40283E+05			.12010E+04	
		28475E+05			40283E+05		.34359E+04			.17077E+04	
Link											
Link			20093E+02				.31320E+04		17077E+04		
Link			20093E+02				.32027E+04	.24989E+04			
Link	21		·.20093E+02				.17592E+04			.14326E+04	
Link	ZZ	- 40023E+04	93124E+04		17592E+04	41938E+04	.64378E+04		14326E+04		

.23267E+03

-.31443E+04

.36688E+02

-.12231E+03

TRV, Tracked Vehicle Dynamics - Version 1.00

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KONSON KONGOS - BOSSES

ASSESSED 1 1997 255-5-5-5

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Output file - Page

Link	Offsets and	Tension Data							
L	Length	Tension-1	Tension-2	Del X1	Del Y1	Del X2	Del YZ	Det 1	Del 2
1	.600006+01	.31573E+04	.33257E+03	22459E-01	20468E-02	18600E-02	.14776E-02	.22552E-01	.23755E-02
2	.60000E+01	.33257E+03	.38032E+04	.18600E-02	14776E-02	.27125E-01	14948E-02	.23755€-02	.27166E-01
3	.60000E+01	.38032E+04	.87154E+04	·.27125E-01	.14948E-02	.62023E-01	53447E-02	.27166E-01	.62253E-01
4	.60000E+01	.87154E+04	.46347E+04	·.62023E-01	.53447E-02	.32578E-01	58867E-02	.62253E-01	.33105E-01
5	.60000E+Q1	.46347E+04	.68456E+04	32578E-01	.58867E-02	.48897E-01	75415E-06	.33105E-01	.48897E-01
6	.60000E+01	.66456E+04	.30957E+04	48897E-01	.75415E-06	.21936E-01	27836E-02	.48897E-01	.22112E-01
7	.60000E+01	.30957E+04	.90213E+04	21936E-01	.27836E-02	.64025E-01	72803E-02	.22112E-01	.64438E-01
8	.60000E+01	.90213E+04	.16565E+05	64025E-01	.72803E-02	.11827E+00	.34057E-02	.64438E-01	.11832E+00
9	.60000E+01	.16565E+05	.19864E+05	11827E+00	34057E-62	.14069E+00	18392E-01	.11832E+00	.14188E+00
10	.60000E+01	.19864E+05	.18914E+05	14069E+00	. 18392E-01	.13509E+00	15649E-02	.14158E+00	.13510E+00
11	.60000E+01	.18914E+05	.14361E+05	13509E+00	.15649E-02	.10209E+00	99869E-02	.13510E+00	.10258E+00
12	.600000€+01	.14361E+05	.77232E+04	10209E+00	.99869E-02	.42117E-01	.35628E-01	.10258E+00	.55165E-01

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Output file

TRV, Tracked Vehicle Dynamics -

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.0021

.0001000

Version 1.00

DW-RPF

2.500

C-22

Output File - Page 20

TRV, Tre	cked Veh	icle Dynamics	- Version 1.0	ю
23	.0023	.0001000	2.500	
24	.0024	.0001000	2.500	
25	.0025	.0001000	2,500 .	
26	.0026	.0001000	2,500	
27		.0001000	2.500	
28		.0001000	2,500	
29		.0001000	2,500	
30		.0001000	2.500	

TRY, Tracked Vehicle Dynamics - Version 1.00

OUTPUT AT TIME .0030

0 i sol acom	ents, Velociti	es, and Acce	teretions						
	X	Y		x-Vel	Y-Vel	Omega	X-Accel	Y-Accel	Alpho
Vehicle	·.43424E+00	.24059€+02	.54720E-05	14397E+03	.36751E+02	.23567E-02	.78370E+03	.949206+04	29147E+01
Wheel 1	74734E+02	.20380€+02	.47124E-01	.29592E+03	-,34171E+03	.15700€+02	.236582+05	.90127E+04	.00000E+00
uneel 2	5016SE+02	. 14483E+02	.34188E-01	15196E+03	.85133E+02	.11396€+02	·.31623E+04	.21429E+05	.000000€+00
Wheel 3	·.25432E+02	.14020€+02	.34188E-01	14647E+03	.14353E+01	.113966+02	·.34624E+03	.36543E+04	.00000€+00
Wheel 4	41730€+00	. 13948E+02	.341686-01	14649E+03	.15778E+02	.11396E+02	29096E+03	.65216E+04	.000000E+00
Wheel 5	.25113E+02	.137778+02	.34188E-01	28668E+03	.73327E+02	.113966+02	24681E+05	. 15612E+05	.00000€+00
Wheet 6	.49538£+02	.13736E+02	.341886-01	12065E+03	.36960€+02	.11396€+02	.54451E+04	89654E+05	.000000€+00
Wheel 7	.740 99E +02	.14812E+0Z	.47124E-01	39557E+03	50718E+03	.15708E+02	11504E+05	11749E+06	.000000€+00
Link 1	76235E+00	.26799E+02	.31115E+01	24186E+03	.11149E+01	.14005E+00	89637E+05	.30998E+04	.27077E+02
Link 2	·.69035E+01	.26937E+02	.30942E+01	35455E+03	.10529E+02	182988+00	.81698E+05	.239638+04	.518178+03
Link 3	13010E+02	.27262E+02	.30823E+01	40755E+03	.13579€+02	30078E+00	.15019E+06	66724E+04	.41177E+03
Link 4	19060E+02	.27618E+02	.30632E+01	43877E+03	.45286£+01	.31830€+00	. 197848+05	93837E+04	.68336E+03
Link 5	25107E+02	.27816E+02	.31341E+01	47236E+03	.95733E+01	17032E+01	.43309E+05	.66383E+04	30745E+03
Link 6	31142E+02	.27917E+0Z	.31162E+01	46101E+03	.23817E+02	20957E+01	25899E+05	33710E+04	14266E+03
Link 7	37176E+02	.28255E+02	.30545E+01	47052E+03	. 13263E+02	.30466E+01	.56264E+05	45240E+04	.84031E+03
Link 8	43188E+02	.28594E+02		47911E+03		38301E+01			66416E+03
Link 9	4920ZE+02	.28965E+02	.30469E+01	39632E+03	.13589E+02	.57120E+01	60813E+05	30287E+05	28719E+03
Link 10	55240E+02	.29284E+02	.31289E+01	· .26287E+03		69227E+01	.16791E+05	.10523E+05	.15282E+04
Link 11	61267E+02	.29648E+02	.30333E+01	13837E+03	26248E+02	.98363E+01	.73176E+05	26474E+05	.18983E+04
Link 12	67267E+02	.29946E+02			63855E+01				20616E+04
Link 13	73237E+02	.30509E+02			67388E+02		69677E+05		.42923E+03
Link 14	78913E+02	.296988+02			·.15780E+03		.17634E+04		47410E+04
Link 15	833686+02				13571E+03			11168E+06	
Link 16	84597E+02		14076E+01		11818E+03		.28146E+06	.55451E+05	.23453E+05
Link 17	82120E+02		89609E+00		11105E+03			13878E+07	
Link 18	77086E+02				23500E+03				
Link 19	71379E+02				36211E+03		36578E+05	.53956E+05	.64445E+04
Link 20	·.65823E+02	.78524E+01			26293E+03	.24280€+02		- 89729E+05	.89102E+04
Link 21	·.60338E+02	.55055E+01	43619E+00	56871E+00	20267E+03	.40418E+01	.70984E+05	90573E+05	14815E+03
Link 22	55005E+02	.27514E+01	51253E+00	.28650E+02	56854E+02	.252286+02	.48198E+05	33705E+05	, 18380E+04
Link 23	·.49356E+02	.12640E+01	90772E-02	.44904E+02	.37301E+02	.118786+02	.27518E+05	25212E+05	.20153E+04
Link 24	43314E+0Z	.13530E+01	.38147E-01	.38188E+02	.40207E+02	65947E+01	.13055E+05	. 262626+05	.27977E+04
Link 25	37271E+02	.13217E+01	52495E-01	.29690E+02	. 16031E+02	47639E+00	.172802+05	304206+05	.31568E+04
Link 26	·.31222E+02	. 12673E+01	.34173E-01	.19144E+02	84981E+00	89737E+01	. 12565€+05	219586+05	16329E+04
Link 27	25164E+02	.12956E+01	22258E-01	.11499E+02	16440E+02	.37458E+00	.32038E+04	903298+04	.37761E+02
Link 28	19104E+02	.125446+01	.66215€-02	.44617E+01	86167E+01	.32560€+01	18058E+04	150418+05	.77078E+03
Link 29	13043E+02	.12681E+01	21837E-02	22979E+01	.15536E+01	26601E+00	21553E+04	·.79412E+04	38634E+03
Link 30	69636E+01	.12546E+01	-,14919E-02	74326E+01	10227E+02	-,43478E+01	.43056E+03	81695E+04	11887E+04
Link 31	92379E+00	.12360E+01	29169E-02	10408E+02	10457E+02	.35589E+00	. 18873E+04	.31870€+02	15286E+03
Link 32	.51373E+01	.12579E+01	.87354E-02	13651E+02	13565E+02	.39166E+01	.14119E+04	16247E+05	.49806E+02
Link 33	.11199E+02	.12668E+01	52617E-02				89491E+02	87135E+04	11380E+04
Link 34	. 17261E+02	.12643E+01	.59543E-02	17041E+02	18367E+02				
Link 35	.23322E+02				71130E+01		57119E+04		.42065E+03
Link 36	.29384E+02	.12962E+01			-,19800E+02		16563E+05		13803E+04
Link 37	.35439E+02				14938E+01		14109E+05	.97323E+04	
Link 38	.41486E+02	.13638E+01		21261E+02		79519E+01			32212E+04
Link 39	.47514E+02		10930E+00		.46645E+02		27986E+05		.46214E+04
Link 40	.53475E+02	.15636E+01		22954E+02		81603E+01		.11684E+06	
Link 41	.59269E+02	.323818+01	.35636E+00		12979E+03			57113E+05	
Link 42	45130F+02	.44533F+01			- 26520F+03			36968F+05	

.26010E+04

.64006E+05 .43377E+04

-.71635E+04 --.25177E+04 .21720E+04 -.15416E+04

32077E+05

.26634E+04 .45655E+04

36711E+04

.20113E+02 .47732E+04 .62041E+04

-.11613E+04

.19172E+04

.22561E+04 .82419E+04

.25233E+04

.18039E+04 .15727E+04 -.15727E+04 .29054E+02 -.29054E+02 -.14146E+04

22561E+04

.82419E+04 .25233E+04

-.18039E+04 .15727E+04 .29054E+02

64006E+05

.43377E+04 .71635E+04

.25177E+04

.21720E+04 .15416E+04 .25072E+03

.20093E+02

15097E+05

.31638E+05 .00000E+00 .00000E+00

.00000E+00 .22468E+04 .00000E+00

.10761E+05 .11699E+06 .20093E+02

.20093E+02

-.20093E+02 -.54664E+04 -.20093E+02

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.32077E+05 .26634E+04 .45655E+04 .36711E+04 .20113E+02

.00000E+00 .36711E+04 .00000E+00 -.20113E+02 .00000E+00 -.47732E+04

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R	Tracked Vehicle Dynamics - Version 1.00 Qutput file - P
Force Link Link Link Link Link	FX FY M FX-End 1 FY-End 2 FY-End 2 M-End 1 M-End 2
Link Link	25 - ,00000ë+00 -,20093ë+02 -,00000ë+00 -,68830ë+04 -,16365ë+04 -,74736ë+02 -,30052ë+03 -,50522ë+03
Link Link	27 .48686;02 -232582+04 .00000+00 -385369;04 .104709+04 .355282+04 .809036+03 -342999+03 .301846+03 .301846+03 .301846+03 .309000+00 -200936+02 .00000+00 -355282+04 .809036+03 .845896+04 .469916+02 -301846+03 .309606+03
Ļink Link	30 .00000E+0020093E+02 .00000E+0083469E+04 .34586E+03 .83692E+0475058E+03 .33439E+03 .38393E+03
Link Link	32 .00000E+0020093E+02 .00000E+0085767E+0461574E+03 .86501E+0420899E+0331916E+0334503E+03
S Link	E0+3E866. E0+3S854. 40+374761 +0+86168. E0+300246. 40+362681 00+300000. \$0+3E902 00+3000000.
Link Link	36 .00000E+0020093E+02 .00000E+0092132E+0414279E+04 .83519E+0414687E+0433763E+0327276E+03
Eink Link	\$69696, \$694006. \$6941275, \$69206570, \$69438490, \$6942466. \$6940000, \$6940000, \$6940000, \$69400000, \$69400000,
Link Link	40 .00000E+0020093E+02 .00000E+0070365E+0428108E+04 .75042E+04 .27414E+04 .27414E+0367404E+03
Link Link	42 .00000E+0020093E+02 .00000E+0079921E+04 .61946E+04 .10212E+0580968E+04 .20955E+0446762E+04
	44 .29412E+0583410E+05 .00000E+0011602E+0530031E+04 .13938E+05 .12372E+0410970E+05 .61488E+04
Link Link Link	46 .00000E+0020093E+02 .00000E+0097499E+0420131E+05 .26317E+04 .26757E+05 .30962E+04 .12747E+04
Çi Link Çi	48 .00000E+0020093E+02 .00000E+00 .31273E+0499115E+0454757E+04 .16760E+04 .86861E+0322208E+04
Link Link	50 .00000E+0020093E+02 .00000E+00 .86414E+04 .37939E+0411276E+05 .19791E+0428026E+0422913E+04
Link Link Link Link Link Link Link Link	52 .20 699E+04 .63775E+04 .00000E+00 .13443E+0523293E+0414934E+0565645E+0332403E+0418990E+04
Link	54 .000006+0020093E+02 .00000E+00 .92890E+04 .1390E+0341471E+0410339E+0414313E+03 .13785E+04
Link Link	56 .00000E+0020093E+02 .00000E+00 .31291E+0478379E+0352366E+04 .48235E+03 .13062E+04 .10777E+04 .5726790E+03 .19594E+04 .00000E+00 .52366E+0448235E+0342299E+0417876E+0410777E+0477625E+03
Link Link	58 .000004-00 .77625E+03 .000004-00 .42299E+04 .17876E+0467050E+04 .77625E+03 .73050E+04 .55306E+02 .000004-00 .67050E+03 .000004-00 .34768E+03 .33050E+00 .55306E+02
Link	
C Link	Offsets and Teneion Data Length Tension-1 Tension-2 Del XI Del Y1 Del X2 Del Y2 Del 1 Del 2
1 2	.60000E+01 .15757E+05 .20431E+0511250E+00 .31198E-02 .14587E+0044147E-02 .11255E+00 .14594E+00 .60000E+01 .20431E+05 .16192E+0514587E+00 .44147E-02 .11553E+0054483E-02 .14594E+00 .11565E+00
2	.60000E+01 .16192E+05 .83753E+04 .11553E+00 .54483E-02 .59743E-01 .31135E-02 .11565E+00 .59824E-01 .60000E+01 .83753E+04 .73353E+04 .59743E-01 .31135E-02 .52394E-01 .22836E-03 .59824E-01 .52395E-01
5	.60000E+01 .73353E+04 .50940E+0452394E-0122836E-03 .34308E-02 .52395E-01 .36386E-01 .50940E+04 .64323E+0434308E-03 .23808E-02 .45928E-0112723E-02 .34386E-01 .45945E-01
\$	
19	.60000e+01 .41581E+04 .71667E+04 .28524E- 01 .82770E-02 .51170E-01 .28288E-02 .29701E-01 .51190E-01 .60000e+01 .71667E+04 .62869E+04 .51112E-01 .28288E-02 .4487E-01 .71627E-02 .51190E-01 .44892E-01 .44892E-01 .4487E-01 .71647E-04 .

Link	Offsets and	Tension Data										
L	Length	Tension-1	Tension-2	Det X1	Del Y1	Del X2	Del Y2	Del 1	Del 2			
13	.60000E+01	.46214E+04		22465E-01		.48345E-01	. 19024E-01	.33010E-01	.51953E-01			
14	.60000E+01	.72735E+04			19024E-01		20210E-02	.51953E-01	.47733E-01			
15	.60000E+01	.66826E+04	.57160E+04	47690E-01	.20210E-02	11004E-01	.39318E-01	.47733E-01	.40829E-01			
16	.60000E+01	.57160E+04	.16384E+05	.11004E-01	- 39318E-01			.40829E-01	.11703E+00			
17	.60000E+01	. 16384E+05	.71594E+05		18578E-01.			.11703E+00	.51139E+00	Wheel	1	
18	.60000E+01	.71594E+05	.50901E+04		45719E+00			.51139E+00	.363588-01	Wheel		
19	.60000E+01	.50901E+04	.84946E+04	19024E-01			51168E-01	.36358E-01	.60676E-01			
20	.60000E+01	.84946E+04		32610E-01			-,17983E-01	.60676E-01	.31796E-01			
21	.60000E+01	.44514E+04	.21721E+04	26222E-01		14366E-03		.31796E-01	.15515E-01			
22	.60000E+01	.21721E+04	.501596+04	.14366E-03	15515E-01			. 15515E-01	.35828E-01	Uhee i	2	
23	. 60000E+01	.50159E+04	.62092E+04	.34094E-01	.11012E-01	44315E-01	17909E-02	.35828E-01	.44351E-01			
24	.60000E+01	.62092E+04	.70749E+04	.44315E-01	.17909E-02	49164E-01	11689E-01	.44351E-01	.50535E-01			
25	.60000E+01	.70749E+04	.77819E+04	.49164E-01	.11689E-01	55583E-01	53383E-03	.50535E-01	.55585E-01			
26	.60000E+01	.77819E+04	.84997E+04	.55583E-01	.53383E-03	60249E-01	.74786E-02	.55585E-01	.60712E-01			
27	.60000E+01	.84997E+04	.85910E+04	.60249E-01	74786E-02	61092E-01	57788E-02	.60712E-01	.61364E-01	Wheel	3	
28	.60000E+01	.85910E+04	.84591E+04	.61092E-01	.57788E-02	60421E-01	33565E-03	.61364E-01	.60422E-01			
29	.60000E+01	.84591E+04	.83540E+04	.60421E-01	.33565E-03	59620E-01	.24704E-02	.60422E-01	.59672E-01			
30	.60000E+01	.83540E+04	.84028E+04	.59620E-01	24704E-02	59780E-01	.53613E-02	.59672E-01	.60020E-01			
31	.60000E+01	.84028E+04	.85988E+04	.59780E-01	53613E-02	61262E-01	43982E-02	.60020E-01	.61420E-01	Ground	and Wheet	4
32	.60000E+01	.85988E+04	.86527E+04		.43982E-02		.14928E-02	.61420E-01	.61805E-01			
33	.60000E+01	.86527E+04	.86693E+04		14928E-02		.45857E-02	.61805E-01	.61923E-01			
34	.60000E+01	.86693E+04	.872116+04		45657E-02		.96049E-02	.61923E-01	.62294E-01			
35	.60000E+01	.87211E+04	.93232E+04		96049E-02			.62294E-01	.66594E-01	Ground	and Wheel	5
36	.60000E+01	.932328+04	.84801E+04	.65809E-01	. 10200E-01	59657E-01	.10490E-01	.66594€-01	.60572E-01			
37	.60000E+01	.84801E+04	.76763E+04	.59657E-01	10490E-01	54416E-01	.67320E-02	.60572E-01	.54831E-01			
38	.60000E+01	.76763E+04	.74081E+04	.54416E-01	67320E-02	52573E-01	.60091E-02	.54831E-01	.52915E-01			
39	.60000E+01	.74081E+04	.75771E+04	.52573E-01	60091E-02	50261E-01	20077E-01	.52915E-01	.54122E-01	Ground	and Wheel	6
40	.60000€+01	.75771E+04	.81757E+04	.50261E-01	.20077E-01	53601E-01	.23177E-01	.54122E-01	.58398E-01			
41	.60000E+01	.81757E+04	.10112E+05		·.23177€-01		.44247E-01	.58398E-01	.72227E-01			
42	.40000E+01	.10112E+05	.13033E+05		44247E-01		.5783SE-01	.72227E-01	.93089€-01			
43	.60000E+01	. 13033E+05	.11984E+05		57835E-01			.93089E-01	.85602E-01			
44	.60000E+01	. 11984E+05	.13993E+05	.82871E-01			88373E-02	.85602E-01		Uhee i	7	
45	.40000E+01	. 13993E+05	.223686+05	.995596-01			14379E+00	.99951E-01	.15977E+00			
46	.60000E+01	.223686+05	.26886E+05	.69642E-01		18798E-01		.15977E+00	. 19204E+00			
47		.26886€+05	. 10393E+05	.18798E-01		.22338E-01		. 19204E+00	.74237E-01			
48	.60000E+01	.10393E+05		22338E-01		.39112E-01		.74237E-01	.40903E-01			
49	.60000E+01			39112E-01		.61724E-01		.40903E-01	.67411E-01			
50	.60000E+01	.94376E+04			27099€-01		14137E-01	.67411E-01	.81773E-01			
51	.60000E+01	.11448E+05		80542E-01			16638E-01	.81773E-01	.97451E-01			
52	.60000E+01	. 13643E+05		96020E-01		. 10667E+00		.97451E-01	.10677E+00	Uhee l		
53		.14948E+05			46889E-02		.99283E-03	.10677E+00	.66357E-01	Wheel	4	
54	.60000E+01	.92900E+04			99283E-03	.29622E-01		.66357E-01	.30529E-01			
55	.60000E+01	.42741E+04			73851E-02		55985E-02	.30529E-01	.23041E-01			
56	.60000E+01	.32258E+04		22351E-01			34453E-02	. 23041E-01	.37563E-01			
57	.60000E+01	.52588E+04		37404E-01			. 12769E - 01	.37563E-01	.32801E-01	Wheel	5	
58	.60000E+01	.45922E+04			12769E-01	.47893E-01		.32801E-01	.48523E-01			
59	.60000€+01	.67933E+04			77990E-02		24834E-02	.48523E-01	.58189E-01			
60	.60000E+01	.81465E+04	.15757E+05	58136E-01	.24834E-02	.11250E+00	31198E-02	.58189E-01	,11255E+00			

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TRV, Tre	cked Yeh	icle Dynamics	- Version 1.00
33	.0033	.0001000	2.500
34	.0034	.0001000	2.500
35	.0035	.0001000	2.500
36	.0036	.0001000	2.500
37	.0037	.0001000	2.500 .
38	.0038	.0001000	2.500
39	.0039	.0001000	2.500
40	.0040	.0001000	2.500

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TRY, Tracked Vehicle Dynamics - Version 1.00

OUTPUT AT TIME .0040

recession describes research recession

Displacement	s. Velocitie	es, and Accel	erstions						
	X	Υ.	. Theta	x-vei	Y-Vel	Omega	Y-Accel	Y-Accel	Alpha
Vehicle -	.57777E+00	.24100E+02	.53219E-05	14305E+05	.45373E+02	39992E-02	.10799E+04	.75202E+04	- 11048E+0Z
Wheel 1 -	.74436E+02	.20053E+02	.62832E-01	.28275E+03	32144E+03	.15708E+02	65121E+05	11749E+03	.00000€+00
Wheel 2 -	.50322E+02	.14571E+02	.45584E-01	16513E+03	.80631E+02	.11396E+02	20181E+05	26571E+05	.00000E+00
Wheel 3 .	.255796+02	.14020E+02		14650E+03		.11396E+02	.40673E+03		.00000E+00
Uheel 4 -	.56402E+00	.13965E+02		14703E+03	.13231E+02	.11396E+02	71217E+03	13826E+05	.00000E+00
	.24814E+02	. 13844E+02	.45584E-01	30638E+03	.44501E+02		10204E+05		.00000E+00
Wheel 6	.49420E+02	. 13740E+02	.45584E-01	11656E+03	11813E+02	.11396E+02	.39150E+04	.17314E+05	.00000E+00
Wheel?	.73705E+02	. 14248E+02	.62832E-01	38732E+03	60844E+03	.15708E+02	.14500E+05	32721E+05	.00000E+00
Link 1 .	.10535E+01	.26704E+02	.31113E+01	31666E+03	.76687E+01	47793E+00	16573E+05	.13927E+05	30691E+03
	.72076E+01	.26945E+02	.30942E+01	27533E+03	.51925E+01	.58751E-01	.24678E+05		. 19848E+03
	.133496+02	.27270E+02		29642E+03	.35470E+01	.92602E+00	.55889E+05		. 13504E+04
Link 4 ·	.19467E+02	.27623E+02		. 36453E+03	.42859E+01	.14390E+01	.12120E+06		.95391E+03
Link 5 -	.25546E+02	.27827E+02	.31322E+01	41077E+03	.94760E+01	20526E+01	.66561E+05	. A3539E+04	32296E+03
Link 6 -	.31604E+02	.27937E+02	.31143E+01	44513E+03	.19126E+02	17631E+01	.72174E+05	. 19814E+04	.39464E+03
	.37625E+02	.28271E+02		43447E+03	.19719E+02	.33260E+01	.40574E+05		28096E+03
	.43630E+02	.286166+02		39331E+03		37542E+01	.12294E+06		.11574E+04
	.49589E+02	.28968E+02		34810E+03	.13093E+01	.52600E+01	.12620E+06		62414E+03
Link 10 -	.55501E+02	.29288E+02	.31233E+01	26523E+03		46972E+01		.55118E+04	.89026E+03
	.61417E+02	.29640E+02		19553E+03	.13296E+02		14882E+06		45405E+04
	.67390E+02						10469E+06		.13778E+04
	.73377E+02				10808E+03	.26130€+02	.48970E+05	.34696E+05	.20359E+04
	.79031E+02				15727E+03		.17228E+06		.81186E+04
	.83383E+02	.257438+02 -			14315E+03	.12272E+02	.10037E+06	.54907E+05	.25359E+05
	.84506E+02	.203386+02 -			12042E+03	.23259€+02	.64690E+03		.34776E+05
	.82046E+02	.15015E+02 ·	.901956+00		10978E+03		.14937E+06		.37754E+04
	.77097E+02						12971E+07		42206E+05
	.71423E+02	.96132E+01 -					92422E+04		
Link 20 -	.65803E+02	.75983E+01 -			22427E+03	.17713E+02	.15506E+05		12696E+05
Link 21 -	.60299E+02	.53011E+01 -	.43174E-00	.65447E+0Z	18185E+03	.45454E+01	.39089E+05	.74783E+05	99012E+03
Link 22 -	.54943E+02	.26668E+01 ·	.48535E+00	.92035E+02	10261E+03	.28781E+02	.62874E+05	29514E+05	.24762E+04
Link 23 -	.492886+02	.12880E+01	.36385E-02	.92056E+02	.14391E+02	.13473E+02	.61300E+05	· . 185 16E+05	. 19273E+04
	.43266E+02	.13990E+01	.32318E-01	.60885E+02	.41635E+02-	56246E+01	.36744E+05		. 10388E+02
	.37234E+02	.133528+01 -		.43986E+02	. 19374E+02	.11178E+01	. 15502E+05	.20127E+05	30570€+03
	.31195E+02	.12579E+01	.25287E-01		11443E+02	83612E+01	.11153E+05	.67955E+04	.15335E+04
	.25149€+02	.12740E+01 ·			24833E+02	.13177E+01	.97951E+04		. 16515E+04
	. 1 9099E+ 02	.12424E+01	.101748-01		10356E+02	.370338+01	.66777E+04	. 10365E+05	. 1 69 63E+03
	.13045E+02	.12667E+01 ·				.13133E-01	.49053E+04	.49803E+04	.84424E+03
	. 69898E+01				55793E+01		.369678+04	.12868E+05	.18996E+04
	.93301E+00				11289E+02		.27046E+04		47086E+03
Link 32	.51247E+01	. 12444E+01			·.72733E+01	. 23458E+01	. 232556+04		23795E+04
Link 33	.11183E+02				41874E+01		.55247E+03	.89873E+04	·.19545E+03
Link 34	.17242E+02				16763E+02	59281E+01	54920E+04	.15288E+05	. 13458E+04
Link 35	.232 99E+ 02	.12000E+01 -				.14957E+01	62534E+04		23857E+04
Link 36	. 29352E+02	. 12711E+01			13203E+02	.180916+01	.39513E+04	.46699E+05	39537E+04
Link 37	.35404E+02	.13054E+01 -	.33894E-01	34991E+02	.18074E+02	.43783E+01	·.14947E+04	.76453E+04	.15731E+04
Link 38	.41455E+02	.13732E+01	.54986E-01	41228E+02	.56821E+00	82521E+01	23312E+05	43484E+05	17486E+04
Link 39	.47483E+02	.12165E+01 ·	. 103566+00	39080E+02	42924E+02	.613916+01	·.55544E+04	47161E+05	60067E+03
Link 40	.53457E+02	.15237E+01		14978E+02	46525E+02	14537E+02	.51883E+04	.40596E+05	71766E+03
Link 41	.59290E+02	.31241E+01	.32847E+00	.398246+02	73758E+02	29426E+02	.47478E+05	.12587E+06	.73163E+04
link 42	A5202F+02	42A09E+01	149226-01	903796+02	- 10101E+63	- 25212F+02	447838+05	193245+04	17751F+05

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Second Proposes

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FY-End 2
-.77201E+03
.29467E+03
.66813E+03
.33230E+03
.13561E+03
.41468E+03
                                                    FX .00000E+00 -.20093E+02 .0000E+00 -.20093E+00 -.20093E+0
                                                                                                                                                                                                           FX-End 1 FY-End 1
-.33634e+04 -.43349e+03
-.32741e+04 .77201e+03
-.60803e+04 -.29467e+03
-.66602e+04 -.66813e+03
-.71695e+04 -.33230e+03
                                                                                                                                                                                                                                                                                                                        FX-End 2
.52741E+04
.60803E+04
                                                                                                                                                                                                                                                                                                                                                                                                                                M-End 1
15076E+04
                                                                                                                                                            00+300000
00+300000
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00+300000
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.71695E+04
.75168E+04
.77719E+04
                                                                                                                                                                                                                                                                                                                                                                                                                              .60757E+03
.69180E+03
.26729E+03
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   69180F+03
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 Link
                                                                                                                                                                                                         - 71695e+06 - 33230e+03 - 75168e+04 - 13561e+03 - 77169e+06 - 41468e+03 - 79641e+06 - 41468e+03 - 81156e+06 - 96514e+03 - 82564e+06 - 3324e+05 - 82564e+06 - 15419e+03 - 7795e+06 - 44964e+03 - 778418e+06 - 22519e+06 - 80472e+06 - 21655e+03
                                                                                                                                                            .00000E+00
.00000E+00
.00000E+00
.00000E+00
Link
Link
Link
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.79641E+04
.831154E+04
.82351E+04
.82651E+04
.797975E+04
.80472E+04
.79695E+04
.6773E+04
.79895E+04
.79283E+04
.10397E+05
.12726E+05
.12138E+05
.13558E+05
                                                                                                                                                                                                                                                                                                                                                                                                                             .33189E+03
                                                                                                                                                                                                                                                                                                                                                                                                                                                                               - 32017F+03
                                                                                                        .20093E+02
.46925E+03
.22367E+04
.54282E+03
.20093E+02
.49953E+03
.34124E+04
.20093E+02
.20093E+02
                                                     .00000E+00
.10702E+02
.00000E+00
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.96514E+03
.33324E+03
.15419E+03
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.30825E+03
.23612E+03
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.27857E+03
Link
Link
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Link
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.57600E+03
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.22319E+04 -.57600E+03
.21653E+03 -.16163E+03
.63418E+03 -.35104E+02
                                                      .00000E+00
                                                     .18744E+03
.00000E+00
.00000E+00
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.00000E+00
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.35104E+02
 Link
 Link
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                                                                                                                                                                                                           - 304/26-04 - .243/38-03

- 796958-04 - .634/38-03

- 675738-04 - .160698-04

- 765838-04 - .301378-03

- 792838-04 - .243258-04

- 127268-05 - .190668-05

- 121388-05 - .203548-05

- 13588-05 - .24308-04
Link
Link
Link
                                                                                                          .20093E+02
.43606E+04
.20093E+02
                                                                                                                                                                                                                                                                                                                                                                                                                            .84042E+03
- .82930E+03
.10071E+04
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.10071E+04
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.24325E+04
.89960E+04
.19066E+05
                                                     .11900E+04
.00000E+00
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                                                                                                          .20093E+02
.20093E+02
.20093E+02
.78334E+05
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 Link
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                                                      .00000E+00
.00000E+00
.33797E+05
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.00000E+00
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.27527E+04
.95028E+04
 Link
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.26210E+04
                                                                                                                                                                                                         -12138E+05 -20354E+05
-13558E+05 -26210E+03
-3647E+04 -78611E+03
-15474E+04 -56571E+04
-92014E+03 -13933E+05
-15854E+04 -83783E+04
-14356E+04 -4520ZE+04
-18349E+04 -4520ZE+04
-10171E+04 -70265E+03
-21300E+03 38111E+04
-16462E+04 -9331E+03
-37969E+04 -11460E+03
-45404E+04 -32093E+04
-10811E+05 -62661E+03
-17770E+05 77994E+03
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 Link
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.00000E+00
.00000E+00
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- .20093E+02
- .20093E+02
- .20093E+02
- .20093E+02
- .20093E+02
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.00000E+00
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.00000E+00
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.60647E+04
.15474E+04
.92014E+03
.15854E+04
.14356E+04
Link
Link
Link
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.21707E+04
.91855E+02
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.13933E+05
.83783E+04
.45202E+04
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-.67304E+03
-.55599E+03
.32513E+04
 Link
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                                                                                                  -.20093E+02
-.20093E+02
-.20093E+02
-.2529E+04
-.20093E+02
-.20093E+02
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-.20093E+02
-.20093E+02
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.45043E+03
.33513E+04
.70265E+03
-.38111E+04
-.93311E+03
.11460E+03
.32093E+04
-.10412E+04
-.62861E+03
 Link
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.00000E+00
.78566E+03
.28825E+03
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.00000E+00
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.11301E+04
.10171E+04
.21300E+03
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.25882E+04
.34181E+04
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.34181E+04
.14557E+04
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 Link
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.91578E+03
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·.16625E+04

·.37949E+04

·.45404E+04

·.69315E+04

·.10811E+05
 Link
Link
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.10806E+04
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.13937E+04
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.13937E+04
Link
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                                                      .00000E+00 -.20093E+02
.00000E+00 -.20093E+02
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-.21378E+05
                                                                                                                                                                                                                                                                                                                                                                           .77994E+03
.45977E+03
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.62750E+02 -.49929E+02
 Link Offsets and Tension Data
L Length Tension-1
-1 .60000E+01 .21383E+05
                                                                                                                                                                                                                                        0el Y1
.32641E-02
.78106E-02
.59179E-02
.37806E-02
.31519E-02
                                                                                                                                                                                                                                                                                          Det X2
.15883E+00
.14966E+00
.12890E+00
.83887E-01
.59164E-01
.32357E-01
                             Length
.60000E+01
.60000E+01
                                                                                                                                Tension-2
.22263E+05
.20969E+05
.18054E+05
.11752E+05
.82830E+04
.45324E+04
                                                                                                                                                                                 Det X1
-.15270E+00
-.15883E+00
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-.78106E-02
-.59179E-02
                                                                                                                                                                                                                                                                                                                                                                                                    Det 1
.15274E+00
.15992E+00
.14978E+00
                                                                                                                                                                                                                                                                                                                                                                                                                                                      Det 2
.15902E+00
.14978E+00
                                                                              .22263E+05
                                                                               .20969E+05
.18054E+05
.11752E+05
                              .60000€+01
                                                                                                                                                                                     . 14966E+00
                                                                                                                                                                                                                                                                                                                                              -. 37806E-02
                                                                                                                                                                                                                                                                                                                                                                                                                                                           12896E+00
                                                                                                                                                                                                                                                                                                                                                                                                     .12896E+00
.83946E-01
.59165E-01
                                                                                                                                                                                        . 12890E+00
. 83887E-01
                                                                                                                                                                                                                                                                                                                                                    .31519E-02
.19256E-03
                                                                                                                                                                                                                                                                                                                                                                                                                                                         .83946E-01
                              .60000E+01
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.32357E-01
.17286E-01
.28379E-01
.75253E-01
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                              .60000E+01
                                                                                .82830F+04
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                                                                               .45324E+04
.24494E+04
.40688E+04
                                                                                                                                   .24494E+04
.40688E+04
.10543E+05
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.26986E-02
.62687E-02
.29088E-02
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-.28379E-01
-.75253E-01
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.62687E-02
.29088E-02
.71807E-03
                             .60000E+01
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.75309E-01
                              .60000E+01
          10
                              .60000E+01
                                                                                .10543F+05
                                                                                                                                    .95183E+04
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                                                                              .95183E+04
.24510E+04
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.40605E+04
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.12706E-01
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. 12484E-01
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                               40000E+01
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Cyc 41 42 Time Time-Step .0041 .0001000 .0042 .0001000

2.500 2.500

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1836 S. 27 (1833)

tav. Tre	cked Veh	icle Dynamics	- Version	1.00
43	.0043	.0001000	2.500	
44	.0044	.0001008	2.500	
45	.0045	.0001000	2.500	
46	.0046	.0001000	2.500	
47	.0047	.0001000	2.500 •	
48	.0048	.0001000	2.500	
49	0049	.0001000	2.500	
50	.0050	.0001000	2.500	

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22222C

.41839E+01

.30323€-01

11010E+03

109948+03

80045E+01

.22925E+05

-. 14291E+06

. 15670E+05

OUTPUT AT TIME .0050

Displacements, Velocities, and Accelerations χ . There we hicked -.72025E-00 .24140E-02 -.54545E-05 wheel 1 -.76195E-02 .19733E-02 .76540E-01 Alpha -.19486E+02 .00000E+00 .00000E+00 .00000E+00 .00000E+00 .00000E+00 .00000E+00 .15378E+04 92298E+03 x-vel .14188E+03 .19082E+03 Y-Vel .51977E+02 -31906E+03 .57232E+02 -18057E+02 -15031E+01 X-Accel .12578E+04 .11650E+06 Y-Accel .55040E+04 .85454E+04 Onega .18967E-01 .15708E+02 - .54545E-05 .78540E-01 .56980E-01 .56980E-01 .56980E-01 .56980E-01 .56980E-01 .78540E-01 .31113E+01 Wheel Wheel Wheel Wheel Wheel Wheel Wheel Link -.76195E+02 -.50496E+02 -.25725E+02 -.71138E+00 .24504E+02 .49305E+02 .73326E+02 -.13588E+01 -.74937E+01 -, 11a50E+06 -, 15762E+05 -, 75229E+03 -, 29992E+03 -, 12889E+04 -, 35418E+04 -, 30674E+05 -, 13766E+05 -, 1456E+05 .14640E+02 .14009E+02 .13970E+02 .13855E+02 .18343E+03 .14593E+03 .14761E+03 .31138E+03 .22006E+05 .12729E+05 .13980E+05 .19778E+05 .11396F+02 .11396E+02 .11396E+02 .11396E+02 .11396E+02 .11396E+02 .15708E+02 .51801E+00 .44919E+00 .14855E+01 .18132E+01 .27739E+01 .13992E+02 .13855E+02 .13745E+02 .13642E+02 .26718E+02 .26952E+02 .27273E+02 .27623E+02 .27831E+02 -.13992E+02 .26315E+02 -.58333E+03 .18395E+02 .11962E+02 .52486E+01 .45929E+01 .13213E+01 .11198E+03 .36871E+03 .29380E+03 .30019E+03 .40997E+05 .94635E+05 .64465E+04 .14946E+05 1234567 244156+05 Link .30945E+01 .92298E+03 Link Link Link Link -.13634E+02 -.19775E+02 -.25905E+02 .30839E+01 .30858E+01 .31299E+01 .31125E+01 .28319E+03 .27560E+03 .30572E+03 .49680E+04 .10200E+05 .58416E+04 .90754E+04 .86373E+02 .87530E+01 .12245E+04 .41835E+05 .13310E+06 .15355E+06 .27831E+02 .27957E+02 .28286E+02 .28623E+02 .28975E+02 .29297E+02 -.31989E+02 .17294E+01 .32478E+03 .19098E+02 .62680E+02 -.38007E+02 -.43960E+02 -.49875E+02 -.55779E+02 .30611E+01 .31082E+01 .30568E+01 .31185E+01 .31822E+03 .28158E+03 .25351E+03 .26651E+03 .89910E+01 .64318E+01 .97662E+01 .12070E+02 .17268E+06 .10062E+06 .29806E+05 .80985E+04 .13329E+05 .62026E+04 .89203E+03 .59611E+04 Link 333346+01 .32790E+03 .85807E+03 .24532E+04 .78703E+03 .23647E+01 .35727E+01 Link Link 10 11 12 13 48171E+01 .29297E+02 .29644E+02 .29907E+02 .30317E+02 .29399E+02 .25603E+02 .20191E+02 - .61684E+02 - .67592E+02 - .73474E+02 - .79034E+02 .30478E+01 .31405E+01 .30045E+01 .26768E+01 .29851E+03 .20615E+03 .75772E+02 .12065E+02 .21297E+02 .72040E+02 .52912E+01 .48828E-02 .21988E+02 .52765E+01 .49727E+04 .26888E+05 .12132E+05 .11258E+06 -.31427E+05 .50153E+05 .32846E+05 .71130E+05 .24162E+03 .30945E+04 .96710E+04 .39223E+04 Link Link Link 14 15 16 17 Link 11586F+02 12914E+03 .39223E+04 .42472E+04 .84331E+04 .12136E+05 .69372E+04 .71552E+04 Link Link -.83333E+02 -.84374E+02 -.81863E+02 -.77107E+02 -.21605E+01 -.13646E+01 -.90280E+00 .45594E+01 .17355E+03 .20845E+03 .15883E+03 .16324E+03 .10856E+03 .25427E+03 .26561E+02 .43425E+02 .44651E+01 .12319E+03 .10460E+06 .67616E+05 .21658E+05 .94193E+06 -.69245E+05 -.28434E+05 -.56856E+06 -.10994E+07 .14906E+02 Link .14906E+02 .11192E+02 .91639E+01 .73734E+01 .51420E+01 .25632E+01 .12961E+01 .14298E+01 .13586E+01 .12545E+01 Link Link Link 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 .42112E+00 94196E+01 .94196E+01 .65463E+02 .22346E+02 .65131E+02 .11766E+03 .14508E+03 .11189E+03 .74129E+02 .46991E+02 .71481E+02 .65774E+02 .60229E+02 .54831E+02 .28273E+00 .33759E+00 .42865E+00 .45731E+00 .12187E+05 .85362E+05 .44748E+05 .23717E+05 45839E+03 38610E+02 .30407E+05 -.45839E+03 -.25001E+03 -.16133E+03 -.95677E+02 .18653E+01 .26698E+02 .21257E+02 .20022E+01 .38610E+02 .15398E+02 .19502E+01 .26109E+02 .14687E+02 .49585E+01 .30501E+00 .78551E+01 -.30407E+05 -.26658E+05 -.22037E+05 -.43222E+04 -.31184E+05 -.53870E+05 -.44077E+05 -.23961E+05 Link .11709E+04 - 24499E+04 - 86798E+03 - 12156E+05 - 53066E+04 - 20307E+05 - 64535E+06 - 15732E+05 Link Link Link Link - .49164E+02 - .43178E+02 - .37176E+02 - .31156E+02 .17979E-01 .26927E-01 .51120E-01 .17382E-01 .17188E+03 .1748E+03 .13665E+04 .37407E+03 .34714E+03 Link Link Link - .25124E+02 - .19086E+02 - .13042E+02 - .69920E+01 .12479E+01 .12373E+01 .12724E+01 .19274E-01 .13966E-01 .18528E-02 .31310E+02 .19067E+02 .85735E+01 .22785E+02 .18585E+01 .13125E+02 28192E+01 39138E+01 96872E+00 .16462E+05 .16339E+05 .12863E+05 .76714E+04 .86012E+03 .37239E+03 .79130E+03 .29313E+04 12473E+01 10090E+01 Link .81189E-02 .67006E+00 .87492E+01 14663E+05 .93956E+00 .51140E+01 .11167E+02 .51633E+01 .10529E+02 .17433E+02 Link .29105E-02 .13019E-01 12226E+01 .71141F+01 91494E-01 .33264E+06 16538F+05 .73552F+03 .10455E+02 .16370E+02 .99191E+01 .58465E+03 .36640E+04 .18232E+04 .12480E+01 .12670E+01 10284E+00 Link 40500E-02 14129E+00 28780E+01 .23898E+05 10841E+04 Link 17219E+02 12420E+01 4459RF - 02 24380E+02 26264F+05 40147F+04 .23271E+02 .29320E+02 .35366E+02 .11947E+01 .12786E+01 .13185E+01 .14858E-01 .44842E-01 .29509E-01 .29320E+02 .32591E+02 .42004E+02 .55544E+01 .15771E+02 .61361E+01 .29107E+04 .64556E+04 .37401E+04 .36052E+04 .95237E+03 .12996E+05 10948E+01 .11954E+04 .51837E+04 Link 35092E+01 .34382E+04 Link .41410E+02 .47450E+02 .53455E+02 .13533E+01 .11981E+01 .15316E+01 .44737E-01 .96616E-01 .19657E+00 .40965E+02 .22272E+02 .15014E+02 .28782E+05 .73053E+05 .10798E+06 .12049E+05 .19059E+04 .90733E+04 .15724E+05 Link 22574E+02 11776E+02 21291E+05 .15934E+02 .60947E+02 .53375E+01 .92864E+01 .38051E+01 .35629E+05 Link .31074E+01 41 59351E+02 .30909E+00 .73163E+02 . 10158E+02 .14560E+05 . 170908+05

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Link	Oiso	Lacem	nts. Velocit	ies, and Acce	iterations						
Link						x-vel	Y-Vel	Omega	X-Accel	Y-Accel	Alpha
Link	Link	43	.71382£+02	.46337E+01	.11306E+00			27807E+02	·.80559E+05	97304E+05	.69983E+04
Link 45	Link	44	.773716+02	.55790E+01	.20127€+00	.37395E+02	38694E+03	.68439E+02	.64198E+06	15228E+07	31010E+03
Link 47	Link	45	.81545E+02	.89503E+01	.11545E+01	19857E+03	17683E+03	.47800E+02	71050E+05	11907E+06	26352E+ü4
Link 48	Link	46	.82662E+02	. 14676E+02	.16009E+01	41838E+03	14097E+03	.19615E+02	99753E+04	16875E+06	.45665E+04
Link 50	Link	47	.80890€+02	.20087E+02	.21620E+01	48853E+03	18069E+03	.12710E+02	. 14076E+05	11858E+05	. 19146E+05
Link 50	Link	48	.76435E+02	.23625E+02	.27553E+01	46646E+03	24654E+03	25141E+02	.29362E+05	. 20936E+06	.16381E+05
Link 51	Link	49	.70663E+02	.24729E+02	31345E+01	41025E+03	15892E+03	52297E+02	.61946E+05	.789148+05	15610E+04
Link 52	Link	50	.44718€+02	.25121E+02	.30116E+01	37104E+03	57049E+02	89411E+01	.77330E+05	. 10402E+04	14299€+05
Link 53	Link	51	.58802E+02	.25519E+02	31365E+01	31109E+03	.56044E+02	31436E+02	.42998E+05	89932E+05	83855E+03
Link 56	Link	52	.52918E+02	.25 996E+ 02	.297416+01	25206E:03	.90424E+02	.12810E+02	11822E+05	.42543E+03	·.34673E+04
Link 55	Link	53	.47034E+02	.26335E+02	30907E+01	22352E+03	.67068E+02	30156E+01	10023E+06	.59946E+05	.324816+03
Link 56	Link	54	.41087E+02	.25888E+02	30387E+01	19099E+03	.10564E+03	18345E+01	86912E+05	27860E+05	26453E+04
Link 56	Link	55	.35113E+02	.25828E+02	.30603E+01	16892E+03	.94949E+02	. 13552E+02	64989E+05	.14117E+05	36330E+04
Link 58 .17060E-02 .26941E-02 .3108E-01 -28517E-03 .21026E-02 .31025E-01 .11109E-06 .21208E-05 .11508E-05 .11508E-05 .11508E-05 .11508E-05 .11508E-05 .11508E-05 .11508E-06 .115	Link	56	.29100E+02	.25996E+02	31131E+01	18083E+03	.99178E+02	12985E+02	93401E+05	. 14655E+05	35002E+04
Link 58	Link	57	.23097E+02	.26489E+02	.29524E+01	22642E+03	.65876E+02	.16567E+02	99329E+05	27808E+04	.40140E+04
Link 59	Link	58	.17060E+02	.26941E+02							.21229E+04
Forces and Noments											
Forces and Naments											
Vehicle					13.27.12.01	12.0250.05	1102102102	, 103, 02, 03		.5.4.22	
Vehicle	Force	es and	Homents								
Name						FX-End 1	FY-End 1	FX-End 2	FY-End 2	M-End 1	M-End 2
Second Color Seco	Vehi	cle	.32553E+05	.14244E+06	2494ZE+07						
Section Sect	Whee	4 1	36114E+05	.26491E+04	.000000€+00						
Neet 4 -3.4790€+02 - 16217E+04 .00000E+00 .00000E+00 .00000E+00 .0000E+00	Whee	1 2	18283E+04	25527E+04							
Unit 1 00000E+00 -20093E+02 00000E+00 -1198E+05 -2061E+03 -1198E+05 -2264E+03 -1198E+05 -2264E+03 -1198E+05 -2264E+03 -1198E+05 -2264E+03 -1198E+05 -2264E+05 -1136E+04 -20000E+00 -20093E+02 00000E+00 -20093E+02 0000E+00 -1198E+05 -3264E+03 -3998E+04 -70600E+02 -27891E+03 47196E+02 1188 00000E+00 -20093E+02 0000E+00 -1198E+05 -3264E+03 -3998E+04 -70600E+02 -47196E+03 -	Whee	1 3	.87265€+02	14766E+04							
Section Sect	Whee	1 4	34790E+02	16217E+04	.00000€+00						
United 7 .95090E+04 .29337E+05 .00000E+00 .2028E+05 .11462E+0319552E+05 .24069E+03 .10996E+02 .26680E+02 .1762E+05 .24069E+03 .10996E+02 .26680E+02 .26680E+02 .26680E+02 .26680E+02 .26680E+02 .26680E+02 .26680E+02 .26680E+03 .20000E+00 .20093E+02 .00000E+00 .21080E+05 .13164E+04 .18905E+05 .86611E+03 .31256E+02 .27891E+03 .2789	Whee	l 5	. 14951E+03	22943E+04	.0000000+00						
Link 2 .00000E+00 -20093E+02 .00000E+00 .1953ZE+05 .1146ZE+03 -1953ZE+05 .2006ZE+05 .1038DE+04 .2668DE+02 .4504PE+02 Link 3 .00000E+00 -20093E+02 .00000E+00 .2082ZE+05 .1038DE+04 .2108DE+05 .13164E+04 .4505PE+02 .31256E+02 Link 5 .00000E+00 -20093E+02 .0000DE+00 .2082ZE+05 .1038DE+04 .2108DE+05 .13164E+04 .4505PE+02 .31256E+02 .1756E+02 .1756E+	Whee	1 6	.41085E+03	.47557E+04	.00000€+00						
Link 3 .00000E+00 -20093E+02 .00000E+00 .21080E+05 -13164E+04 -18905E+05 .80611E+03 .31256E+02 .5126E+02 .116 .00000E+00 -20093E+02 .00000E+00 .21080E+05 -13164E+04 -18905E+05 .80611E+03 .31256E+02 .27891E+03 .116 .00000E+00 -20093E+02 .00000E+00 .18905E+05 .80611E+03 .31256E+02 .27891E+03 .1198E+05 .5224E+03 .3789E+04 .70608E+02 .27891E+03 .1198E+05 .5224E+03 .3789E+04 .70608E+02 .47196E+02 .3016P+03 .1198E+05 .5224E+03 .3789E+04 .70608E+02 .47196E+02 .3016P+03 .1198E+05 .524E+03 .3189E+04 .60240E+03 .3016P+03	Whee	17	.95090€+04	.29337E+05	.000000€+00						
Link 6 .00000E+00 -20093E+02 .00000E+00 .18905E+05 -13164E+06 -18905E+05 .80611E+03 -31256E+02 .27891E+03 .47196E+02 .1ink 5 .00000E+00 -20093E+02 .00000E+00 .18905E+05 -80611E+03 -11984E+05 .52244E+03 .27891E+03 .47196E+02 .1ink 6 .00000E+00 -20093E+02 .00000E+00 .18905E+05 -80611E+03 -11984E+05 .52244E+03 .27891E+03 .47196E+02 .1ink 7 .00000E+00 -20093E+02 .00000E+00 .18905E+05 .80611E+03 -11984E+05 .52244E+03 .27891E+03 .47196E+02 .1ink 8 .00000E+00 -20093E+02 .00000E+00 .49803E+04 .60240E+03 .30149E+03 .30149E+03 .1ink 8 .00000E+00 -20093E+02 .00000E+00 .49803E+04 .60240E+03 .11762E+05 .19329E+03 .37356E+03 .37356E+03 .17356E+03 .17356E+03 .17356E+03 .25977E+03 .3344E+03 .37356E+03 .57356E+03 .1ink 10 .00000E+00 -20093E+02 .00000E+00 -101212E+05 .25977E+03 .11762E+05 .19329E+03 .37356E+03 .57356E+03 .1ink 11 .00000E+00 -20093E+02 .00000E+00 -11083E+05 .29973E+04 .12481E+05 .48318E+03 .5525E+03 .6735E+03 .1ink 12 .00000E+00 -20093E+02 .00000E+00 -11083E+05 .20973E+04 .12481E+05 .53081E+03 .22332E+03 .22332E+03 .15007E+04 .1ink 13 .00000E+00 -20093E+02 .00000E+00 -11083E+05 .20973E+04 .12481E+05 .53081E+03 .22332E+03 .15007E+04 .27281E+02 .1ink 14 .00000E+00 -20093E+02 .00000E+00 -12481E+05 .53081E+03 .13112E+05 .22580E+04 .15007E+04 .27281E+02 .20064E+04 .15007E+04 .27281E+02 .00000E+00 -20093E+02 .00000E+00 -72575E+04 .59778E+04 .82971E+04 .22981E+04 .22981E+04 .23971E+04 .22984E+04 .23971E+04 .22984E+04 .31707E+04 .1ink 15 .00000E+00 -20093E+02 .00000E+00 -72575E+04 .59778E+04 .18181E+04 .23971E+04 .29084E+04 .31707E+04 .1ink 16 .00000E+00 -20093E+02 .00000E+00 -72575E+04 .59778E+04 .18181E+04 .23971E+04 .29084E+04 .31707E+04 .1ink 17 .15095E+05 .00080E+00 .0000E+00 .20093E+02 .00000E+00 .20093E+00 .20093E+00 .20093E+00 .2009	Link	. 1									
Link 5 .00000E+00 -20093E+02 .00000E+00 .18905E+05 -80611E+03 -11984E+05 .5244E+03 .27891E+03 .27891E+03 .27891E+03 .27891E+03 .19905E+05 .5244E+03 .27891E+03 .27891E+03 .47196E+05 .10000E+00 .20093E+02 .00000E+00 .18905E+05 .52244E+03 .19989E+04 .70608E+02 .47196E+02 .30149E+03 .10000E+00 .20093E+02 .00000E+00 .39989E+04 .70608E+02 .48903E+04 .60240E+03 .10212E+05 .2997TE+03 .30344E+03 .37356E+03 .10000E+00 .20093E+02 .00000E+00 .20093E+02 .00000E+00 .20093E+02 .00000E+00 .20093E+02 .0000E+00 .20093E+02 .00000E+00 .10212E+05 .2997TE+03 .11742E+05 .2997TE+03 .37356E+03 .55245E+03 .55245E+03 .10000E+00 .20093E+02 .00000E+00 .10212E+05 .2997TE+03 .11742E+05 .48318E+03 .55245E+03 .55245E+03 .10000E+00 .20093E+02 .00000E+00 .101742E+05 .2997TE+03 .11742E+05 .20073E+04 .6735E+03 .22332E+03 .1000E+00 .20093E+02 .00000E+00 .10183E+05 .20073E+04 .12481E+05 .53081E+03 .2233E+03 .2233E+03 .1000E+00 .20093E+02 .00000E+00 .1083E+05 .20073E+04 .12481E+05 .22589E+04 .15007E+04 .27281E+02 .10000E+00 .20093E+02 .00000E+00 .13112E+05 .53081E+03 .13112E+05 .22589E+04 .15007E+04 .27281E+02 .10000E+00 .20093E+02 .00000E+00 .13112E+05 .53081E+03 .13112E+05 .22589E+04 .15007E+04 .27281E+02 .10000E+00 .20093E+02 .00000E+00 .13112E+05 .53081E+03 .13112E+05 .22589E+04 .15007E+04 .27281E+02 .10000E+00 .20093E+02 .00000E+00 .13112E+05 .53081E+03 .13112E+05 .2971E+04 .2971E+04 .2970E+04 .27084E+04 .10000E+00 .20093E+02 .00000E+00 .33112E+05 .59778E+04 .59778E+04 .59778E+04 .2970E+04 .2970E+04 .2770E+04 .1770E+04 .1770E	Link										
Link 6 .00000E+00 -20093E+02 .00000E+00 .1890SE+05 -80611E+03 -11984E+05 .52244E+03 .27891E+03 .47194E+02 Link 7 .00000E+00 -20093E+02 .00000E+00 .11984E+05 -52244E+03 .39989E+04 .60240E+03 .30149E+03 .30149E+03 .1018E+03 .00000E+00 .20093E+02 .00000E+00 .39989E+04 .60240E+03 .30149E+03 .30149E+03 .30149E+03 .1018E+05 .29977E+03 .30149E+03 .37356E+03 .11782E+05 .29977E+03 .30149E+03 .57356E+03 .11782E+05 .29973E+04 .67354E+03 .57356E+03 .11782E+05 .29973E+04 .67354E+03 .57356E+03 .11782E+05 .29973E+04 .67354E+03 .57356E+03 .11782E+05 .29973E+04 .67354E+03 .57356E+03 .11782E+05 .29973E+04 .29973E+04 .67354E+03 .2233E+03 .11782E+05 .29973E+04 .29973E+04 .67354E+03 .2233E+03 .11782E+05 .29973E+04 .2783E+02 .29084E+04 .29973E+04 .2	Link										
Link 7 .00000E+00 -20093E+02 .0000E+00 -39980E+04 -7060BE+02 .49803E+04 .7060BE+03 .30149E+03 .30149E+03 .30149E+03 .10149E+03 .0000E+00 -20093E+02 .0000E+00 -49803E+04 .60240E+03 .30149E+03 .30149E+03 .30149E+03 .10149E+03 .0000E+00 -20093E+02 .00000E+00 -10212E+05 .2997TE+03 .10212E+05 -2597TE+03 .36344E+03 .37356E+03 .10149E+03 .10149E+03 .10212E+05 .2997TE+03 .36344E+03 .37356E+03 .10149E+03 .10149E+03 .10212E+05 .2997TE+03 .36344E+03 .37356E+03 .37356E+03 .10149E+03 .10212E+05 .2997TE+03 .36344E+03 .37356E+03 .37356E+03 .37356E+03 .37356E+03 .10212E+05 .2997TE+04 .48318E+03 .55245E+03 .37356E+03 .55245E+03 .10149E+05 .20093E+04 .20093E+02 .00000E+00 -11932E+03 .2997TE+04 .12481E+05 .53081E+03 .2233E=03 .2233E=03 .2233E=03 .2233E=03 .2233E+03 .10149E+05 .20093E+02 .00000E+00 .20093E+02 .00000E+00 .1312E+05 .20093E+04 .72575E+04 .59778E+04 .27281E+02 .10149E+05 .00000E+00 .20093E+02 .00000E+00 .13131E+05 .22589E+04 .72575E+04 .27281E+02 .20084E+04 .10149E+05 .00000E+00 .20093E+02 .00000E+00 .1313E+05 .22589E+04 .3534E+04 .27281E+05 .20093E+02 .00000E+00 .72575E+04 .59778E+04 .27281E+04 .29084E+04 .10149E+05 .20093E+05 .00000E+00 .72575E+04 .59778E+04 .29371E+04 .29084E+04 .31707E+04 .27281E+02 .00000E+00 .20093E+02 .00000E+00 .72575E+04 .59778E+04 .29371E+04 .29384E+03 .31707E+04 .27281E+02 .00000E+00 .20093E+02 .00000E+00 .72575E+05 .5083E+03 .22455E+05 .18538E+05 .21704E+04 .94269E+04 .13626E+05 .2003E+04 .94269E+04 .13626E+05 .2003E+04 .94269E+04 .94269E+04 .94269E+04 .94269E+04 .13626E+05 .0000E+00 .20093E+02 .00000E+00 .20093E+0	Link										
Link 8 .00000E+0020093E+02 .00000E+0049803E+0470608E+02 .69803E+0460240E+0330149E+0330149E+0330344E+03 .1018 8 .00000E+0020093E+02 .00000E+0010212E+05 .2997E+03 .1762E+052997E+03 .37356E+03 .37356E+03 .1752E+05 .2997E+03 .1762E+0519329E+0337356E+03 .37356E+03 .1752E+05 .19329E+03 .1762E+05 .19329E+03 .37356E+03 .73556E+03 .1762E+05 .19329E+03 .1762E+05 .19329E+03 .1752E+05 .20973E+04 .67354E+03 .67354E+03 .1753E+05 .20973E+04 .67354E+03 .2332E+03 .15007E+04 .67354E+03 .1753E+05 .20973E+04 .67354E+03 .22332E+03 .15007E+04 .1018 .10 .00000E+0020093E+02 .00000E+001183E+05 .20973E+04 .12481E+05 .53081E+03 .22332E+03 .15007E+04 .1018 .10 .00000E+0020093E+02 .00000E+001183E+05 .52589E+04 .7257SE+04 .59778E+04 .7257E+02 .7257E+04 .27281E+02 .29084E+04 .1181E+05 .00000E+00 .20093E+02 .00000E+0018181E+04 .23971E+04 .33341E+04 .23971E+04 .29084E+04 .11707E+04 .27281E+02 .00000E+00 .20093E+02 .00000E+00 .7257SE+04 .59778E+04 .18181E+04 .23971E+04 .23971E+04 .29084E+04 .1707E+04 .27084E+04 .2708E+04 .1707E+04 .2708E+04 .1707E+04 .2708E+05 .0000E+00 .20093E+02 .00000E+00 .18181E+04 .23971E+04 .53341E+04 .23971E+04 .9428E+04 .1818E+04 .23971E+04 .9428E+04 .1818E+05 .20973E+04 .1818E+04 .23971E+04 .9428E+04 .1818E+05 .20973E+04 .1818E+04 .23971E+04 .9428E+04 .1818E+05 .20973E+04 .1818E+04 .9428E+04 .1818E+04 .23971E+04 .9428E+04 .1818E+05 .20973E+04 .1818E+04 .9428E+04 .1818E+04 .9428E+0	Link	5	.000000€+00	200938+02							.47196E+02
Link 9 .00000E+0020093E+02 .00000E+0010903E+05 .25977E+03 .10212E+05 .25977E+03 .33344E+03 .77356E+03 .1162E+05 .25977E+03 .11762E+05 .25977E+03 .37356E+03 .77356E+03 .77356E+03 .11762E+05 .19329E+03 .37356E+03 .55245E+03 .77356E+03 .11762E+05 .19329E+03 .17341E+05 .48318E+03 .55245E+03 .67334E+03 .11762E+05 .19329E+03 .17341E+05 .48318E+03 .55245E+03 .67334E+03 .11762E+05 .19329E+03 .17341E+05 .48318E+03 .55245E+03 .77356E+03 .22332E+03 .17341E+05 .1276E+04 .12681E+05 .53081E+03 .22332E+03 .15007E+04 .12681E+05 .53081E+03 .22332E+03 .15007E+04 .17681E+05 .17681E+05 .20073E+04 .12681E+05 .53081E+03 .22332E+03 .15007E+04 .17681E+05 .17681E+05 .20073E+04 .15007E+04 .27281E+02 .20081E+04 .17681E+05 .00000E+00 .20093E+02 .00000E+00 .12681E+05 .53081E+03 .13112E+05 .22580E+04 .15007E+04 .27281E+02 .20081E+04 .17681E+05 .00000E+00 .20093E+02 .00000E+00 .72575E+04 .59778E+04 .29781E+04 .29081E+04 .27281E+02 .20081E+04 .17681E+05 .176	Link										
Link 10 00000E+00 -20093E+02 00000E+00 -10212E+05 2597TE+03 11762E+05 -19329E+03 -37356E+03 -55245E+03 Link 11 00000E+00 -20093E+02 00000E+00 -11341E+05 -48318E+03 1108E+05 -20973E+04 -67354E+03 -55245E+03 Link 12 00000E+00 -20093E+02 00000E+00 -11341E+05 -48318E+03 1108E+05 -20973E+04 -67354E+03 -2233ZE+03 Link 12 00000E+00 -20093E+02 00000E+00 -11083E+05 -20973E+04 112681E+05 -53081E+03 2233ZE+03 15007E+04 Link 13 00000E+00 -20093E+02 00000E+00 -12481E+05 -22589E+04 112681E+05 53081E+03 2233ZE+03 15007E+04 Link 15 00000E+00 -20093E+02 00000E+00 -13112E+05 -22589E+04 172575E+04 59778E+04 27281E+02 29084E+04 Link 15 00000E+00 -20093E+02 00000E+00 -72575E+04 59778E+04 18181E+04 23971E+04 29084E+04 21707E+04 Link 17 -15995E+05 -10089E+05 00000E+00 -20093E+02 00000E+00 -33341E+04 53341E+04 23971E+04 98364E+03 -31707E+04 21707E+04 Link 18 -27489E+05 -80654E+05 00000E+00 -20093E+02 00000E+00 -38341E+04 23971E+04 53341E+04 98364E+03 -31707E+04 21704E+04 Link 19 00000E+00 -20093E+02 00000E+00 -22655E+05 18538E+05 -85025E+04 -85025E+03 49487E+04 94289E+04 Link 20 00000E+00 -220093E+02 00000E+00 -22655E+05 18538E+05 50005E+04 94289E+04 Link 20 00000E+00 -220093E+02 00000E+00 -20093E+02 00000E+00	Link						70608E+02				
Link 10 .00000E+0020093E+02 .00000E+001176ZE+05 .7932E+03 .11341E+0548318E+03 .5524SE+03 .67354E+03 Link 11 .00000E+0020093E+02 .00000E+0011083E+05 .20973E+04 .12481E+05 .53081E+03 .2233E+03 .15007E+04 Link 12 .00000E+0020093E+02 .00000E+0011083E+05 .20973E+04 .12481E+05 .53081E+03 .2233E+03 .15007E+04 Link 13 .00000E+0020093E+02 .00000E+0012481E+05 .53081E+03 .1311ZE+05 .22580E+04 .15007E+04 .27281E+02 Link 15 .00000E+0020093E+02 .00000E+007257SE+04 .59778E+04 .59778E+04 .27281E+02 .29084E+04 Link 16 .00000E+0020093E+02 .00000E+007257SE+04 .59778E+04 .33341E+04 .23971E+04 .29084E+04 .31707E+04 Link 1715995E+05 .10089E+05 .00000E+0053341E+04 .93864E+03 .2245SE+05 .18538E+05 .21704E+04 Link 1827489E+0580654E+05 .00000E+0053341E+04 .93864E+03 .2245SE+05 .18538E+05 .21704E+04 Link 20 .00000E+00 .20093E+02 .00000E+00 .53341E+04 .93864E+03 .2245SE+05 .4838E+04 .9468E+04 .94280E+04 .13626E+05 Link 20 .00000E+00 .20093E+02 .00000E+00 .5932E+03 .49487E+04 .7958E+04 .13628E+05 .2033E+04 .13108E+04 Link 21 .00000E+00 .20093E+02 .00000E+00 .5179SE+03 .5602SE+04 .20041E+04 .13628E+05 .2033E+04 .13108E+04 .12878E+04 .2343SE+03 .13108E+04 .12878E+04 .2033E+04 .13108E+04 .12878E+04 .2343SE+03 .13108E+04 .12878E+04 .2343SE+03 .13108E+04 .12878E+04 .2343SE+03 .13108E+04 .12878E+04 .2343SE+03 .19242E+04 .12878E+04 .33108E+04 .12878E+04 .33108E+04 .12878E+04 .1287	Link										
Link 11 .00000E+00 -20093E+02 .00000E+00 -11341E+05 .4831E=03 .11083E+05 .20973E+04 -67354E+03 -22332E+03 .1007E+04 .11461E+05 .53081E+03 .2233E+03 .1007E+04 .11461E+05 .53081E+03 .2233E+03 .1507E+04 .11461E+05 .53081E+03 .2233E+03 .1507E+04 .11461E+05 .53081E+03 .2233E+03 .1507E+04 .1	Link	9	.000000€+00	20093E+02	.00000E+00	10212E+05	.25977E+03	.11762E+05	 . 19329€+03 	37356€+05	55245E+03
Link 12 .00000E+0020093E+02 .00000E+0011083E+05 .20973E+04 .12481E+05 .53081E+03 .2333E+03 .53067E+04 .27281E+02 .00000E+0020093E+02 .00000E+0013112E+052589E+04 .72575E+04 .59778E+04 .59778E+04 .27281E+02 .29084E+04 .10000E+0020093E+02 .00000E+0013112E+052589E+04 .72575E+04 .59778E+04 .27281E+02 .29084E+04 .10000E+00 .20093E+02 .0000E+007575E+04 .59778E+04 .18181E+04 .23971E+04 .29084E+04 .31707E+04 .1000E+00 .20093E+02 .0000E+0020978E+04 .53341E+04 .93864E+03 .31707E+04 .2708E+04	Link	10	.000000€+00	20093E+02	.000000€+00	11762E+05	. 19329£+03				
Link 13 .00000E+0020093E+02 .00000E+0012481E+0553081E+03 .13112E+05 .22589E+041500TE+04 .27281E+02 Link 14 .00000E+0020093E+02 .00000E+0072575E+04 .59778E+04 .27281E+02 .29084E+04 .1510E+05 .00000E+0020093E+02 .00000E+0072575E+04 .59778E+04 .2971E+04 .29084E+04 .3170TE+04 .16181E+04 .29971E+04 .29971E+04 .29084E+04 .3170TE+04 .16181E+04 .29971E+04	Link	- 11	.00000E+00	200938+02	.00000E+00	11341E+05	.48318E+03	.11083E+05	20973E+04	67354E+03	22332E+03
Link 14 .00000E+00 -20093E+02 .00000E+0013112E+0522589E+04 .72575E+04 .59778E+04 .2781E+02 .2908LE+04 Link 15 .00000E+0020093E+02 .00000E+0072575E+04 .59778E+04 .1818LE+04 .23971E+04 .2908LE+04 .21770E+04 .21770E+03 .20050E+05 .20000E+00 .20	Link	12	.00000E+00	20093E+02	.00000€+00	11083E+05	.20973E+04	.12481E+05	.53081£+03	.22332E+03	. 15007E+04
Link 15 .00000E+0020093E+02 .00000E+0072575E+0459778E+04 .18181E+04 .2971E+04 .2904E+04 .31707E+04 .10000E+00 .20093E+02 .00000E+005334E+04 .9397E+04 .5334E+04 .93864E+03 .31707E+04 .21704E+04 .15095E+05 .10089E+05 .00000E+00 .5334E+04 .93864E+03 .22455E+05 .18538E+05 .21704E+04 .94269E+04 .10000E+00 .20093E+02 .00000E+00 .5334E+04 .93864E+03 .22455E+05 .18538E+05 .21704E+04 .94269E+04 .10000E+00 .20093E+02 .00000E+00 .20093E+05 .0000E+00 .20093E+05 .0000E+00 .20093E+02 .0000E+00 .20093E+00 .200	Link	13	.00000E+00	20093E+02	.00000€+00	12481E+05	53081E+03	.13112E+05	.22589E+04	15007E+04	27281E+02
Link 16 .00000E+00 .20093E+02 .00000E+0018181E+0423971E+04 .53341E+04 .93864E+033170TE+04 .21704E+04 .15108E+05 .15995E+0510089E+05 .00000E+0022455E+05 .9354E+04 .9255E+05 .80654E+05 .00000E+00 .22455E+05 .9352E+03 .6487E+04 .49487E+04 .49487E+04 .49487E+04 .49487E+04 .49487E+04 .49487E+04 .49487E+04 .13626E+05 .20033E+04 .2	Link	14	.00000E+00	20093E+02	.00000E+00	-,13112E+05	.22589E+04	.72575E+04	.59778E+04	.27281E+02	.29084E+04
Link 16 .00000E+00 .20093E+02 .00000E+0018181E+0423971E+04 .53341E+04 .93864E+033170TE+04 .21704E+04 .15108E+05 .15995E+0510089E+05 .00000E+0022455E+05 .9354E+04 .9255E+05 .80654E+05 .00000E+00 .22455E+05 .9352E+03 .6487E+04 .49487E+04 .49487E+04 .49487E+04 .49487E+04 .49487E+04 .49487E+04 .49487E+04 .13626E+05 .20033E+04 .2	Link	15	.00000E+00	20093E+02	.00000E+00	72575E+04	59778E+04	.18181E+04	.23971E+04	29084E+04	.31707E+04
Link 1715995E+0510089E+05 .00000E+0053341E+049386KE+03 .22455E+05 .18538E+05 .2170KE+0494289E+04 Link 1827489E+0580654E+05 .00000E+0020455E+05 .18538E+05 .9632E+03 .49487E+04 .94289E+04 .13626E+05 Link 19 .00000E+0020093E+02 .00000E+0096322E+0349487E+0461795E+03 .56025E+0413626E+05 .20333E+04 .13626E+05 .20333E+04 .13626E+05 .20333E+04 .1362E+05 .20333E+04 .1362E+05 .20333E+04 .1362E+05 .20333E+04 .1362E+04 .12878E+04 .20333E+04 .13108E+04 .10000E+00 .20093E+02 .00000E+00 .20041E+04 .212878E+04 .210190E+04 .11910E+04 .113108E+04 .19242E+04 .10000E+00 .20093E+02 .00000E+00 .20093E+02 .0000E+00 .20093E+02 .0000E+00 .20093E+04 .2033E+04 .31508E+04 .31508E+04 .19242E+04 .1362E+03 .19242E+04 .20333E+04 .2											
Link 18 -27489€+05 -80654€+05 -00000E+00 -22455€+05 18538E+05 9632E=03 49487E+04 94289€+04 13626E+05 Link 19 00000E+00 -20093E+02 00000E+00 -96322E+03 -49487E+04 -6179SE+03 5025E+04 -13626E+05 -2033E+04 Link 20 00000E+00 -20093E+02 00000E+00 -6179SE+03 -5602SE+04 -2004TE+04 12878E+04 2033SE+04 -13108E+04 Link 21 00000E+00 -20093E+02 00000E+00 -20093E+02 -0000E+00 -20093E+02 00000E+00 -20093E+02 0000E+00 -20093E+00 -20093E+00 -20093E+00 -20093E+00 -20093E+00 -20093E+00 -20093E+00 -2			15995E+05	10089E+05					18538E+05	.21704E+04	94289E+04
Link 19 .00000E+0020093E+02 .00000E+0096322E+0349487E+0461795E+03 .56025E+0413626E+0520333E+04 Link 20 .00000E+0020093E+02 .00000E+00 .51795E+0356025E+0420041E+04 .12878E+04 .20333E+04 .13108E+04 Link 21 .00000E+0020093E+02 .00000E+00 .20041E+0412878E+0431501E+0410190E+04 .13108E+04 .19262E+04 Link 22 .00000E+0020093E+02 .00000E+00 .31501E+04 .10190E+0433748E+04 .20333E+0319262E+04 .12458E+03											
Link 20 .00000E+0020093E+02 .00000E+00 .61795E+0356025E+0420041E+04 .12878E+04 .2033E+0413108E+04 Link 21 .00000E+0020093E+02 .00000E+00 .20041E+0412878E+0431501E+04 .10190E+04 .13108E+04 .19242E+04 .10190E+04 .23343E+04 .23433E+0319242E+04 .12458E+03											
Link 21 .00000E+00 - 20093E+02 .00000E+00 .20041E+04 - 12878E+04 - 31501E+04 - 10190E+04 .13108E+04 .19242E+04 Link 22 .00000E+00 - 20093E+02 .00000E+00 .31501E+04 .10190E+0433748E+04 .23433E+0319242E+04 .12458E+03											
Link 22 .000006+0020093E+02 .00000E+00 .31501E+04 .10190E+0433748E+04 .23433E+0319242E+04 .12458E+03											

force		Homents								
		FX	FY	*	FX-End 1	FY-End 1	FX-End 2	FY-End 2	H-End 1	M-End 2
Link	24	:000000#+00	20093E+02	.00000E+00	.17533E+04		. 10480E+04	. 19226E+03	.15968E+04	.25838E+03
Link	25	.000000€+00			10480E+04	19226E+03	.33400E+04	41977E+03		51815E+03
Link	26		200938+02		33400E+04	.41977E+03	.45860E+04	12374E+03	.51815E+03	.79642E+03
Link	27	.000000€+00	. 18895E+03		45860E+04	.12374E+03	.54420E+04		·.79642E+03	. 16454E+03
Link	28	.000000E+00	. 12501E+04		-,54420E+04	74329E+03	.62916E+04	17124E+03	16454E+03	27782E+03
Link	29	.00000€+00	20093E+02	.00000€+00	62916E+04	.17124E+03	.69605E+04	.66693E+03	.27782E+03	17681E+03
Link	30	.00000E+00	.25366E+03	.00000E+00	69605E+04	66693E+03	.73594E+04	.11757E+04	.17681E+03	.10224E+03
Link	31	- 82071E-01	.27180E+04		- 73594E+04	11757E+04		68234E+03		.36616E+02
Link	32	.00000E+06	.177485+03		- 75323E+04	.66234E+03		27019E+03		62808E+02
Link	33		20093E+02		.,75019E+04	.27019E+03	.73114E+04	.992586+03		22213E+03
Link	34	.000000€+00	.78373E+03		-,73114E+04	·.99258E+03	.72166E+04	.15746E+04	.22213E+03	.30413E+03
Link	35	28482E+03	.25915E+04	.000000€+00	72166E+04	·.15746E+04	. 73501E+04	82943E+03	30413E+03	49960E+02
Link	36	.00000€+00	20093E+02	.000000€+00	73501E+04	.82943E+03	.70144E+04	·.85886E+03	.69960E+02	.23585E+03
Link	37	.00000E+00	20093E+02	.00000E+08	-,70144E+04	.85886E+03	.681996+04	15145E+04	23585E+03	10917E+04
Link	38		20093E+02		- 68199E+04	. 15145E+04	.79270E+04	.21893E+01	.10917E+04	.14169E+04
Link	39		13833E+04	.00000E+00			.10749E+05			42074E+03
			20093E+02							
Link	40				10749€+05		. 135 16E+05	.10820E+05		27084E+03
Link	41		20093E+02		·. 13516E+05		.14273E+05	. 10213E+05	.27084E+03	.87043E+03
Link	42	.00000E+00	·.20093E+02	.00000E+00	14273E+05	10213E+05	.130818+05	.28020E+04	87043E+03	27620E+04
Link	43	71015E+03	33113E+04	.00000E+00	13081E+05	·.28020E+04	.96023E+04	.10535E+04	.27620E+04	.81189E+04
Link	44	.41135E+05	82018E+05	.00000E+00	96023E+04	10535E+04	.28902E+04	38874E+04	81189E+04	.43653E+03
Link	45		20093E+02		28902E+04					13198E+04
Link	46		.20093E+02	.00000E+00	.80442E+03		13231E+04		.13198E+04	.68869E+03
Link	47		20093E+02	.00000€+00	.13231E+04			11635E+05		17864E+04
Link	48		20093E+02	.00000€+00	.59121E+03	.11635E+05		·.72825E+03	.178648+04	
Link	49		20093E+02		·.93560E+03	.72825€+03	.41568E+04	.33954E+04	. 13538E+04	.32614E+04
Link	50	.00000E+00	20093E+0Z	.00000€+00	+.41568E+04	33954E+04	.81780E+04	.34696E+04	32614E+04	15489E+04
Link	51	.000000€+00	20093E+02	.000000€+00	81780E+04	34696E+04	. 10414E+05	11868E+04	.15489E+04	.32550E+04
Link	52	.00000E+00	20093E+02	.0000000	10414E+05	.11868E+04	.97991E+04	11446E+04	- 32550E+04	81331E+03
Link	53		20093E+02		97991E+04	.11646E+06	.45869E+04	.19927E+04	.81331E+03	.21370E+03
Link	54		20093E+02		45869E+04		.67508E+02		21370E+03	.85372E+03
Link	55		· .20093E+02		67508E+02					19381E+04
Link	56		20093E+02	.000000€+00	.33119€+04			.21004E+04	. 19381E+04	. 19446E+04
Link	57	42006E+03	.37497E+04	.00000E+00	.81688E+04		12914E+05			61734E+03
Link	58		20093E+02	.000000€+00	.12914E+05	. 17939E+04	18691E+05	67096E+03	.61734E+03	·.39866E+03
Link	59	.000000€+00	20093E+02	.00000E+00	.18691E+05	.67096E+03	2062BE+05	. 13264E+03	.39866E+03	.61954E+02
Link	60	.000000€+00	20093E+02	.000000E+00	.206285+05	13264E+03	20268E+05	11462E+03	· .61954E+02	10996E+02
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8			66E+04 .10216			29E-027294				OE-01
9			16E+05 .11764			SSE-028401				8E-01
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TRV, Tracked Vehicle Dynamics -

Cutout file - Pose 35

IRV. Tr	acked Veh	icle Dynamics	- Versian 1.00	ı
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IRV, Tracked Vehicle Dynamics - Version 1.00

OUTPUT AT TIME .0060

Displac	:0714	nts, Velociti	es, and Acce							
		X	Y	Theta	X-Vel	Y-Vet	Omega	X-Accel	Y-Accel	Alpha
Vehicle		84149E+00			14057E+03		41414E-01	.13719E+04		252196+02
	1	74036E+02	.19436E+02	.94248E-01	.123148+03			81806E+05	.336438+05	.000000E+00
	2	50687E+02	.14686E+02		19680E+03	.36299E+02		10308E+05	19658E+05	.0000000000
	3	25871E+02	.13985E+02		14503E+03		.11396E+02	.10910E+04	10896E+05	.000000E+00
	4	85903E+00	.13964E+02		14758E+03	82252E+01	.11396E+02	.40193E+03	.30687E+04	,000000E+00
	5	.24195E+02	.13845E+02		30501E+03	.53823E+01	.11396E+02	.13450E+05	.42853E+05	.0000000
	6	.49195E+02	.13792E+02		10969E+03	.67480E+02		676408+02	.357718+05	.00000€+00
	7	.72964E+02	.13123E+02		29867E+03	42541E+03	.15708E+02	.17147E+06	.43821E+06	.000000€+00
	1	·.16588E+01	.26738E+02		30894E+03	.21812E+02		17266E+05		21961E+03
	5	77936E+01	.26970€+02		29414E+03	. 19501E+02		. 15770€+05	18020€+04	.34632E+03
	3	13919E+02	.27281E+02		28238E+03	.79958E+01	.192748+01	. 18766€+05	195838+03	.81426E+03
	4	·.20037E+02	.27616E+02		24867E+03	78031E+01	. 18373E+01	.40678E+05	.25508E+03	.23329E+03
	5	26143E+0Z	.27829€+02		19092E+03		39935E+01		84836E+04	
	6	32220E+02	.27969E+02		15418E+03		15886E+01		68113E+04	.15187E+03
	7	38230E+02	.28292E+02		15454E+03	.64716E+01	.32311E+01			58651E+03
	8	·.44193E+02	.28631E+02		19755E+03		22056E+01		10723E+05	.16855E+03
	9	50128E+02	.28981E+02		24927E+03	-80461E+00			12967E+05	
	10	56050E+02	.29299€+02		24269E+03		21684E+01	.94040€+05	·.39380E+04	.27314E+04
	11	61936E+0Z	.29637E+02		19478E+03	.71083E+01	.38234E+01	.136548+06		39247E+04
	12	67772E+02			16311E+03		31025E-01	. 181568+05		19525E+04
	13	73591E+02	.30271E+02		17647E+03			15842E+06		11864E+05
	14	791426+02			18813E+03			16061E+06	.80223E+04	.46542E+04
	15	83375E+02			91945E+02			15879E+06		33631E+04
	16	84263E+02			90906E+01			32161E+06		
	17	81789E+02		89304E+00		10739E+03		32431E+05		.11354E+05
	18	77116E+02			86830E+01					.36947E+05 .12832E+04
	19	71571E+02			11074E+03			40030E+05 54663E+05	.33342E+05 .11866E+05	.10055E+05
	20	65774E+02			22157E+02				20920E+05	.89626E+04
	21	60178E+02		42476E+00		21542E+03 11119E+03		*.32102E+05		.69232E+03
	22	54725E+02		43374E+00				31698E+05 31403E+05		
	23	49018E+02	.12990E+01	.31922E-01 .22659E-01			387638+01		.53044E+04	.48552E+03
	24	43045E+02								12966E+03
	25	37075E+02		50809E-01			72296E+01		.21269E+04	19591E+04
	26	31089E+02	.12553E+01	.964496-02					.42269E+04	.13018E+03
	27	25080E+02		16295E-01		13170E+01				13355E+04
	28	19057E+02	.12417E+01	.17849E-01						68535E+03
	29	13025E+02		71548E-03 79841E-02					.55613E+04	.89063E+02
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	31	94258E+00			11383E+02		-,21666E+00		.63695E+04	.74144E+03
	32	.51028E+01	.12648E+01						83214E+04	
	33	.11148E+02			19251E+02	-23787E+02		25856E+04		
	34	.17194E+02			.25845E+02		023326+00	34804E+04	- 103326+03	- 15148E+03
	35	.23239E+02			33601E+02					16855E+03
	36	.29283E+02	.12856E+01		37104E+02				.24033E+05	.16732E+04
	37	.35329E+02			.26249E+02		.17602E+01 91957E+01		.29090£+04	.41024E+04
	38	.41388E+02	.13561E+01		28593E+01				-,23572E+05	
	39	.47456E+02		80581E-01						58169E+04
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tink i	42	. 45383E+02	.39932E+01	.343618-01	.3114BE+02		a+abot+01	98963E+05	*.0703!E+U3	*, 31134E*U3

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force	end and	Homents								
		FX	FY	M	FX-End 1	FY-End 1	FX-End 2	FY-End 2	M-End 1	M-End 2
Link	24	.00000E+00	20093E+02	.00000E+00	.35568E+04	.32562E+03	34546E+04 -	.29698E+02	.14274E+04	. 18126E+03
Link	25	.00000E+00	20093E+02	.00000E+00	.34546E+04	29698E+02	·.13878E+04	.40790E+03	18126E+03	48640E+03
Link	26	.00000E+00	20093E+02	.000000E+0:3	.13878E+04			.53859E+03	.48640E+03	.78568E+03
Link	27	.00000E+00			12963E+04	53859E+03	.33174E+04 -		78568E+03	.12070E+03
Link	28	.00000E+00			33174E+04	.30095E+03	.45699E+04 -			
Link	29		- 20093E+02		45699E+04	.37006E+03	.54625E+04 ·			51813E+02
Link	30		20093E+02		54625E+04	.18255E+03		.12673E+03	.51813E+02	.25966E+02
Link	31		13753E+03		60898E+04				·.25966E+02	
Link	32		20093E+02		63913E+04			.49598E+03	.47541E+02	.77706E+02
Link	33		20093E+02		64316E+04				77706E+02	
Link	34		20093E+02		64338E+04		.62993E+04 -		.15292E+03	. 19476E+03
Link	35		12384E+04		62993E+04	.43382£+03			19476E+03	
Link	36		<i>2</i> 0093E+02		66125E+04		.693548+04 -		.33120€+03	.28428E+03
Link	37		20093E+02		69354E+04	.87684E+02			28428E+03	
Link	38	.000000€+00	20093E+0Z	.00000E+00	85968E+04	11821E+04	,11180E+05	. 13535E+04	.76423E+03	.22590E+04
Link	39	87446E+03	39369E+04	.000000€+00	11180E+05	13535E+04	. 15332E+05	.40646E+04	22590E+04	94595E+03
Link	40	.000000E+00	20093E+02	.00000E+00	15332E+05	40646E+04	.16043E+05 -	.17826E+04	.94595E+03	13500E+04
Link	41	.00000E+00	20093E+02	.00000E+00	16043E+05	.17826E+04	.13634E+05 -	.81781E+04	.13500E+04	.26095E+03
Link	42	.00000E+00	20093E+02	.00000E+00	13634E+05	.81781E+04	.84878E+04 -	.11790E+05	26095E+03	29715E+04
Link	43		11670E+06		84878E+04	.11790E+05	.38269E+04 ·		.29715E+04	.82896E+04
Link	44		48131E+05		38269E+04		·,10814E+03 ·			.14543E+04
Link	45		20093E+02	.00000E+00	.10814E+03	74890E+04	.36240E+03 -		14543E+04	
Link	46		20093E+02		36240E+03	.73713E+04	.41004E+04 -		.98925E+03	.14399E+04
Link	67		20093E+02		41004E+04	.70599E+04	.74793E+04 -		14399E+04	
Link	48		20093E+02		74793E+04	.84768E+04	.88971E+04 ·		.79956E+03	
Link	40		20093E+02		88971E+04	.11646E+05	.10484E+05 -		.16651E+04	.17727E+04
Link	50		20093E+02		10484E+05	.89945E+04	.12816E+05 ·		17727E+04	
Link	51		20093E+02		12816E+05	.50311E+04	.13295E+05 -		.13500E+04	.25583E+04
Link	52		-,20093E+02		13295E+05	.61360E+03			25583E+04	
Link	53		·.20093E+02					.59289E+03		· .77757E+01
Link	54		20093E+02		83867E+04			.175416+04	.77757E+01	.73147E+03
Link	55		20093E+02			17541E+04			73147E+03	
Link	56		· . 20093E+02	.00000E+00			-,12299E+05 -		.16337E+04	.24729E+04
			20093E+02	.00000E+00	.122996+05					
Link	57								· .24729E+04	
Link	58		20093E+02	.0000000	.17646E+05		18645E+05 ·			- 41076E+03
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9	.6000	XXE+01 .7398	80E+04 .93498	E+04 .527	6E-01303	SE-026633	SE-01 .77062	E-02 .5284	3E-01 .6678	5E-01
10	.6000	0E+01 .9349	98E+04 .14234	E+05 .6633	8E-017706	SZE-02 1012	27E+00 .90254	E-02 .6678	5E-01 .1016	7E+00
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DW-RPM 2.500

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TRY, Tre	cked Veh	icle Dynamics	- Version 1.00
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